Component/System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Ignition Switch Run/Start Position Circuit Stuck Low Detected	B2B0D	This monitoring checks if the hardwired Run/Crank analog signal matches the value of the Run/Crank Terminal Status message received from the ECM. This fault is set if the two signals do not match where the hardwired signal is set to INACTIVE while the serial data signal is set to ACTIVE.	Run/Crank Analog Signal State **AND** Run/Crank Terminal Status **AND** X **OUT OF** Y	<= 1.5V = ACTIVE = 80 = 100	ECM Timed Out	= FALSE	0.8 [Sec]	Type B 2 Trips
Ignition Switch Run/Start Position Circuit Stuck High Detected	B2B0E	This monitoring checks if the hardwired Run/Crank analog signal matches the value of the Run/Crank Terminal Status message received from the ECM. This fault is set if the two signals do not match where the hardwired signal is set to ACTIVE while the serial data signal is set to INACTIVE.	Run/Crank Analog Signal State **AND** Run/Crank Terminal Status **AND** X **OUT OF** Y	>=5.5V = INACTIVE = 80 = 100	ECM Timed Out	= FALSE	0.8 [Sec]	Type B 2 Trips
Bus-Off detected on the HS Primary bus (Bus A)	U2413	This fault is set if the HS Primary bus enters the Bus-Off state	Bus Off Event Occurred on HS Primary	= TRUE	Run/Crank Analog Signal State **OR** Comm Enable Hardwire Line **AND** System Voltage	>= 5.5V >= 4.5V > 5.5V	25[usec] for pass 10[usec] for fail	Type B 2 Trips

Component/System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Internal memory failure on the CGM Detected	B2B12	This monitoring checks whether a double bit ECC error has occurred in code flash or RAM. This fault is set if an ECC error has occurred.	ECC Error Detected	= TRUE	Guarded Read Flag	= FALSE	50ms	Type B 2 Trips
		This monitoring checks and sets a fault if a defect in the data flash (NVM) is detected.	NVM Fault Detected	= TRUE	N/A	N/A	1.5 us	
Microcontroller Performance Failure Detected	B2B13	This monitoring shall check whether the ALU in the microcontroller is functioning correctly by running an algorithm and checking the results against an expected value. If the result is incorrect the fault shall be set.	Test Result 1 **AND** Test Result 2	!= Expected Result 1 != Expected Result 2	N/A	N/A	1.5 us	Type B 2 Trips
		This monitoring shall check whether any clock monitoring interrupts have occurred. If any clock monitoring interrupts have occurred this fault shall be set.	Clock Monitoring Interrupt Occurred	= TRUE	N/A	N/A		

Component/System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Loss of Communication with the ECM Detected	U18D5	This monitoring shall check a supervised message from the ECM to check the communication status. If the CGM has not received the supervised message from the ECM for 2.5x of its periodic rate, a secondary counter shall be enabled and decremented. When the secondary timer reaches zero, this fault shall be set if the message still has not been received.	Supervised Message has not been received in 62.5[ms] **THEN** Secondary Timer (4 sec)	= TRUE = 0 sec	Run/Crank Analog Signal State **AND** System Voltage	>= 5.5V >= 7V	4.0625 [sec]	Type B 2 Trips
Loss of Communication with the TCM Detected	U18D7	This monitoring shall check a supervised message from the TCM to check the communication status. If the CGM has not received the supervised message from the TCM for 2.5x of its periodic rate, a secondary counter shall be enabled and decremented. When the secondary timer reaches zero, this fault shall be set if the message still has not been received.	Supervised Message has not been received in 2.5[sec] **THEN** Secondary Timer (4 sec)	= TRUE = 0 sec	Run/Crank Analog Signal State **AND** System Voltage	= ACTIVE >= 7V	6.5 [sec]	Type B 2 Trips

Component/System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Loss of Communication with the EBCM Detected	U18DC	This monitoring shall check a supervised message from the EBCM to check the communication status. If the CGM has not received the supervised message from the EBCM for 2.5x of its periodic rate, a secondary counter shall be enabled and decremented. When the secondary timer reaches zero, this fault shall be set if the message still has not been received.	Supervised Message has not been received in 2.5[sec] **THEN** Secondary Timer (4 sec)	= TRUE = 0 sec	Run/Crank Analog Signal State **AND** System Voltage	= ACTIVE >= 7V	6.5 [sec]	Type B 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
CGM Ignition Switch Run/ Start Position Circuit Low	B2B0D	This DTC monitors for a CGM Ignition Switch Run/Start Position Circuit Low error as determined by the CGM	The CGM Diagnostic Status Message signal in GMLAN frame $3CF indicates that the CGM Ignition Switch Run/Start Position Circuit Low DTC has set in the CGM.		General Enable Criteria:		Diagnostic runs in 12.5 ms loop	Type B, 2 Trips
					Message $3CF	is being received		
					Central Gateway Module	is present on the bus		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
CGM Ignition Switch Run/ Start Position Circuit High	B2B0E	This DTC monitors for a CGM Ignition Switch Run/Start Position Circuit High error as determined by the CGM	The CGM Diagnostic Status Message signal in GMLAN frame $3CF indicates that the CGM Ignition Switch Run/Start Position Circuit High DTC has set in the CGM.		General Enable Criteria: Message $3CF Central Gateway Module	 is being received is present on the bus	Diagnostic runs in 12.5 ms loop	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
CGM Control Module Memory Failure	B2B12	This DTC monitors for a CGM Control Module Memory Failure error as determined by the CGM	The CGM Diagnostic Status Message signal in GMLAN frame $3CF indicates that the CGM Control Module Memory Failure DTC has set in the CGM.		General Enable Criteria: Message $3CF Central Gateway Module	 is being received is present on the bus	Diagnostic runs in 12.5 ms loop	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
CGM Control Module Internal Performance Failure	B2B13	This DTC monitors for a CGM Control Module Internal Performance Failure error as determined by the CGM	The CGM Diagnostic Status Message signal in GMLAN frame $3CF indicates that the CGM Control Module Internal Performance Failure DTC has set in the CGM.		General Enable Criteria: Message $3CF Central Gateway Module	 is being received is present on the bus	Diagnostic runs in 12.5 ms loop	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Steering Wheel Angle Sensor Signal Message Counter Incorrect	C1211	This DTC monitors for an error in the Steering Wheel Angle Sensor Signal Message Counter	Communication of the Alive Rolling Count or Protection Value from the Steering Wheel Angle Sensor over CAN bus is incorrect for out of total samples	 >= 15.00 counts >= 16.00 counts	Message frame All the following conditions are met for Power Mode Powertrain Relay Voltage Run/Crank Ignition Voltage	= Is available >= 3,000.00 milliseconds = Run >= 11.00 Volts >= 11.00 Volts	Executes in 10ms loop.	Type C, No SVS "Safety Emissions Neutral Diagnostic"

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Intake Camshaft Actuator Solenoid Circuit Open – Bank 1	P0010	Controller specific output driver circuit diagnoses the CAM phaser oil control valve solenoid high sided driver for an open circuit failure when the output is powered on by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates open circuit failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for an open circuit.	≥ 200 K Ω impedance between signal and controller ground.	System supply voltage Output driver is commanded on Ignition switch is in crank or run position	> 11.00 Volts	20 failures out of 25 samples 250 ms /sample, continuous	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Intake Camshaft System Performance – Bank 1	P0011	Detects a VVT system error by comparing the desired and actual cam positions when VVT is activated.	Camshaft position error [absolute value of (desired position - actual position)] is compared to thresholds to determine if excessive.	(Intake cam Bank 1) Cam Position Error > (**P0011_CamPosErrorLimIc1**) deg	**Intake Cam Phsr Enable**	= TRUE	100.00 failures out of 125.00 samples 100 ms /sample	Type B, 2 Trips
					System Voltage	> 11.00 Volts		
					Engine Running	= TRUE		
					Power Take Off (PTO) active	= FALSE		
					Desired cam position	> 0 deg		
					Desired AND Measured cam position	> (**P0011_CamPosErrorLimIc1**) deg AND < (**CalculatedPerfMaxIc1**) deg		
					Desired cam position variation	< 3.00 deg for (**P0011_P05CC_StablePositionTimeIc1**) seconds		
					No Active DTCs	P0010 P2088 P2089		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust Camshaft Actuator Solenoid Circuit Open – Bank 1	P0013	Controller specific output driver circuit diagnoses the CAM phaser oil control valve solenoid high sided driver for an open circuit failure when the output is powered on by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates open circuit failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for an open circuit.	≥ 200 K Ω impedance between signal and controller ground.	System supply voltage Output driver is commanded on Ignition switch is in crank or run position	> 11.00 Volts	20 failures out of 25 samples 250 ms /sample, continuous	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust Camshaft System Performance – Bank 1	P0014	Detects a VVT system error by comparing the desired and actual cam positions when VVT is activated.	Camshaft position error [absolute value of (desired position - actual position)] is compared to thresholds to determine if excessive.	(Exhaust cam Bank 1) Cam Position Error > (**P0014_CamPosErrorLimEc1**) deg	**Exhaust Cam Phsr Enable** System Voltage Engine Running Power Take Off (PTO) active Desired cam position Desired AND Measured cam position Desired cam position variation No Active DTCs	= TRUE > 11.00 Volts = TRUE = FALSE > 0 deg > (**P0014_CamPosErrorLimEc1**) deg AND < (**CalculatedPerfMaxEc1**) deg < 3.00 deg for (**P0014_P05CE_StablePositionTimeEc1**) seconds P0013 P2090 P2091	100.00 failures out of 125.00 samples 100 ms /sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Crankshaft Position (CKP)- Camshaft Position (CMP) Correlation Bank 1 Sensor A	P0016	Detects cam to crank misalignment by monitoring if the cam sensor pulse for bank 1 sensor A occurs during the incorrect crank position, diagnostic passes when the cam sensor pulse is in the expected range	Out of range cam edge measurements in one engine cycle Out of range values are: cam edge measurement OR cam edge measurement from the expeced nominal cam position	>= 4 cam edges < -7.1 Crank Degrees > 8.3 Crank Degrees	Crankshaft and camshaft position signals are synchronized Engine is Spinning Cam phaser control indcates the phaser is 'parked' No Active DTCs: Time since last execution of a test IntCamECC_OilPresLow	Test is Enabled CrankSensor_FA P0340, P0341 > 1.0 sec = FALSE	4 cam edge measurements and 1 test sample per engine cycle Test failure is 4 fails in 5 samples Diagnostic failure is 2 failed tests out of 3 If the first test fails, the next test is delayed to confirm the phaser 'parked' This delay time is defined by **P0016, P0017, P0018, P0019: Cam Correlation Oil Temperature Threshold** For mid-park phasers, an additional delay **P0016-0019 Mid-Park Phaser Delay** is applied	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Crankshaft Position (CKP)-Camshaft Position (CMP) Correlation Bank 1 Sensor B	P0017	Detects cam to crank misalignment by monitoring if the cam sensor pulse for bank 1 sensor B occurs during the incorrect crank position, diagnostic passes when the cam sensor pulse is in the expected range	Out of range cam edge measurements in one engine cycle Out of range values are: cam edge measurement OR cam edge measurement from the expeced nominal cam position	>= 4 cam edges < -8.4 Crank Degrees > 9.2 Crank Degrees	Crankshaft and camshaft position signals are synchronized Engine is Spinning Cam phaser control indcates the phaser is 'parked' No Active DTCs: Time since last execution of a test ExhCamECC_OilPresLow	Test is Enabled CrankSensor_FA P0365, P0366 > 1.0 sec = FALSE	4 cam edge measurements and 1 test sample per engine cycle Test failure is 4 fails in 5 samples Diagnostic failure is 2 failed tests out of 3 If the first test fails, the next test is delayed to confirm the phaser 'parked' This delay time is defined by **P0016, P0017, P0018, P0019: Cam Correlation Oil Temperature Threshold** For mid-park phasers, an additional delay **P0016-0019 Mid-Park Phaser Delay** is applied	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
O2S Heater Control Circuit Bank 1 Sensor 1	P0030	Controller specific output driver circuit diagnoses the heater output low sided driver for an open circuit failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver off state indicates open circuit failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for an open circuit.	≥ 200 K Ω impedance between output and controller ground.	Ignition Voltage Engine Speed	= Crank or Run > 11.0 volts > 400 RPM	20 failures out of 25 samples 250 ms / sample Continuous	Type B, 2 Trips Note: In certain controllers P0031 may also set

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
O2S Heater Control Circuit Bank1 Sensor1	P0031	Controller specific output driver circuit diagnoses the heater output low sided driver for a short to ground failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver off state indicates short to ground failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to ground.	≤ 0.5 Ω impedance between output and controller ground.	Ignition Voltage Engine Speed	= Crank or Run > 11.0 volts > 400 RPM	20 failures out of 25 samples 250 ms / sample Continuous	Type B, 2 Trips Note: In certain controllers P0030 may also set

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
O2S Heater Control Circuit Bank1 Sensor1	P0032	Controller specific output driver circuit diagnoses the heater output low sided driver for a short to power failure when the output is powered on by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to power failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to power.	≤ 0.5 Ω impedance between output and controller power.	Ignition Voltage Engine Speed	= Crank or Run > 11.0 volts > 400 RPM	20 failures out of 25 samples 250 ms / sample Continuous	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
O2S Heater Control Circuit Bank 1 Sensor 2	P0036	Controller specific output driver circuit diagnoses the heater output low sided driver for an open circuit failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver off state indicates open circuit failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for an open circuit.	≥ 200 K Ω impedance between output and controller ground.	Ignition Voltage Engine Speed	= Crank or Run > 11.0 volts > 400 RPM	20 failures out of 25 samples 250 ms / sample Continuous	Type B, 2 Trips Note: In certain controllers P0037 may also set

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
O2S Heater Control Circuit Bank1 Sensor2	P0037	Controller specific output driver circuit diagnoses the heater output low sided driver for a short to ground failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver off state indicates short to ground failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to ground.	≤ 0.5 Ω impedance between output and controller ground.	Ignition Voltage Engine Speed	= Crank or Run > 11.0 volts > 400 RPM	20 failures out of 25 samples 250 ms / sample Continuous	Type B, 2 Trips Note: In certain controllers P0036 may also set

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
O2S Heater Control Circuit Bank1 Sensor2	P0038	Controller specific output driver circuit diagnoses the heater output low sided driver for a short to power failure when the output is powered on by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to power failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to power.	≤ 0.5 Ω impedance between output and controller power.	Ignition Voltage Engine Speed	= Crank or Run > 11.0 volts > 400 RPM	20 failures out of 25 samples 250 ms / sample Continuous	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
HO2S Heater Resistance Bank 1 Sensor 1	P0053	Detects an oxygen sensor heater having an incorrect or out of range resistance value. This test calculates the heater's resistance (using voltage and current) at engine start after a longer soak condition and compares it to the expected values for the released sensor. This fault is set if the heater resistance is outside the expected range.	Heater Resistance outside of the expected range of	7.3 < ohms < 14.6	No Active DTC's Coolant – IAT Engine Soak Time Coolant Temp Ignition Voltage Engine Run time	ECT_Sensor_FA P262B IAT_SensorFA < 8.0 ºC > 28,800 seconds ≥ -30.0 ºC < 32.0 volts < 0.06 seconds	Once per valid cold start	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
HO2S Heater Resistance Bank 1 Sensor 2) (For Dual Bank Exhaust Only	P0054	Detects an oxygen sensor heater having an incorrect or out of range resistance value. This test calculates the heater's resistance (using voltage and current) at engine start after a soak condition and compares it to the expected values for the released sensor. This fault is set if the heater resistance is outside the expected range.	Heater Resistance outside of the expected range of	7.3 < ohms < 14.6	No Active DTC's Coolant – IAT Engine Soak Time Coolant Temp Ignition Voltage Engine Run time	ECT_Sensor_FA P262B IAT_SensorFA < 8.0 ºC > 28,800 seconds ≥ -30.0 ºC < 32.0 volts < 0.06 seconds	Once per valid cold start	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
MAP / MAF / Throttle Position Correlation	P0068	Detect when MAP and MAF do not match estimated engine airflow as established by the TPS	Difference between MAP and estimated MAP exceeds threshold (kPa), or P0651 (5 Volt Ref), or P0107 (MAP circuit low), or P0108 (MAP circuit high) have failed this key cycle, then MAP portion of diagnostic fails Absolute difference between MAF and estimated MAF exceed threshold (grams/sec), or P0102 (MAF circuit low), or P0103 (MAF circuit hi) have failed this key cycle, or maximum MAF versus RPM (Table) is greater than or equal to maximum MAF versus battery voltage, then MAF portion of diagnostic fails	Table, f(TPS). See supporting tables: **P0068_Delta MAP Threshold f(TPS)** Table, f(TPS). See supporting tables: **P0068_Delta MAF Threshold f(TPS)** Table, f(RPM). See supporting tables: **P0068_Maximum MAF f(RPM)** Table, f(Volts). See supporting tables: **P0068_Maximum MAF f(Volts)**	Engine Speed Run/Crank voltage	> 800 RPM > 6.41 Volts	Continuously fail MAP and MAF portions of diagnostic for 0.1875 s Continuous in MAIN processor	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Intake Air Temperature Sensor 2 Circuit Performance (applications with humidity sensor, but no manifold temperature sensor)	P0096	Detects an Intake Air Temperature 2 (IAT2) sensor value that is stuck in range by comparing the IAT2 sensor value against the IAT and coolant temperature sensor values and failing the diagnostic if the IAT2 value is more different than the IAT and coolant temperature values than is expected. If the engine has been off for a long enough period of time, the air temperature values in the engine compartment of the vehicle are considered to have equalized, and the diagnostic can be enabled. The diagnostic will fail if the IAT and coolant temperature values are similar, and the IAT2 value is not similar to the IAT and coolant temperature values. This diagnostic is executed once per ignition cycle if the enable conditions are met.	ABS(Power Up IAT - Power Up IAT2) AND ABS(Power Up ECT – Power Up IAT2) >= ABS(Power Up ECT – Power Up IAT)	> 25 deg C	Time between current ignition cycle and the last time the engine was running Powertrain Relay Voltage for a time No Active DTCs:	> 28,800 seconds >= 11.0 Volts >= 0.9 seconds PowertrainRelayFault ECT_Sensor_Ckt_FA IAT_SensorCircuitFA HumTempSnsrCktFA EngineModeNotRunTimer Error	Executes once at the beginning of each ignition cycle if enable conditions are met	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Intake Air Temperature Sensor Circuit 2 Low (applications with humidity)	P0097	Detects a continuous short to ground in the Intake Air Temperature 2 (IAT2) signal circuit or an IAT2 sensor that is outputting a frequency signal that is too low. The diagnostic monitors the IAT2 sensor output frequency and fails the diagnostic when the IAT2 frequency is too low. The IAT2 sensor is a thermistor in which the resistance across the sensor can be equated to a temperature. The temperature value is converted by the sensor to a frequency value in Hertz. A digital square wave signal is transmitted by the sensor to the ECM. The ECM calculates the frequency of the square wave signal and converts that frequency to a temperature value. A lower frequency is equivalent to a lower temperature. This diagnostic is enabled if the Powertrain Relay voltage is high enough.	Raw IAT 2 Input	< 13 Hertz (~-60 deg C)	Powertrain Relay Voltage for a time No Active DTCs:	>= 11.0 Volts >= 0.9 seconds PowertrainRelayFault	40 failures out of 50 samples 1 sample every 100 msec	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Intake Air Temperature Sensor Circuit 2 High (applications with humidity)	P0098	Detects an Intake Air Temperature 2 (IAT2) sensor that is outputting a frequency signal that is too high. The diagnostic monitors the IAT2 sensor output frequency and fails the diagnostic when the IAT2 frequency is too high. The IAT2 sensor is a thermistor in which the resistance across the sensor can be equated to a temperature. The temperature value is converted by the sensor to a frequency value in Hertz. A digital square wave signal is transmitted by the sensor to the ECM. The ECM calculates the frequency of the square wave signal and converts that frequency to a temperature value. A higher frequency is equivalent to a higher temperature. This diagnostic is enabled if the Powertrain Relay voltage is high enough.	Raw IAT 2 Input	> 390 Hertz (~150 deg C)	Powertrain Relay Voltage for a time No Active DTCs:	>= 11.0 Volts >= 0.9 seconds PowertrainRelayFault	40 failures out of 50 samples 1 sample every 100 msec	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Intake Air Temperature Sensor 2 Intermittent In-Range (applications with humidity)	P0099	Detects a noisy or erratic signal in the Intake Air Temperature 2 (IAT2) circuit by monitoring the IAT2 sensor and failing the diagnostic when the IAT2 signal has a noisier output than is expected. When the value of the IAT2 signal in °C is determined, a delta is calculated between the current reading and the previous reading. The absolute value of these deltas is summed over a number of IAT2 readings. The result of this summation is called a “string length”. Since the IAT2 signal is anticipated to be relatively smooth, a string length of a particular magnitude indicates a noisy or erratic IAT2 signal. The diagnostic will fail if the string length is too high. This diagnostic is enabled if the Powertrain Relay voltage is high enough.	String Length Where: "String Length" = sum of "Diff" calculated over And where: "Diff" = ABS(current IAT 2 reading - IAT 2 reading from 100 milliseconds previous)	> 100.00 deg C 10 consecutive IAT 2 readings	Powertrain Relay Voltage for a time No Active DTCs:	>= 11.0 Volts >= 0.9 seconds PowertrainRelayFault	4 failures out of 5 samples Each sample takes 1.0 seconds	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Intake Air Pressure Measurement System - Multiple Sensor Correlation (naturally aspirated with TIAP/ Baro sensor)	P00C7	Detects an inconsistency between pressure sensors in the induction system in which a particular sensor cannot be identified as the failed sensor. If the engine has been off for a sufficient amount of time, the pressure values in the induction system will have equalized. The Manifold Pressure (MAP) and Barometric Pressure (BARO) sensors values are checked to see if they are within the normal expected atmospheric pressure range. If they are, then MAP and BARO are compared to see if their values are similar. If the MAP and BARO values are not similar, there are no other pressure sensors to compare against to identify which sensor is not rational. The Multiple Pressure Sensor Correlation Diagnostic will fail in this case.	ABS(Manifold Pressure - Baro Pressure)	> 10.0 kPa	Time between current ignition cycle and the last time the engine was running Engine is not rotating Manifold Pressure Manifold Pressure Baro Pressure Baro Pressure No Active DTCs: No Pending DTCs:	> 10.0 seconds >= 50.0 kPa <= 115.0 kPa >= 50.0 kPa <= 115.0 kPa EngineModeNotRunTimer Error MAP_SensorFA AAP_SnsrFA MAP_SensorCircuitFP AAP_SnsrCktFP	4 failures out of 5 samples 1 sample every 12.5 msec	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Humidity Sensor Circuit Low	P00F4	Detects a continuous short to ground in the humidity signal circuit or a humidity sensor that is outputting a duty cycle that is too low. The diagnostic monitors the humidity sensor duty cycle output and fails the diagnostic when the humidity duty cycle is too low. The humidity sensor converts the capacitance across the sensor to a relative humidity. The relative humidity value is converted by the sensor to a duty cycle value in %. A digital square wave signal is transmitted by the sensor to the ECM. The ECM calculates the duty cycle of the square wave signal and converts that duty cycle to a relative humidity value in % through a transfer function. This diagnostic is enabled if the Powertrain Relay voltage is high enough.	Humidity Duty Cycle	<= 5.0 %	Powertrain Relay Voltage for a time No Active DTCs:	>= 11.0 Volts >= 0.9 seconds PowertrainRelayFault	40 failures out of 50 samples 1 sample every 100 msec	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Humidity Sensor Circuit High	P00F5	Detects a humidity sensor that is outputting a duty cycle signal that is too high. The diagnostic monitors the humidity sensor duty cycle output and fails the diagnostic when the humidity duty cycle is too high. The humidity sensor converts the capacitance across the sensor to a relative humidity. The relative humidity value is converted by the sensor to a duty cycle value in %. A digital square wave signal is transmitted by the sensor to the ECM. The ECM calculates the duty cycle of the square wave signal and converts that duty cycle to a relative humidity value in % through a transfer function. This diagnostic is enabled if the Powertrain Relay voltage is high enough.	Humidity Duty Cycle	>= 95.0 %	Powertrain Relay Voltage for a time No Active DTCs:	>= 11.0 Volts >= 0.9 seconds PowertrainRelayFault	40 failures out of 50 samples 1 sample every 100 msec	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Humidity Sensor Circuit Intermittent	P00F6	Detects a noisy or erratic signal in the humidity circuit by monitoring the humidity sensor and failing the diagnostic when the humidity signal has a noisier output than is expected. When the value of relative humidity in % is determined, a delta is calculated between the current reading and the previous reading. The absolute value of these deltas is summed over a number of humidity readings. The result of this summation is called a “string length”. Since the humidity signal is anticipated to be relatively smooth, a string length of a particular magnitude indicates a noisy or erratic humidity signal. The diagnostic will fail if the string length is too high. This diagnostic is enabled if the Powertrain Relay voltage is high enough.	String Length Where: "String Length" = sum of "Diff" calculated over And where: "Diff" = ABS(current Humidity reading - Humidity reading from 100 milliseconds previous)	> 80 % 10 consecutive Humidity readings	Powertrain Relay Voltage for a time No Active DTCs:	>= 11.0 Volts >= 0.9 seconds PowertrainRelayFault	4 failures out of 5 samples Each sample takes 1.0 seconds	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Mass Air Flow System Performance (naturally aspirated)	P0101	Detects a performance failure in the Mass Air Flow (MAF) sensor, such as when a MAF value is stuck in range. This diagnostic is performed using the Intake Flow Rationality Diagnostic (IFRD). IFRD calculates modeled values of sensors from other sensors. The other sensors are the Manifold Pressure (MAP) sensor and Throttle Position sensor (TPS). These modeled values are compared against the actual sensor values to see if they are similar. If they are similar, then the model passes. If they are not similar, then that model is considered to be failed. Certain combinations of model passes and model failures can be interpreted to be caused by a performance issue with the MAF sensor. In this case, the MAF Performance diagnostic will fail.	Filtered Throttle Model Error AND ABS(Measured Flow – Modeled Air Flow) Filtered AND ABS(Measured MAP – MAP Model 2) Filtered	<= 130 kPa*(g/s) > 11.0 grams/sec > 19.0 kPa	Engine Speed Engine Speed (Coolant Temp OR OBD Coolant Enable Criteria (Coolant Temp OR OBD Max Coolant Achieved Intake Air Temp Intake Air Temp Minimum total weight factor (all factors multiplied together) See Residual Weight Factor tables.	>= 400 RPM <= 6,500 RPM >= -9 Deg C = TRUE) <= 130 Deg C = FALSE) >= -20 Deg C <= 125 Deg C >= 0.50 Filtered Throttle Model Error multiplied by **P0101, P0106, P0121, P012B, P0236, P1101: TPS Residual Weight Factor based on RPM** Modeled Air Flow Error multiplied by **P0101, P0106, P010B, P0121, P012B, P0236, P1101: MAF1 Residual Weight Factor based on RPM** and **P0101, P0106, P010B, P0121, P012B, P0236, P1101: MAF1 Residual Weight Factor based on MAF Est**	Continuous Calculation are performed every 12.5 msec	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
						MAP Model 2 Error multiplied by **P0101, P0106, P0121, P012B, P0236, P1101: MAP2 Residual Weight Factor based on RPM**		
					No Active DTCs:	MAP_SensorCircuitFA EGRValvePerformance_FA MAF_SensorCircuitFA CrankSensor_FA ECT_Sensor_FA IAT_SensorFA		
					No Pending DTCs:	EGRValve_FP ECT_Sensor_Ckt_FP IAT_SensorCircuitFP		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Mass Air Flow Sensor Circuit Low Frequency	P0102	Detects a continuous short to ground in the MAF sensor circuit or a MAF sensor that is outputting a frequency that is too low. The diagnostic monitors the MAF sensor frequency output and fails the diagnostic when the MAF frequency is too low. The MAF sensor monitors the temperature of a circuit in the air flow of the engine. The temperature of this circuit is related to the air velocity across the sensor. The MAF sensor converts this air velocity to a mass air flow value. The mass air flow value is converted by the sensor to a frequency value in Hertz. A digital square wave signal is transmitted by the sensor to the ECM. The ECM calculates the frequency of the square wave signal and converts that frequency to a mass air flow value in grams/second through a transfer function.	MAF Output	<= 750 Hertz (~ 0.30 gm/sec)	Engine Run Time Engine Speed Ignition Voltage Above criteria present for a period of time	> 1.0 seconds >= 300 RPM >= 10.0 Volts >= 1.0 seconds	200 failures out of 250 samples 1 sample every cylinder firing event	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Mass Air Flow Sensor Circuit High Frequency	P0103	Detects a MAF sensor that is outputting a frequency signal that is too high. The diagnostic monitors the MAF sensor frequency output and fails the diagnostic when the MAF frequency is too high. The MAF sensor monitors the temperature of a circuit in the air flow of the engine. The temperature of this circuit is related to the air velocity across the sensor. The MAF sensor converts this air velocity to a mass air flow value. The mass air flow value is converted by the sensor to a frequency value in Hertz. A digital square wave signal is transmitted by the sensor to the ECM. The ECM calculates the frequency of the square wave signal and converts that frequency to a mass air flow value in grams/second through a transfer function.	MAF Output	>= 14,500 Hertz (~ 412.2 gm/sec)	Engine Run Time Engine Speed Ignition Voltage Above criteria present for a period of time	> 1.0 seconds >= 300 RPM >= 10.0 Volts >= 1.0 seconds	200 failures out of 250 samples 1 sample every cylinder firing event	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Manifold Absolute Pressure Sensor Performance (naturally aspirated)	P0106	Detects a performance failure in the Manifold Pressure (MAP) sensor, such as when a MAP value is stuck in range. If the engine has been off for a sufficient amount of time, the pressure values in the induction system will have equalized. The MAP sensor value is checked to see if it is within the normal expected atmospheric pressure range. If it is not, then the MAP performance diagnostic will fail. The engine running portion of this diagnostic is performed using the Intake Flow Rationality Diagnostic (IFRD). IFRD calculates modeled values of sensors from other sensors. The other sensors are the Mass Air Flow (MAF) sensor and Throttle Position sensor (TPS). These modeled values are compared against the actual sensor values to see if they are similar. If they are similar, then the model	<u>**Engine Running:**</u> Filtered Throttle Model Error AND ABS(Measured MAP – MAP Model 1) Filtered AND ABS(Measured MAP – MAP Model 2) Filtered	 <= 130 kPa*(g/s) > 19.0 kPa > 19.0 kPa	Engine Speed Engine Speed (Coolant Temp OR OBD Coolant Enable Criteria (Coolant Temp OR OBD Max Coolant Achieved Intake Air Temp Intake Air Temp Minimum total weight factor (all factors multiplied together) See Residual Weight Factor tables. No Active DTCs:	>= 400 RPM <= 6,500 RPM >= -9 Deg C = TRUE) <= 130 Deg C = FALSE) >= -20 Deg C <= 125 Deg C >= 0.50 Filtered Throttle Model Error multiplied by **P0101, P0106, P0121, P012B, P0236, P1101: TPS Residual Weight Factor based on RPM** MAP Model 1 Error multiplied by **P0101, P0106, P0121, P012B, P0236, P1101: MAP1 Residual Weight Factor based on RPM** MAP Model 2 Error multiplied by **P0101, P0106, P0121, P012B, P0236, P1101: MAP2 Residual Weight Factor based on RPM** MAP_SensorCircuitFA	Continuous Calculations are performed every 12.5 msec	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		passes. If they are not similar, then that model is considered to be failed. Certain combinations of model passes and model failures can be interpreted to be caused by a performance issue with the MAP sensor. In this case, the MAP Performance diagnostic will fail.			No Pending DTCs:	EGRValvePerformance_FA MAF_SensorCircuitFA CrankSensor_FA ECT_Sensor_FA IAT_SensorFA EGRValve_FP ECT_Sensor_Ckt_FP IAT_SensorCircuitFP		
			Engine Not Rotating: Manifold Pressure OR Manifold Pressure	< 50.0 kPa > 115.0 kPa	Time between current ignition cycle and the last time the engine was running Engine is not rotating No Active DTCs: No Pending DTCs:	> 10.0 seconds EngineModeNotRunTimerError MAP_SensorCircuitFA AAP_SnsrCktFA MAP_SensorCircuitFP AAP_SnsrCktFP	4 failures out of 5 samples 1 sample every 12.5 msec	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Manifold Absolute Pressure Sensor Circuit Low (Gen III)	P0107	Detects a continuous short to ground in the Manifold Absolute Pressure (MAP) signal circuit by monitoring the MAP sensor output voltage and failing the diagnostic when the MAP voltage is too low. The MAP sensor is a pressure transducer which outputs a voltage proportional to the absolute pressure.	MAP Voltage	< 3.0 % of 5 Volt Range (This is equal to 6.1 kPa)	Continuous		320 failures out of 400 samples 1 sample every 12.5 msec	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Manifold Absolute Pressure Sensor Circuit High (Gen III)	P0108	Detects a continuous short to power or open circuit in the Manifold Absolute Pressure (MAP) signal circuit by monitoring the MAP sensor output voltage and failing the diagnostic when the MAP voltage is too high. The MAP sensor is a pressure transducer which outputs a voltage proportional to the absolute pressure.	MAP Voltage	> 90.0 % of 5 Volt Range (This is equal to 115.0 kPa)	Continuous		320 failures out of 400 samples 1 sample every 12.5 msec	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Intake Air Temperature Sensor Circuit Performance (applications with humidity sensor, but no manifold temperature sensor)	P0111	Detects an Intake Air Temperature (IAT) sensor value that is stuck in range by comparing the IAT sensor value against the IAT2 and coolant temperature sensor values and failing the diagnostic if the IAT value is more different than the IAT2 and coolant temperature values than is expected. If the engine has been off for a long enough period of time, the air temperature values in the engine compartment of the vehicle are considered to have equalized, and the diagnostic can be enabled. The diagnostic will fail if the IAT2 and coolant temperature values are similar, and the IAT value is not similar to the IAT2 and coolant temperature values. This diagnostic is executed once per ignition cycle if the enable conditions are met.	ABS(Power Up IAT - Power Up IAT2) AND ABS(Power Up ECT – Power Up IAT) > ABS(Power Up ECT – Power Up IAT2)	> 25 deg C	Time between current ignition cycle and the last time the engine was running Powertrain Relay Voltage for a time No Active DTCs:	> 28,800 seconds >= 11.0 Volts >= 0.9 seconds PowertrainRelayFault ECT_Sensor_Ckt_FA IAT_SensorCircuitFA HumTempSnsrCktFA EngineModeNotRunTimer Error	Executes once at the beginning of each ignition cycle if enable conditions are met	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Intake Air Temperature Sensor Circuit Low	P0112	Detects a continuous short to ground in the Intake Air Temperature (IAT) signal circuit by monitoring the IAT sensor output resistance and failing the diagnostic when the IAT resistance is too low. The IAT sensor is a thermistor in which the resistance across the sensor can be equated to a temperature. A lower resistance is equivalent to a higher temperature.	Raw IAT Input	< 62.00 Ohms (~150 deg C)	Engine Run Time	> 0.00 seconds	40 failures out of 50 samples 1 sample every 100 msec	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Intake Air Temperature Sensor Circuit High	P0113	Detects a continuous open circuit in the Intake Air Temperature (IAT) signal circuit by monitoring the IAT sensor output resistance and failing the diagnostic when the IAT resistance is too high. The IAT sensor is a thermistor in which the resistance across the sensor can be equated to a temperature. A higher resistance is equivalent to a lower temperature.	Raw IAT Input	> 126,840 Ohms (~-60 deg C)	Engine Run Time	> 0.00 seconds	40 failures out of 50 samples 1 sample every 100 msec	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Intake Air Temperature Sensor Intermittent In-Range	P0114	Detects a noisy or erratic signal in the Intake Air Temperature (IAT) circuit by monitoring the IAT sensor and failing the diagnostic when the IAT signal has a noisier output than is expected. When the value of the IAT signal in °C is determined, a delta is calculated between the current reading and the previous reading. The absolute value of these deltas is summed over a number of IAT readings. The result of this summation is called a “string length”. Since the IAT signal is anticipated to be relatively smooth, a string length of a particular magnitude indicates a noisy or erratic IAT signal. The diagnostic will fail if the string length is too high.	String Length Where: "String Length" = sum of "Diff" calculated over And where: "Diff" = ABS(current IAT reading - IAT reading from 100 milliseconds previous)	> 80.00 deg C 10 consecutive IAT readings	Continuous		4 failures out of 5 samples Each sample takes 1.0 seconds	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Engine Coolant Temperature (ECT) Sensor Performance	P0116	This DTC detects an ECT (Engine Coolant temperature) sensor that is biased high or stuck above the thermostat monitoring diagnostic. This check is performed after a soak condition.	A failure will be reported if any of the following occur: 1) ECT at power up > IAT at power up by an IAT based table lookup value after a minimum 28,800 second soak (fast fail). 2) ECT at power up > IAT at power up by 20.0 ºC after a minimum 28,800 second soak and a block heater has not been detected. 3) ECT at power up > IAT at power up by 20.0 C after a minimum 28,800 seconds soak and the time spent cranking the engine without starting is greater than 7.5 seconds with the LowFuelConditionDiag	See **P0116_Fail if power up ECT exceeds IAT by these values** in the Supporting tables section = False	No Active DTC's Non-volatile memory initization Test complete this trip Test aborted this trip IAT LowFuelCondition Diag ================== Block Heater detection is enabled when either of the following occurs: 1) ECT at power up > IAT at power up by 2) Cranking time ================== Block Heater is detected and diagnostic is aborted when 1) or 2) occurs: 1a) Vehicle drive time 1b) Vehicle speed 1c) Additional Vehicle drive time is provided to 1a when Vehicle speed is below 1b as follows:	VehicleSpeedSensor_FA IAT_SensorFA ECT_Sensor_Ckt_FA IgnitionOffTimeValid TimeSinceEngineRunning Valid = Not occurred = False = False ≥ -9 ºC = False ================== > 20.0 ºC < 7.5 seconds ================== > 400 seconds with > 15 MPH 0.00 times the seconds with vehicle speed below 1b	1 failure 500 msec/ sample Once per valid cold start	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					1d) IAT drops from power up IAT 2a) ECT drops from power up ECT 2b) Engine run time =================== Diagnostic is aborted when 3) or 4) occurs: 3) Engine run time with vehicle speed below 1b 4) Minimum IAT during test	≥ 5.0 ºC ≥ 5 ºC Within ≤ 60 seconds ================== > 1800 seconds ≤ -9 ºC		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Engine Coolant Temp Sensor Circuit Low	P0117	Circuit Continuity This DTC detects a short to ground in the ECT (Engine Coolant temperature) signal circuit or the ECT sensor. This is accomplished by monitoring the resistance of the circuit. If the resistance goes out of the expected range the DTC is set.	ECT Resistance (@ 150ºC)	< 55 Ohms			5 failures out of 6 samples 1 sec/ sample Continuous	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Engine Coolant Temp Sensor Circuit High	P0118	Circuit Continuity This DTC detects a short to high or open in the ECT (Engine Coolant temperature) signal circuit or the ECT sensor. This is accomplished by monitoring the resistance of the circuit. If the resistance goes out of the expected range the DTC is set.	ECT Resistance (@ -60ºC)	> 134,000 Ohms	Engine run time OR IAT min	> 10.0 seconds ≥ -9.0 °C	5 failures out of 6 samples 1 sec/ sample Continuous	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Engine Coolant Temperature (ECT) Sensor Circuit Intermittent	P0119	Circuit Erratic This DTC detects large step changes in the ECT (Engine Coolant temperature) signal circuit or the ECT sensor. Allowable high and low limits are calculated for the next sample based on the previous sample and sensor time constant. If the sensor responds faster than should be possible the DTC is set.	ECT temperature step change: 1) postive step change is greater than calculated high limit OR 2) negitive step change is lower than calculated low limit. The calculated high and low limits for the next reading use the following calibrations: 1) Sensor time constant 2) Sensor low limit 3) Sensor high limit *****Generic Example***** If the last ECT reading was 90 Deg C, the Time constant was calibrated at 10 seconds, the low limit was calibrated to -80 Deg C and the high limit was calibrated to 200 Deg C the caluculated limits are 101 Deg C and 73 Deg C. The next reading (after the 90 Deg C reading) must be between 73 Deg C and 101 Deg C to be valid. *****************************	7.4 seconds -60.0 Deg C 200.0 Deg C	No Active DTC's	ECT_Sensor_Ckt_FP	3 failures out of 4 samples 1 sec/ sample Continuous	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Throttle Position Sensor Performance (naturally aspirated)	P0121	Detects a performance failure in the Throttle Position sensor (TPS) sensor, such as when a TPS value is stuck in range. This diagnostic is performed using the Intake Flow Rationality Diagnostic (IFRD). IFRD calculates modeled values of sensors from other sensors. The other sensors are the Manifold Pressure (MAP) sensor and Mass Air Flow (MAF) sensor. These modeled values are compared against the actual sensor values to see if they are similar. If they are similar, then the model passes. If they are not similar, then that model is considered to be failed. Certain combinations of model passes and model failures can be interpreted to be caused by a performance issue with the TPS sensor. In this case, the TPS Performance diagnostic will fail.	Filtered Throttle Model Error AND ABS(Measured MAP – MAP Model 2) Filtered	> 130 kPa*(g/s) <= 19.0 kPa	Engine Speed Engine Speed (Coolant Temp OR OBD Coolant Enable Criteria (Coolant Temp OR OBD Max Coolant Achieved Intake Air Temp Intake Air Temp Minimum total weight factor (all factors multiplied together) See Residual Weight Factor tables. No Active DTCs:	>= 400 RPM <= 6,500 RPM >= -9 Deg C = TRUE) <= 130 Deg C = FALSE) >= -20 Deg C <= 125 Deg C >= 0.50 Filtered Throttle Model Error multiplied by **P0101, P0106, P0121, P012B, P0236, P1101: TPS Residual Weight Factor based on RPM** MAP Model 2 Error multiplied by **P0101, P0106, P0121, P012B, P0236, P1101: MAP2 Residual Weight Factor based on RPM** MAP_SensorCircuitFA EGRValvePerformance_FA MAF_SensorCircuitFA CrankSensor_FA ECT_Sensor_FA IAT_SensorFA	Continuous Calculation are performed every 12.5 msec	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					No Pending DTCs:	EGRValve_FP ECT_Sensor_Ckt_FP IAT_SensorCircuitFP		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
TPS1 Circuit Low	P0122	Detects a continuous or intermittent short low or open in TPS1 circuit by monitoring the TPS 1 sensor percent Vref and failing the diagnostic when the TPS percent Vref is too low. This diagnostic only runs when battery voltage is high enough.	TPS1 % Vref <	0.3250 % Vref	Run/Crank voltage No 5V reference error or fault for # 4 5V reference circuit	> 6.41 Volts P06A3	79 / 159 counts; 57 counts continuous; 3.125 ms /count in the ECM main processor	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
TPS1 Circuit High	P0123	Detects a continuous or intermittent short high in TPS1 circuit by monitoring the TPS 1 sensor percent Vref and failing the diagnostic when the TPS percent Vref is too high. This diagnostic only runs when battery voltage is high enough.	TPS1 % Vref >	4.750 % Vref	Run/Crank voltage No 5V reference error or fault for # 4 5V reference circuit	> 6.41 Volts P06A3	79 / 159 counts; 57 counts continuous; 3.125 ms /count in the ECM main processor	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Engine Coolant Temperature Below Stat Regulating Temperature	P0128	This DTC detects if the ECT (EngineCoolant temperature) does not achieve the required target temperature after an allowed energy accumulation by the engine. This can be caused by an ECT sensor biased low or a cooling system that is not warming up correctly because of a stuck open thermostat or other fault.	Energy is accumulated after the first conbustion event using Range #1 or #2 below: Thermostat type is divided into normal (non-heated) and electrically heated. For this application the "type" cal (KeTHMG_b_TMS_ElecThstEquipped) = 0 If the type cal is equal to one, the application has an electrically heated t-stat, if equal to zero the the application has an non heated t-stat. See appropiate section below. ***************************** Type cal above = 1 (Electrically heated t-stat) == == == == Range #1 (Primary) ECT reaches Commanded temperature minus 19 °C when Ambient min is ≤ 52 °C and > 10 °C. Note: Warm up target for range #1 will be at least 64 °C == == == == Range #2 (Alternate) ECT reaches Commanded temperature minus 19 °C when Ambient min is ≤ 10 °C and > -9 °C. Note: Warm up target for range #2 will be at least	See the two tables named: **P0128_Maximum Accumulated Energy for Start-up ECT conditions - Primary** and **P0128_Maximum Accumulated Energy for Start-up ECT conditions - Alternate** in the Supporting tables section. This diagnostic models the net energy into and out of the cooling	No Active DTC's Engine not run time (soaking time before current trip) Engine run time Fuel Condition Distance traveled *************************** If Engine RPM is continuously greater than for this time period The diagnostic test for this key cycle will abort *************************** *************************** If T-Stat Heater commanded duty cycle for this time period	ECT_Sensor_Ckt_FA ECT_Sensor_Perf_FA VehicleSpeedSensor_FA OAT_PtEstFiltFA IAT_SensorCircuitFA MAF_SensorFA THMR_AWP_AuxPumpFA THMR_AHV_FA THMR_SWP_Control_FA THMR_SWP_NoFlow_FA THMR_SWP_FlowStuckOn_FA EngineTorqueEstInaccurate ≥ 1,800 seconds 30 ≤ Eng Run Tme ≤ 1,400 seconds Ethanol ≤ 87 % ≥ 0.93 miles *************************** 9,999 rpm 5.0 seconds *************************** *************************** > 20.0 % duty cycle > 5.0 seconds	1 failure to set DTC 1 sec/ sample Once per ignition key cycle	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			55 °C ***************************** Type cal above = 0 (non - heated t-stat) == == == == Range #1 (Primary) ECT reaches 71 °C when Ambient min is ≤ 52 °C and > 10 °C. == == == == Range #2 (Alternate) ECT reaches 55 °C when Ambient min is ≤ 10 °C and > -9 °C. *****************************	system during the warm-up process. The five energy terms are: heat from combustion (with AFM correction), heat from after-run, heat loss to enviroment, heat loss to cabin and heat loss to DFCO.	The diagnostic test for this key cycle will abort *************************** ECT at start run	*************************** -40 ≤ ECT ≤ 52 °C		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
O2S Circuit Low Voltage Bank 1 Sensor 1	P0131	This DTC determines if the O2 sensor signal circuit is shorted low. When enabled, the diagnostic monitors the O2S signal and compares it to the threshold. The diagnostic failure counter is incremented if the O2S signal is below the threshold value. This DTC is set based on the fail and sample counters.	Oxygen Sensor Signal	< 40.0 mVolts	No Active DTC's	TPS_ThrottleAuthorityDefaulted MAP_SensorFA AIR System FA Ethanol Composition Sensor FA EvapPurgeSolenoidCircuit_FA EvapFlowDuringNonPurge_FA EvapVentSolenoidCircuit_FA EvapSmallLeak_FA EvapEmissionSystem_FA FuelTankPressureSnsrCkt_FA FuelInjectorCircuit_FA	320 failures out of 400 samples Frequency: Continuous in 100 milli - second loop	Type B, 2 Trips
					AIR intrusive test Fuel intrusive test Idle intrusive test EGR intrusive test System Voltage EGR Device Control Idle Device Control Fuel Device Control AIR Device Control	= Not active = Not active = Not active = Not active 10.0 < Volts = Not active = Not active = Not active = Not active		
					Low Fuel Condition Only when FuelLevelDataFault	= False = False		
					Commanded Equivalence Ratio Air Per Cylinder Fuel Control State Closed Loop Active	0.9912 < ratio < 1.0137 65 < mgram < 500 = Closed Loop = TRUE (Please see "**Closed Loop Enable Clarification**" in Supporting Tables).		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					All Fuel Injectors for active Cylinders Fuel Condition Ethanol Estimation in Progress Fuel State All of the above met for	Enabled (On) Ethanol ≤ 87 % = Not Active (Please see "**Ethanol Estimation in Progress**" in Supporting Tables). DFCO not active > 5.0 seconds		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
O2S Circuit High Voltage Bank 1 Sensor 1	P0132	This DTC determines if the O2 sensor signal circuit is shorted high or open. When enabled, the diagnostic monitors the O2S signal and compares it to the threshold. The diagnostic failure counter is incremented if the O2S signal is above the threshold value. This DTC is set based on the fail and sample counters.	Oxygen Sensor Signal	> 1,050 mvolts	No Active DTC's System Voltage AFM Status Heater Warm-up delay Engine Run Time Engine Run Accum Low Fuel Condition Diag Only when FuelLevelDataFault *********************** Secondary delay after above conditions are complete (cold start condition) Secondary delay after above conditions are complete (not cold start condition) Commanded Equivalence Ratio *********************** All of the above met for	TPS_ThrottleAuthorityDefaulted MAF_SensorFA MAP_SensorFA EvapExcessPurgePsbl_FA FuelInjectorCircuit_FA Ethanol Composition Sensor FA AIR System FA 10.0 < Volts = All Cylinders active = Complete > 5.0 seconds > 30.0 seconds = False = False *********************** > 100.0 seconds when engine soak time > 28,800 seconds > 100.0 seconds when engine soak time ≤ 28,800 seconds ≤ 1.014 EQR *********************** > 3.0 seconds	100 failures out of 125 samples Frequency: Continuous in 100 milli - second loop	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
O2S Slow Response Bank 1 Sensor 1) (For use with ESPD and w/o WRAF	P0133	This DTC determines if the Bank 1 primary O2 sensor has a slow response (in the Rich to Lean (R2L) or Lean to Rich (L2R) direction) and thereby can no longer be used for closed loop fuel control based on emission correlation testing. This diagnostic runs passively (see enable conditions) and monitors the time the O2 sensor signal is between an upper and lower voltage thresholds over the sample period. The diagnostic also monitors the O2 sensor signal for the number of Slope Time (ST) switches in each direction between the same upper and lower voltage thresholds over the sample period. When the required data is collected, an average R2L and L2R response time and individual R2L and L2R Slope Time (ST) switch count is calculated. This fault is set when the L2R and R2L response test results are compared to the	Fault condition present when the average response time is caluclated over the test time, and compared to the threshold. OR Slope Time L/R Switches OR Slope Time R/L Switches	Refer to **P0133_O2S Slow Response Bank 1 Sensor 1 Pass/Fail Threshold table** in the Supporting Tables tab < 5 < 5 The test averages the signal response time over 60.0 seconds when the signal is transitioning between 400 mvolts and 600 mvolts. An average rich to lean time and lean to rich time are each calculated separately. Note: the table listed above uses the following calibratable X axis: **P0133_KnEOSD_t_ST_LRC_LimRS1** and calibratable Y axis: **P0133_KnEOSD_t_ST_RLC_LimRS1**	No Active DTC's Bank 1 Sensor 1 DTC's not active System Voltage EGR Device Control Idle Device Control Fuel Device Control AIR Device Control Low Fuel Condition Only when FuelLevelDataFault Green O2S Condition	TPS_ThrottleAuthorityDefaulted MAP_SensorFA IAT_SensorFA ECT_Sensor_FA AmbientAirDefault MAF_SensorFA EvapPurgeSolenoidCircuit_FA EvapFlowDuringNonPurge_FA EvapVentSolenoidCircuit_FA EvapSmallLeak_FA EvapEmissionSystem_FA FuelTankPressureSnsrCkt_FA FuelInjectorCircuit_FA AIR System FA Ethanol Composition Sensor FA EngineMisfireDetected_FA P0131, P0132, P0134 > 10.0 Volts = Not active = Not active = Not active = Not active = False = False = Not Valid, Green O2S condition is considered valid until the accumulated air flow is greater than	Sample time is 60 seconds Frequency: Once per trip	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		"P0133_O2S Slow Response Bank 1 Sensor 1 "Pass/Fail Threshold Table" and the outcome determines a response faulted condition. Additionally, this fault is set when the L2R or R2L slope time switch count test results are less than the ST individual thresholds.				**Multiple DTC Use_Green Sensor Delay Criteria - Limit** for the following locations: B1S1, B2S1 (if applicable) in Supporting Tables tab. Airflow accumulation is only enabled when airflow is above 18.0 grams/sec.		
					O2 Heater on for Learned Htr resistance	≥ 30 seconds = Valid (the heater resistance has learned since NVM reset, see enable conditions for "HO2S Heater Resistance DTC's")		
					Engine Coolant (Or OBD Coolant Enable Criteria	> 60 ºC = TRUE)		
					IAT Engine run Accum	> -40 ºC > 30 seconds		
					Time since any AFM status change Time since Purge On to Off change Time since Purge Off to On change	> 1.5 seconds > 1.0 seconds > 1.5 seconds		
					Engine airflow Engine speed Fuel Condition Baro Air Per Cylinder	10 ≤ grams/sec ≤ 40 1,300 ≤ RPM ≤ 3,500 < 87 % Ethanol > 70 kpa ≥ 130 mGrams		
					Fuel Control State Closed Loop Active	= Closed Loop = TRUE (Please see "**Closed Loop Enable**		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					LTM (Block Learn) fuel cell Transient Fuel Mass Baro Fuel Control State Fuel State Commanded Proportional Gain ================== All of the above met for	**Clarification**" in Supporting Tables). = Enabled, refer to **Multiple DTC Use - Response Cell Enable Table** for additional info. ≤ 100.0 mgrams = Not Defaulted not = Power Enrichment DFCO not active ≥ 0.0 % ================== > 2.0 seconds		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
O2S Heater Performance Bank 1 Sensor 1	P0135	This DTC determines if the O2 sensor heater is functioning properly by monitoring the current through the heater circuit. This test compares the measured heater current (monitored thru the low side driver) and compares it to the expected values (over the voltage range provided) for the released sensor. The diagnostic failure counter is incremented if the heater current is outside the expected range. This DTC is set based on the fail and sample counters.	Heater Current outside of the expected range of	0.2 < Amps < 2.0	No Active DTC's System Voltage Heater Warm-up delay O2S Heater device control B1S1 O2S Heater Duty Cycle All of the above met for	ECT_Sensor_FA > 10.0 Volts = Complete = Not active > zero > 120 seconds	7 failures out of 9 samples Frequency: 3 tests per trip 10 seconds delay between tests and 1 second execution rate	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
O2S Circuit Low Voltage Bank 1 Sensor 2) (For Single Bank Exhaust Only	P0137	This DTC determines if the O2 sensor signal circuit is shorted low. When enabled, the diagnostic monitors the O2S signal and compares it to the threshold. The diagnostic failure counter is incremented if the O2S signal is below the threshold value. This DTC is set based on the fail and sample counters.	Oxygen Sensor Signal	< 40 mvolts	No Active DTC's AIR intrusive test Fuel intrusive test Idle intrusive test EGR intrusive test System Voltage EGR Device Control Idle Device Control Fuel Device Control AIR Device Control Low Fuel Condition Only when FuelLevelDataFault Commanded Equivalence Ratio Air Per Cylinder Fuel Control State Closed Loop Active	TPS_ThrottleAuthorityDefaulted MAP_SensorFA AIR System FA Ethanol Composition Sensor FA EvapPurgeSolenoidCircuit_FA EvapFlowDuringNonPurge_FA EvapVentSolenoidCircuit_FA EvapSmallLeak_FA EvapEmissionSystem_FA FuelTankPressureSnsrCkt_FA FuelInjectorCircuit_FA = Not active = Not active = Not active = Not active 10.0 < Volts = Not active = Not active = Not active = Not active = False = False 0.991 ≤ ratio ≤ 1.014 65 ≤ mgrams ≤ 500 = Closed Loop = TRUE (Please see "**Closed Loop Enable Clarification**" in Supporting Tables).	320 failures out of 400 samples Frequency: Continuous in 100 milli - second loop	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					All Fuel Injectors for active Cylinders Fuel Condition Ethanol Estimation in Progress Fuel State All of the above met for	Enabled (On) Ethanol ≤ 87 % = Not Active (Please see “**Ethanol Estimation in Progress**” in Supporting Tables). DFCO not active > 5.0 seconds		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
O2S Circuit High Voltage Bank 1 Sensor 2) (For Single Bank Exhaust Only	P0138	This DTC determines if the O2 sensor signal circuit is shorted high or open. When enabled, the diagnostic monitors the O2S signal and compares it to the threshold. The diagnostic failure counter is incremented if the O2S signal is above the threshold value. This DTC is set based on the fail and sample counters.	Oxygen Sensor Signal	> 1,050 mvolts	No Active DTC's	TPS_ThrottleAuthorityDefaulted MAF_SensorFA MAP_SensorFA EvapExcessPurgePsbl_FA FuelInjectorCircuit_FA Ethanol Composition Sensor FA AIR System FA	100 failures out of 125 samples Frequency: Continuous in 100 milli - second loop	Type B, 2 Trips
					System Voltage AFM Status Heater Warm-up delay Engine Run Time Engine Run Accum	10.0 < Volts = All Cylinders active = Complete > 5.0 seconds > 30.0 seconds		
					Low Fuel Condition Only when FuelLevelDataFault	= False = False		
					*********************** Secondary delay after above conditions are complete (cold start condition)	*********************** > 150.0 seconds when engine soak time > 28,800 seconds		
					Secondary delay after above conditions are complete (not cold start condition)	> 150.0 seconds when engine soak time ≤ 28,800 seconds		
					Commanded Equivalence Ratio	≤ 1.014 EQR		
					*********************** All of the above met for	*********************** > 3.0 seconds		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
O2 Sensor Slow Response Rich to Lean Bank 1 Sensor 2	P013A	The P013A diagnostic is the third in a sequence of six intrusive secondary O2 monitors which include DTCs P2270, P013E, P013A, P2271, P013F, & P013B. This DTC determines if the secondary O2 sensor has an slow response to an A/F change from Rich to Lean and thereby can no longer be used for secondary O2 sensor fuel control or for catalyst monitoring. This diagnostic commands fuel cut off while monitoring the sensor signal and the accumulated mass air flow. Note: The Primary method is used when the secondary O2 sensor signal transitions from above the upper threshold to below the lower threshold, otherwise the Secondary method is used. <u>Primary method</u>: The P013A diagnostic measures the secondary O2 sensor voltage response rate	Primary Method: The EWMA of the Post O2 sensor normalized integral value. The EWMA repass limit is The EWMA calculation uses a 0.15 coefficient. OR Secondary Method: The Accumulated mass air flow monitored during the Slow Response Test (between the upper and lower voltage thresholds)	> 8.0 units ≤ 7.5 units > 30.0 grams (upper voltage threshold is 450 mvolts and lower voltage threshold is 150 mvolts)	No Active DTC's B1S2 DTC's Not Active this key cycle System Voltage Learned heater resistance Green O2S Condition	TPS_ThrottleAuthorityDefaulted ECT_Sensor_FA IAT_SensorFA MAF_SensorFA MAP_SensorFA AIR System FA FuelInjectorCircuit_FA FuelTrimSystemB1_FA FuelTrimSystemB2_FA EngineMisfireDetected_FA Ethanol Composition Sensor FA O2S_Bank_ 1_TFTKO O2S_Bank_ 2_TFTKO P013B, P013E, P013F, P2270 or P2271 > 10.0 Volts = Valid (the heater resistance has learned since NVM reset, see enable conditions for "HO2S Heater Resistance DTC's") = Not Valid, Green O2S condition is considered valid until the accumulated air flow is greater than **Multiple DTC Use_Green Sensor Delay Criteria - Limit** for the following locations: B1S2, B2S2 (if applicable) in Supporting Tables tab. Airflow accumulation is only enabled when airflow is above 18.0 grams/sec.	Frequency: Once per trip Note: if NaPOPD_b_ResetFastRespFunc = FALSE for the given Fuel Bank OR NaPOPD_b_RapidResponseActive = TRUE, multiple tests per trip are allowed.	Type A, 1 Trips EWMA

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		between an upper and lower voltage threshold. The response rate is then normalized to mass air flow rate and scaled resulting in a normalized intregral value. The normalized integral is fed into a 1st order lag filter to update the final EWMA result. DTC P013A is set when the EWMA value exceeds the EWMA threshold. Note: This EWMA diagnostic employs two features, Fast Initial Response (FIR) and Rapid Step Response (RSR). The FIR feature is used following a code clear event or any event that results in erasure of the engine controller's non-volatile memory. The RSR feature is used when a step change in the test result is identified. Both these temporary features improve the EWMA result following a non-typical event by allowing multiple intrusive tests on a given trip until the total number of tests reach a calibration value. Secondary method:			Low Fuel Condition Only when FuelLevelDataFault Post fuel cell Crankshaft Torque DTC's Passed =================== After above conditions are met: DFCO mode is continued (wo driver initiated pedal input).	= False = False = Enabled, refer to **Multiple DTC Use - Block learn cells to enable Post oxygen sensor tests** for additional info. < 100.0 Nm P2270 (and P2272 if applicable) P013E (and P014A if applicable) ==================		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		This fault is set if the secondary O2 sensor does not achieve the required lower voltage threshold before the accumulated mass air flow threshold is reached.						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
O2 Sensor Slow Response Lean to Rich Bank 1 Sensor 2	P013B	The P013B diagnostic is the sixth in a sequence of six intrusive secondary O2 monitors which include DTCs P2270, P013E, P013A, P2271, P013F, & P013B. This DTC determines if the secondary O2 sensor has an slow response to an A/F change from Lean to Rich and thereby can no longer be used for secondary O2 sensor fuel control or for catalyst monitoring. This diagnostic increases the delivered fuel while monitoring the sensor signal and the accumulated mass air flow. Note: The Primary method is used when the secondary O2 sensor signal transitions from below the lower threshold to above the upper threshold, otherwise the Secondary method is used. <u>Primary method</u>: The P013B diagnostic measures the secondary O2 sensor voltage response rate	Primary Method: The EWMA of the Post O2 sensor normalized integral value. The EWMA repass limit is The EWMA calculation uses a 0.20 coefficient. OR Secondary Method: The Accumulated mass air flow monitored during the Slow Response Test (between the upper and lower voltage thresholds)	> 8.0 units ≤ 7.5 units > 100 grams (lower voltage threshold is 350 mvolts and upper voltage threshold is 650 mvolts)	No Active DTC's B1S2 DTC's Not Active this key cycle System Voltage Learned heater resistance Green O2S Condition	TPS_ThrottleAuthorityDefaulted ECT_Sensor_FA IAT_SensorFA MAF_SensorFA MAP_SensorFA AIR System FA FuelInjectorCircuit_FA FuelTrimSystemB1_FA FuelTrimSystemB2_FA EngineMisfireDetected_FA Ethanol Composition Sensor FA O2S_Bank_ 1_TFTKO O2S_Bank_ 2_TFTKO P013A, P013E, P013F, P2270 or P2271 > 10.0 Volts = Valid (the heater resistance has learned since NVM reset, see enable conditions for "HO2S Heater Resistance DTC's") = Not Valid, Green O2S condition is considered valid until the accumulated air flow is greater than **Multiple DTC Use_Green Sensor Delay Criteria - Limit** for the following locations: B1S2, B2S2 (if applicable) in Supporting Tables tab. Airflow accumulation is only enabled when airflow	Frequency: Once per trip Note: if NaPOPD_b_ResetFastRespFunc = FALSE for the given Fuel Bank OR NaPOPD_b_RapidResponseActive = TRUE, multiple tests per trip are allowed.	Type A, 1 Trips EWMA

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		between an lower and upper voltage threshold. The response rate is then normalized to mass air flow rate and scaled resulting in a normalized intregral value. The normalized integral is fed into a 1st order lag filter to update the final EWMA result. DTC P013B is set when the EWMA value exceeds the EWMA threshold. Note: This EWMA diagnostic employs two features, Fast Initial Response (FIR) and Rapid Step Response (RSR). The FIR feature is used following a code clear event or any event that results in erasure of the engine controller's non-volatile memory. The RSR feature is used when a step change in the test result is identified. Both these temporary features improve the EWMA result following a non-typical event by allowing multiple intrusive tests on a given trip until the total number of tests reach a calibration value. Secondary method:			 Green Cat System Condition Low Fuel Condition Only when FuelLevelDataFault Post fuel cell DTC's Passed =================== After above conditions are met: Fuel Enrich mode continued. =================	is above 18.0 grams/sec. = Not Valid, Green Cat System condition is considered valid until accumulated airflow is greater than 360,000 grams. Airflow accumulation is only enabled when estimated Cat temperature is above 600 Deg C and airflow is greater than 18.0 grams/sec. (Note: This feature is only enabled when the vehicle is new and cannot be enabled in service). = False = False = Enabled, refer to **Multiple DTC Use - Block learn cells to enable Post oxygen sensor tests** for additional info. P2270 P013E P013A P2271 P013F ==================		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		This fault is set if the secondary O2 sensor does not achieve the required upper voltage threshold before the accumulated mass air flow threshold is reached.			During this test the following must stay TRUE or the test will abort: 0.960 ≤ Base Commanded EQR ≤ 1.080			

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
O2 Sensor Delayed Response Rich to Lean Bank 1 Sensor 2	P013E	The P013E diagnostic is the second in a sequence of six intrusive secondary O2 monitors which include DTCs P2270, P013E, P013A, P2271, P013F, & P013B. This DTC determines if the secondary O2 sensor has an initial delayed response to an A/F change from Rich to Lean and thereby can no longer be used for secondary O2 sensor fuel control or for catalyst monitoring. This diagnostic commands fuel cut off while monitoring the sensor signal and the accumulated mass air flow. This fault is set if the secondary O2 sensor does not achieve the required voltage before the accumulated mass air flow threshold is reached.	Post O2 sensor voltage AND The Accumulated mass air flow monitored during the Delayed Response Test under DFCO DFCO begins after: 1) Catalyst has been rich for a minimum of AND 2) Catalyst Rich Accumulation Air Flow is	> 450 mvolts > 50 grams > 1 secs ≥ 9.0 grams	No Active DTC's B1S2 DTC's Not Active this key cycle System Voltage Learned heater resistance Green O2S Condition	TPS_ThrottleAuthorityDefaulted ECT_Sensor_FA IAT_SensorFA MAF_SensorFA MAP_SensorFA AIR System FA FuelInjectorCircuit_FA FuelTrimSystemB1_FA FuelTrimSystemB2_FA EngineMisfireDetected_FA Ethanol Composition Sensor FA O2S_Bank_ 1_TFTKO O2S_Bank_ 2_TFTKO P013A, P013B, P013F, P2270 or P2271 > 10.0 Volts = Valid (the heater resistance has learned since NVM reset, see enable conditions for "HO2S Heater Resistance DTC's") = Not Valid, Green O2S condition is considered valid until the accumulated air flow is greater than **Multiple DTC Use_Green Sensor Delay Criteria - Limit** for the following locations: B1S2, B2S2 (if applicable) in Supporting Tables tab. Airflow accumulation is only enabled when airflow	Frequency: Once per trip Note: if NaPOPD_b_ResetFastRespFunc = FALSE for the given Fuel Bank OR NaPOPD_b_RapidResponseActive = TRUE, multiple tests per trip are allowed.	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					  Low Fuel Condition Only when FuelLevelDataFault Post fuel cell Crankshaft Torque DTC's Passed Number of fueled cylinders =================== After above conditions are met: DFCO mode entered (wo driver initiated pedal input).	is above 18.0 grams/sec. = False = False = Enabled, refer to **Multiple DTC Use - Block learn cells to enable Post oxygen sensor tests** for additional info. < 100.0 Nm P2270 ≤ 3 cylinders ==================		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
O2 Sensor Delayed Response Lean to Rich Bank 1 Sensor 2	P013F	The P013F diagnostic is the fifth in a sequence of six intrusive secondary O2 monitors which include DTCs P2270, P013E, P013A, P2271, P013F, & P013B. This DTC determines if the secondary O2 sensor has an initial delayed response to an A/F change from Lean to Rich and thereby can no longer be used for secondary O2 sensor fuel control or for catalyst monitoring. This diagnostic increases the delivered fuel while monitoring the sensor signal and the accumulated mass air flow. This fault is set if the secondary O2 sensor does not achieve the required voltage before the accumulated mass air flow threshold is reached.	Post O2 sensor voltage AND The Accumulated mass air flow monitored during the Delayed Response Test	< 350 mvolts > 150 grams	No Active DTC's	TPS_ThrottleAuthorityDefaulted ECT_Sensor_FA IAT_SensorFA MAF_SensorFA MAP_SensorFA AIR System FA FuelInjectorCircuit_FA FuelTrimSystemB1_FA FuelTrimSystemB2_FA EngineMisfireDetected_FA Ethanol Composition Sensor FA O2S_Bank_ 1_TFTKO O2S_Bank_ 2_TFTKO	Frequency: Once per trip Note: if NaPOPD_b_ResetFastRespFunc = FALSE for the given Fuel Bank OR NaPOPD_b_RapidResponseActive = TRUE, multiple tests per trip are allowed	Type B, 2 Trips
					B1S2 DTC's Not Active this key cycle	P013A, P013B, P013E, P2270 or P2271		
					System Voltage	> 10.0 Volts		
					Learned heater resistance	= Valid (the heater resistance has learned since NVM reset, see enable conditions for "HO2S Heater Resistance DTC's")		
					Green O2S Condition	= Not Valid, Green O2S condition is considered valid until the accumulated air flow is greater than **Multiple DTC Use_Green Sensor Delay Criteria - Limit** for the following locations: B1S2, B2S2 (if applicable) in Supporting Tables tab. Airflow accumulation is only enabled when airflow		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
						is above 18.0 grams/sec.		
					Green Cat System Condition	= Not Valid, Green Cat System condition is considered valid until accumulated airflow is greater than 360,000 grams. Airflow accumulation is only enabled when estimated Cat temperature is above 600 Deg C and airflow is greater than 18.0 grams/ sec. (Note: This feature is only enabled when the vehicle is new and cannot be enabled in service).		
					Low Fuel Condition	= False		
					Only when FuelLevelDataFault	= False		
					Post fuel cell	= Enabled, refer to **Multiple DTC Use - Block learn cells to enable Post oxygen sensor tests** for additional info.		
					DTC's Passed	P2270 P013E P013A P2271		
					Number of fueled cylinders	≥ 1 cylinders		
					===================	==================		
					After above conditions are met: Fuel Enrich mode entered.			
					=================			
					During this test the			

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					following must stay TRUE or the test will abort: 0.960 ≤ Base Commanded EQR ≤ 1.080			

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
O2S Heater Performance Bank 1 Sensor 2) (For Single Bank Exhaust Only	P0141	This DTC determines if the O2 sensor heater is functioning properly by monitoring the current through the heater circuit. This test compares the measured heater current (monitored thru the low side driver) and compares it to the expected values (over the voltage range provided) for the released sensor. The diagnostic failure counter is incremented if the heater current is outside the expected range. This DTC is set based on the fail and sample counters.	Heater Current outside of the expected range of	0.2 > amps > 2.0	No Active DTC's System Voltage Heater Warm-up delay O2S Heater device control B1S1 O2S Heater Duty Cycle All of the above met for	ECT_Sensor_FA > 10.0 Volts = Complete = Not active > zero > 120 seconds	7 failures out of 9 samples Frequency: 3 tests per trip 10 seconds delay between tests and 1 second execution rate.	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
O2 Sensor Delayed Response Rich to Lean Bank 1 Sensor 1) (For use w/o WRAF	P015A	DTC P015A detects that the primary oxygen sensor for Bank 1 has delayed response when the air fuel ratio transitions from rich to lean condition. This diagnostic runs simultaneously with the intrusive secondary O2 monitor rich to lean tests (P013E / P013A / P2271), which commands fuel cut off. Note: The Primary method is used when the primary O2 sensor signal transitions from above to below the O2 voltage threshold, otherwise the Secondary method is used. Primary method: The P015A diagnostic measures the primary O2 sensor response time between a rich condition above a starting voltage threshold and a lower voltage threshold. The response time is then scaled and normalized to mass air flow rate, engine speed, Baro, and intake air temperature resulting in a normalized delay	Primary Method: The EWMA of the Pre O2 sensor normalized R2L time delay value. The EWMA repass limit is The EWMA calculation uses a 0.25 coefficient. This method calculates the result when the Pre O2 sensor voltage is OR Secondary Method: The Accumulated time monitored during the R2L Delayed Response Test. AND Pre O2 sensor voltage is	> 0.97 EWMA (sec) ≤ 0.87 EWMA (sec) < 450 mvolts ≥ 2.0 Seconds > 100.0 mvolts	No Active DTC's System Voltage EGR Device Control Idle Device Control Fuel Device Control AIR Device Control Low Fuel Condition Only when FuelLevelDataFault Green O2S Condition	TPS_ThrottleAuthorityDefaulted MAP_SensorFA IAT_SensorFA ECT_Sensor_FA AmbientAirDefault MAF_SensorFA EvapPurgeSolenoidCircuit_FA EvapFlowDuringNonPurge_FA EvapVentSolenoidCircuit_FA EvapSmallLeak_FA EvapEmissionSystem_FA FuelTankPressureSnsrCkt_FA FuelInjectorCircuit_FA AIR System FA FuelTrimSystemB1_FA FuelTrimSystemB2_FA EthanolCompositionSensor_FA EngineMisfireDetected_FA P0131, P0132, P013A, P013B, P013E, P013F, P2270, P2271 > 10.0 Volts = Not active = Not active = Not active = Not active = False = False = Not Valid, Green O2S condition is	Frequency: Once per trip Note: if NaESPD_b_FastInitRespIsActive = TRUE for the given Fuel Bank OR NaESPD_b_RapidResponseIsActive = TRUE, multiple tests per trip are allowed	Type A, 1 Trips EWMA

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		value. The normalized delay is fed into a 1st order lag filter to update the final EWMA result. DTC P015A is set when the EWMA value exceeds the EWMA threshold. Note: This EWMA diagnostic employs two features, Fast Initial Response (FIR) and Rapid Step Response (RSR). The FIR feature is used following a code clear event or any event that results in erasure of the engine controller's non-volatile memory. The RSR feature is used when a step change in the test result is identified. Both these temporary features improve the EWMA result following a non-typical event by allowing multiple intrusive tests on a given trip until the total number of tests reach a calibration value. Secondary method: This fault is set if the primary O2 sensor does not achieve the required lower voltage threshold before a delay time threshold is reached.				considered valid until the accumulated air flow is greater than **Multiple DTC Use_Green Sensor Delay Criteria - Limit** for the following locations: B1S1, B2S1 (if applicable) in Supporting Tables tab. Airflow accumulation is only enabled when airflow is above 18.0 grams/sec.		
					O2 Heater (pre sensor) on for	≥ 30 seconds		
					Learned Htr resistance	= Valid (the heater resistance has learned since NVM reset, see enable conditions for "HO2S Heater Resistance DTC's")		
					Engine Coolant (Or OBD Coolant Enable Criteria	> 60 ºC = TRUE)		
					IAT	> -40 ºC		
					Engine run Accum	> 30 seconds		
					Engine Speed to initially enable test	1,150 ≤ RPM ≤ 3,500		
					Engine Speed range to keep test enabled (after initially enabled)	1,000 ≤ RPM ≤ 3,650		
					Engine Airflow	2.0 ≤ gps ≤ 10.5		
					Vehicle Speed to initially enable test	43.5 ≤ MPH ≤ 77.7		
					Vehicle Speed range to keep test enabled (after initially enabled)	40.4 ≤ MPH ≤ 80.8		
					Closed loop integral	0.92 ≤ C/L Int ≤ 1.08		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Closed Loop Active	= TRUE (Please see "**Closed Loop Enable Clarification**" in Supporting Tables).		
					Evap	not in control of purge		
					Ethanol Estimation in Progress	= Not Active (Please see **"Ethanol Estimation in Progress**" in Supporting Tables).		
					Baro Post fuel cell	> 70 kpa = enabled		
					EGR Intrusive diagnostic All post sensor heater delays O2S Heater (post sensor) on Time Predicted Catalyst temp Fuel State	= not active = not active ≥ 60.0 sec 650 ≤ ºC ≤ 900 = DFCO possible		
					=================== All of the above met for at least 2.0 seconds, and then the Force Cat Rich intrusive stage is requested. ===================	================== ==================		
					Pre O2S voltage B1S1 at end of Cat Rich stage Fuel State Number of fueled cylinders	≥ 775 mvolts = DFCO active ≤ 3 cylinders		
					=================== After above conditions are met: DFCO Mode is entered (wo driver	==================		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					initiated pedal input).			

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
O2 Sensor Delayed Response Lean to Rich Bank 1 Sensor 1) (For use w/o WRAF	P015B	DTC P015B detects that the primary oxygen sensor for Bank 1 has delayed response when the air fuel ratio transitions from lean to rich condition. This diagnostic runs simultaneously with the intrusive secondary O2 monitor lean to rich tests (P013F / P013B), which commands fuel enrichment. Note: The Primary method is used when the primary O2 sensor signal transitions from lean condition to above the O2 voltage threshold, otherwise the Secondary method is used. Primary method: The P015B diagnostic measures the primary O2 sensor response time between a lean condition and a higher voltage threshold. The response time is then scaled and normalized to mass air flow rate, engine speed, Baro, and intake air temperature resulting in a normalized delay value. The normalized delay is fed into a 1st	Primary method: The EWMA of the Pre O2 sensor normalized L2R time delay value. The EWMA repass limit is The EWMA calculation uses a 0.25 coefficient. OR Secondary method: The Accumulated time monitored during the L2R Delayed Response Test. AND Pre O2 sensor voltage is OR At end of Cat Rich stage the Pre O2 sensor output is	> 0.96 EWMA (sec) ≤ 0.86 EWMA (sec) ≥ 2.0 Seconds < 450 mvolts < 775 mvolts	No Active DTC's P015A test is complete and System Voltage EGR Device Control Idle Device Control Fuel Device Control AIR Device Control Low Fuel Condition Only when FuelLevelDataFault	TPS_ThrottleAuthorityDefaulted MAP_SensorFA IAT_SensorFA ECT_Sensor_FA AmbientAirDefault MAF_SensorFA EvapPurgeSolenoidCircuit_FA EvapFlowDuringNonPurge_FA EvapVentSolenoidCircuit_FA EvapSmallLeak_FA EvapEmissionSystem_FA FuelTankPressureSnsrCkt_FA FuelInjectorCircuit_FA AIR System FA FuelTrimSystemB1_FA FuelTrimSystemB2_FA EthanolCompositionSensor_FA EngineMisfireDetected_FA P0131, P0132, P013A, P013B, P013E, P013F, P015A, P2270, P2271 = Passed > 10.0 Volts = Not active = Not active = Not active = Not active = False = False	Frequency: Once per trip Note: if NaESPD_b_FastInitRespIsActive = TRUE for the given Fuel Bank OR NaESPD_b_RapidResponseIsActive = TRUE, multiple tests per trip are allowed	Type A, 1 Trips EWMA

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		order lag filter to update the final EWMA result. DTC P015B is set when the EWMA value exceeds the EWMA threshold. Note: This EWMA diagnostic employs two features, Fast Initial Response (FIR) and Rapid Step Response (RSR). The FIR feature is used following a code clear event or any event that results in erasure of the engine controller's non-volatile memory. The RSR feature is used when a step change in the test result is identified. Both these temporary features improve the EWMA result following a non-typical event by allowing multiple intrusive tests on a given trip until the total number of tests reach a calibration value. <u>Secondary method</u>: This fault is set if the primary O2 sensor does not achieve the required higher voltage threshold before a delay time threshold is reached.			Green O2S Condition O2 Heater (pre sensor) on for Learned Htr resistance Engine Coolant (Or OBD Coolant Enable Criteria IAT Engine run Accum Engine Speed to initially enable test Engine Speed range to keep test enabled (after initially enabled) Engine Airflow Vehicle Speed to initially enable test Vehicle Speed range to keep test enabled (after	= Not Valid, Green O2S condition is considered valid until the accumulated air flow is greater than **Multiple DTC Use_Green Sensor Delay Criteria - Limit** for the following locations: B1S1, B2S1 (if applicable) in Supporting Tables tab. Airflow accumulation is only enabled when airflow is above 18.0 grams/sec. ≥ 30 seconds = Valid (the heater resistance has learned since NVM reset, see enable conditions for "HO2S Heater Resistance DTC's") > 60 ºC = TRUE) > -40 ºC > 30 seconds 1,150 ≤ RPM ≤ 3,500 1,000 ≤ RPM ≤ 3,650 2.0 ≤ gps ≤ 10.5 43.5 ≤ MPH ≤ 77.7		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					initially enabled)	40.4 ≤ MPH ≤ 80.8		
					Closed loop integral Closed Loop Active	0.92 ≤ C/L Int ≤ 1.08 = TRUE (Please see "**Closed Loop Enable Clarification**" in Supporting Tables).		
					Evap	not in control of purge		
					Ethanol Estimation in Progress	= Not Active (Please see "**Ethanol Estimation in Progress**" in Supporting Tables).		
					Baro Post fuel cell EGR Intrusive diagnostic All post sensor heater delays O2S Heater (post sensor) on Time	> 70 kpa = enabled = not active = not active ≥ 60.0 sec		
					Predicted Catalyst temp Fuel State Number of fueled cylinders	650 ≤ ºC ≤ 900 = DFCO inhibit ≥ 1 cylinders		
					================ When above conditions are met: Fuel Enrich mode is entered.	==================		
					================	==================		
					During this test: Engine Airflow must stay between: and the delta Engine Airflow over 12.5msec	2 ≤ gps ≤ 20		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					must be :	≤ 3.0 gps		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel System Too Lean Bank 1	P0171	Determines if the primary fuel control system for Bank 1 is in a lean condition, based on the filtered long-term and short-term fuel trim. A normally operating system operates centered around long-term fuel trim metric of 1.0. For lean conditions extra fuel trim is required therefor values > 1.0 indicate a Lean condition. A fault is determined, when the long term fuel metric exceeds the threshold value. In addition to the long-term fuel trim limit, the short-term fuel trim metric can be monitored and the fault sets once both threshold values are exceeded. The short-term fuel trim metric is only monitored on programs that have acceptable emissions when the long-term fuel metric reaches its full authority.	The filtered long-term fuel trim metric AND The filtered short-term fuel trim metric (Note: any value below 0.95 effectively nullifies the short-term fuel trim criteria)	>= 1.320 >= 0.100 If a fault has been detected the long-term fuel trim metric must be < 1.320 and the short-term fuel trim metric must be < 2.000 to repass the diagnostic.	The primary fuel trim diagnostic is enabled Engine speed BARO Coolant Temp Coolant Temp MAP Inlet Air Temp MAF Fuel Level Long Term Fuel Trim data accumulation: Sometimes, certain Long-Term Fuel Trim Cells are not utilized for control and/or diagnosis Closed Loop Long Term FT	 400 <rpm< 6,100 > 70 kPa > -20 °C (or OBD Coolant Enable Criteria = TRUE) < 130 °C 15 <kPa< 255 -20 <°C< 150 1 <g/s< 1,000 > 10 % or if fuel sender is faulty the diagnostic will bypass the fuel level criteria. > 35.0 seconds of data must accumulate on each trip, with at least 15.0 seconds of data in the current fuel trim cell before a pass or fail decision can be made. (Please see **P0171_P0172_P0174_P0175 Long-Term Fuel Trim Cell Usage** in Supporting Tables for a list of cells utilized for diagnosis) Enabled Enabled (Please see "**Closed Loop Enable Clarification**" and "**Long**	Frequency: 100 ms Continuous Loop	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
						Term FT Enable Criteria" in Supporting Tables.)		
					EGR Diag. Catalyst Diag. Post O2 Diag. Device Control EVAP Diag.	Intrusive Test Not Active Intrusive Test Not Active Intrusive Test Not Active Not Active Large Leak Diagnostic (P0455) Not Active		
					No active DTC:	IAC_SystemRPM_FA MAP_SensorFA MAF_SensorFA MAF_SensorTFTKO AIR System FA EvapExcessPurgePsbl_FA Ethanol Composition Sensor FA FuelInjectorCircuit_FA EngineMisfireDetected_FA EGRValvePerformance_FA EGRValveCircuit_FA MAP_EngineVacuumStatus AmbPresDfltdStatus TC_BoostPresSnsrFA O2S_Bank_1_Sensor_1_FA		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel System Too Rich Bank 1	P0172	Determines if the fuel control system is in a rich condition, based on the filtered long-term fuel trim metric.A normally operating system operates centered around long-term fuel trim metric of 1.0. For rich conditions less fuel trim is required therefor values < 1.0 indicate a rich condition. There are two methods to determine a Rich fault. They are Passive and Intrusive. A Passive Test decision can be made up until the time that purge is first enabled. From that point forward, rich faults can only be detected by turning purge off intrusively. If during this period of time the filtered long-term fuel trim metric exceeds the threshold a fault will be set. In addition to the long-term fuel trim limit, the short-term fuel trim metric can be monitored and the fault sets once both threshold values are exceeded. The short-	**Passive Test:** The filtered Non-Purge Long Term Fuel Trim metric AND The filtered Short Term Fuel Trim metric (Note: any value above 1.05 effectively nullifies the short-term fuel trim criteria) ****************************** **Intrusive Test:** For 2 out of 3 intrusive segments The filtered Purge Long Term Fuel Trim metric AND The filtered Non-Purge Long Term Fuel Trim metric AND The filtered Short Term Fuel Trim metric (Note: any value above 1.05 effectively nullifies the short-term fuel trim criteria)	<= 0.720 <= 2.000 *************************** <= 0.725 <= 0.720 <= 2.000 If a fault has been detected (by the passive or intrusive test) the long-term fuel trim metric must be > 0.790 and the short-	****************************** Purge Vapor Fuel	Secondary Parameters and Enable Conditions are identical to those for P0171, with the exception that fuel level is not considered. ****************************** <= 100.00 % Intrusive Test is inhibited when Purge Vapor percentage is greater than this threshold. (Note: values greater than 50% indicate the Purge Vapor Fuel requirement is not being used) A minimum number of accumlated Fuel Trim Data samples are required to adequately learn a correct Purge Vapor Fuel value. See the table **Minimum Non-Purge Samples for Purge** (**Vapor Fuel**) for the Purge Off cells used to validate the Purge Vapor Fuel parameter.	Frequency: 100 ms Continuous Loop ******************* **Segment Definition:** Segments can last up to 35 seconds and are separated by the lesser of 30.0 seconds of purge-on time or enough time to purge 45 grams of vapor. A maximum of 3 completed segments or 25 attempts are allowed for each intrusive test. After an intrusive test report is completed, another intrusive test cannot occur for 300 seconds to allow sufficient	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		term fuel trim metric is only monitored on programs that have acceptable emissions when the long-term fuel metric reaches its full authority. Once purge is enabled if the filtered Purge Long Term Fuel Trim metric > 0.725 , the test passes without intrusively checking the filtered Non-Purge Long Term Fuel Trim metric. However if the filtered Purge Long Term Fuel Trim metric is <= 0.725 , the Intrusive test is invoked. The purge is ramped off to determine if excess purge vapor is the cause of the rich condition. If during 2 out of 3 intrusive segments, the filtered Purge Long Term Fuel Trim metric <= 0.720 the fault will set. Performing intrusive tests too frequently may also affect EVAP and EPAIII emissions, and the execution frequency of other diagnostics. This is why the intrusive test is operated over several		term fuel trim metric must be > 0.000 to repass the diagnostic. The intrusive test will be enabled at long-term fuel metric values < 0.73 until the diagnostic repasses after a failure.		If the accumulated purge volume is > 0.0 grams, the intrusive test will not be inhibited even if Purge Vapor Fuel is > 100.0 %.	time to purge excess vapors from the canister. During this period, fuel trim will pass if the filtered Purge Long Term Fuel Trim metric > 0.725 for at least 150.0 seconds, indicating that the canister has been purged.	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		segments allowing Purge to renable between segments. Likewise, for these reasons, if after the 3 intrusive segments the diagnostic continues to pass, there is a delay period of 300 seconds to allow sufficient time to purge excess vapors from the canister, before re-evaluating a Rich condition if it still exists.						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Coolant Temperature Dropped Below Diagnostic Monitoring Temperature	P01F0	This DTC detects an unexplained cooling system cool down below the OBD monitoring threshold during normal operating conditions. This check is run throughout the key cycle.	For this application the "type" cal (KeTHMG_b_TMS_ElecThstEquipped) = 0 If the type cal is equal to one, the application has an electrically heated t-stat, if equal to zero the the application has an non heated t-stat. See appropiate section below. ***************************** Type cal above = 0 (non - heated t-stat) == == == ==		No Active DTC's	ECT_Sensor_Ckt_FA VehicleSpeedSensor_FA OAT_PtEstFiltFA THMR_AWP_AuxPumpFA THMR_AHV_FA THMR_SWP_Control_FA EngineTorqueEstInaccurate ECT_Sensor_Perf_FA THMR_SWP_NoFlow_FA THMR_SWP_FlowStuckOn_FA	48 seconds out of a 60 seconds window Continuous	Type B, 2 Trips
					Engine Runtime	≥ 30.0 seconds		
					Distance traveled this key cycle	≥ 1.5 km		
			Engine coolant temperature	≤ 70.0 Deg C	Ambient air pressure	≥ 55.0 kPa		
					Ambient air temperature	≥ -9.0 Deg C		
			***************************** Type cal above = 1 (Electrically heated t-stat) == == == ==		************************** Engine coolant temperature			
			Engine coolant temperature	≤ 63.0 Deg C	At least once during the key cycle			
					Type 0 (non-heated t-stat)	≥ 71 Deg C		
					Type 1 (Electrically heated T-stat)	≥ 71.0 to 81.0 Deg C		
					************************** Heat to coolant	**Cool Down Diagnostic** ≥ **Min Heat to Coolant**		
					DFCO time	≤ 3.0 seconds		
					Thermostat duty cycle	≤ 100.0 %		
					RPM	≤ 8,192		
					Active Fuel Management is not in	Half Cylinder Mode		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector 1 Open Circuit - (PFI)	P0201	Controller specific output driver circuit diagnoses Injector 1 low sided driver for an open circuit failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver off state indicates open circuit failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for an open circuit.	>= 200 KOhms impedance between signal and controller ground	Powertrain Relay Voltage within range for a duration Engine Running	>= 11.00 Volts >= 5 Seconds >= 0 Seconds	50.00 failures out of 63.00 samples 100 ms /sample Continuous	Type A, 1 Trips Note: In certain controllers P0261 may also set (Injector 1 Short to Ground)

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector 2 Open Circuit - (PFI)	P0202	Controller specific output driver circuit diagnoses Injector 2 low sided driver for an open circuit failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver off state indicates open circuit failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for an open circuit.	>= 200 KOhms impedance between signal and controller ground	Powertrain Relay Voltage within range for a duration Engine Running	>= 11.00 Volts >= 5 Seconds >= 0 Seconds	50.00 failures out of 63.00 samples 100 ms /sample Continuous	Type A, 1 Trips Note: In certain controllers P0264 may also set (Injector 2 Short to Ground)

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector 3 Open Circuit - (PFI)	P0203	Controller specific output driver circuit diagnoses Injector 3 low sided driver for an open circuit failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver off state indicates open circuit failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for an open circuit.	>= 200 KOhms impedance between signal and controller ground	Powertrain Relay Voltage within range for a duration Engine Running	>= 11.00 Volts >= 5 Seconds >= 0 Seconds	50.00 failures out of 63.00 samples 100 ms /sample Continuous	Type A, 1 Trips Note: In certain controllers P0267 may also set (Injector 3 Short to Ground)

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector 4 Open Circuit - (PFI)	P0204	Controller specific output driver circuit diagnoses Injector 4 low sided driver for an open circuit failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver off state indicates open circuit failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for an open circuit.	>= 200 KOhms impedance between signal and controller ground	Powertrain Relay Voltage within range for a duration Engine Running	>= 11.00 Volts >= 5 Seconds >= 0 Seconds	50.00 failures out of 63.00 samples 100 ms /sample Continuous	Type A, 1 Trips Note: In certain controllers P0270 may also set (Injector 4 Short to Ground)

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
TPS2 Circuit Low	P0222	Detects a continuous or intermittent short low or open in TPS2 circuit by monitoring the TPS 2 sensor percent Vref and failing the diagnostic when the TPS percent Vref is too low. This diagnostic only runs when battery voltage is high enough.	TPS2 % Vref <	0.250 % Vref	Run/Crank voltage No 5V reference error or fault for # 4 5V reference circuit	> 6.41 Volts P06A3	79 / 159 counts; 57 counts continuous; 3.125 ms /count in the ECM main processor	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
TPS2 Circuit High	P0223	Detects a continuous or intermittent short high in TPS2 circuit by monitoring the TPS 2 sensor percent Vref and failing the diagnostic when the TPS percent Vref is too high. This diagnostic only runs when battery voltage is high enough.	TPS2 % Vref >	4.590 % Vref	Run/Crank voltage No 5V reference error or fault for # 4 5V reference circuit	> 6.41 Volts P06A3	79 / 159 counts; 57 counts continuous; 3.125 ms /count in the ECM main processor	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector 1 Low side circuit shorted to ground (PFI)	P0261	Controller specific output driver circuit diagnoses Injector 1 low sided driver for a short to ground failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver off state indicates short to ground failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to ground.	<= 0.5 Ohms impedance between signal and controller ground	Powertrain Relay Voltage within range for a duration Engine Running	>= 11.00 Volts >= 5 Seconds >= 0 Seconds	50.00 failures out of 63.00 samples 100 ms /sample Continuous	Type A, 1 Trips Note: In certain controllers P0201 may also set (Injector 1 Open Circuit)

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector 1 Low side circuit shorted to power (PFI)	P0262	Controller specific output driver circuit diagnoses Injector 1 low sided driver for a short to power failure when the output is powered on by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to power failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to power.	 <= 0.5 Ohms impedance between signal and controller power	Powertrain Relay Voltage within range for a duration Engine Running	>= 11.00 Volts >= 5 Seconds >= 0 Seconds	50.00 failures out of 63.00 samples 100 ms /sample Continuous	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector 2 Low side circuit shorted to ground (PFI)	P0264	Controller specific output driver circuit diagnoses Injector 2 low sided driver for a short to ground failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver off state indicates short to ground failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to ground.	 <= 0.5 Ohms impedance between signal and controller ground	Powertrain Relay Voltage within range for a duration Engine Running	>= 11.00 Volts >= 5 Seconds >= 0 Seconds	50.00 failures out of 63.00 samples 100 ms /sample Continuous	Type A, 1 Trips Note: In certain controllers P0202 may also set (Injector 2 Open Circuit)

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector 2 Low side circuit shorted to power (PFI)	P0265	Controller specific output driver circuit diagnoses Injector 2 low sided driver for a short to power failure when the output is powered on by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to power failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to power.	<= 0.5 Ohms impedance between signal and controller power	Powertrain Relay Voltage within range for a duration Engine Running	>= 11.00 Volts >= 5 Seconds >= 0 Seconds	50.00 failures out of 63.00 samples 100 ms /sample Continuous	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector 3 Low side circuit shorted to ground (PFI)	P0267	Controller specific output driver circuit diagnoses Injector 3 low sided driver for a short to ground failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver off state indicates short to ground failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to ground.	<= 0.5 Ohms impedance between signal and controller ground	Powertrain Relay Voltage within range for a duration Engine Running	>= 11.00 Volts >= 5 Seconds >= 0 Seconds	50.00 failures out of 63.00 samples 100 ms /sample Continuous	Type A, 1 Trips Note: In certain controllers P0203 may also set (Injector 3 Open Circuit)

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector 3 Low side circuit shorted to power (PFI)	P0268	Controller specific output driver circuit diagnoses Injector 3 low sided driver for a short to power failure when the output is powered on by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to power failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to power.	 <= 0.5 Ohms impedance between signal and controller power	Powertrain Relay Voltage within range for a duration Engine Running	>= 11.00 Volts >= 5 Seconds >= 0 Seconds	50.00 failures out of 63.00 samples 100 ms /sample Continuous	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector 4 Low side circuit shorted to ground (PFI)	P0270	Controller specific output driver circuit diagnoses Injector 4 low sided driver for a short to ground failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver off state indicates short to ground failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to ground.	 <= 0.5 Ohms impedance between signal and controller ground	Powertrain Relay Voltage within range for a duration Engine Running	>= 11.00 Volts >= 5 Seconds >= 0 Seconds	50.00 failures out of 63.00 samples 100 ms /sample Continuous	Type A, 1 Trips Note: In certain controllers P0204 may also set (Injector 4 Open Circuit)

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector 4 Low side circuit shorted to power (PFI)	P0271	Controller specific output driver circuit diagnoses Injector 4 low sided driver for a short to power failure when the output is powered on by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to power failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to power.	<= 0.5 Ohms impedance between signal and controller power	Powertrain Relay Voltage within range for a duration Engine Running	>= 11.00 Volts >= 5 Seconds >= 0 Seconds	50.00 failures out of 63.00 samples 100 ms /sample Continuous	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Random Misfire Detected Cylinder 1 Misfire Detected Cylinder 2 Misfire Detected Cylinder 3 Misfire Detected Cylinder 4 Misfire Detected	P0300 P0301 P0302 P0303 P0304	These DTC's will determine if a random or a cylinder specific misfire is occurring by monitoring various terms derived from crankshaft velocity. The rate of misfire over an interval is compared to both emissions and catalyst damaging thresholds. The pattern of crankshaft acceleration after the misfire is checked to differentiate between real misfire and other sources of crank shaft noise. Emissions Neutral Default Action: If consumed Emissions Neutral Default DTCs from other subsystems are set: Ignore Rough Road, Traction, Stability, and Antilock brake signals. If default action not activated, Misfire Monitor could complete less frequently or inaccurately. Default Action Latched for duration of Trip Default Action: If Misfire P030x sets on some hybrid applications, the isolation damper	Crankshaft Deceleration Value(s) vs. Engine Speed and Engine load The equation used to calculate deceleration value is tailored to specific vehicle operating conditions. The selection of the equation used is based on the 1st single cylinder continuous misfire threshold tables encountered that are not max of range. If all tables are max of range at a given speed/load, that speed load region is an ***Undetectable region*** see Algorithm Description Document for additional details. SINGLE CYLINDER CONTINUOUS MISFIRE((Medres_Decel Medres_Jerk OR (Medres_Decel Medres_Jerk OR (Lores_Decel Lores_Jerk OR (Lores_Decel Lores_Jerk OR RevBalanceTime)	- see details of thresholds on Supporting Tables Tab > **RufSCD_Decel** AND > **RufSCD_Jerk)** > **SCD_Decel** AND > **SCD_Jerk)** > **RufCyl_Decel** AND > **RufCyl_Jerk)** > **CylModeDecel** AND > **CylModeJerk)** >**RevMode_Decel**	Engine Run Time Engine Coolant Temp Or If ECT at startup Then System Voltage + Throttle delta - Throttle delta Early Termination option: (used on plug ins that may not have enough engine run time at end of trip for normal interval to complete.)	> 2 crankshaft revolution "ECT" If OBD Max Coolant Achieved = FALSE -9 °C < ECT Or if OBD Max Coolant Achieved = TRUE -9 °C < ECT < 126 °C < -9 °C If OBD Max Coolant Achieved = FALSE 21 °C < ECT If OBD Max Coolant Achieved = TRUE 21 °C < ECT < 126 °C 9.00 < volts < 32.00 < 100.00 % per 25 ms < 100.00 % per 25 ms Not Enabled	Emission Exceedence = any (5) failed 200 rev blocks out of (16) 200 rev block tests Failure reported for (1) Exceedence in 1st (16) 200 rev block tests, or (4) Exceedences thereafter. OR when Early Termination Reporting = Enabled and engine rev > 1,000 revs and < 3,200 revs at end of trip	Type B, 2 Trips (Mil Flashes with Catalyst damage level of Misfire)

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		between engine and transmission can go into extreme resonance. Default action is to move rpm out of the resonance zone. If default action not activated, significant hardware damage could occur rendering vehicle inoperable.	****************************** **This Feature not used on Gasoline engines** Combustion Modes that force selection of Idle Tables ****************************** Other patterns of misfire use adjustments to the single cylinder continuous misfire threshold tables: RANDOM MISFIRE Use random misfire thresholds If no misfire for (Medres_Decel AND Medres_Jerk) OR (Medres_Decel AND Medres_Jerk) OR (Lores_Decel AND Lores_Jerk)	************************** **This Feature not used on Gasoline engines** **CombustModeIdleTbl** in Supporting Tables ************************** > 6 Engine Cycles > **RufSCD_Decel** * **Random_SCD_Decel** >**RufSCD_Jerk** * **Random_SCD_Jerk** > **SCD_Decel** * **Random_SCD_Decel** > **SCD_Jerk** * **Random_SCD_Jerk** > **RufCyl_Decel** * **RandomCylModDecel** > **RufCyl_Jerk** * **RandomCylModJerk**			any Catalyst Exceedence = (1) 200 rev block as data supports for catalyst damage. Catalyst Failure reported with (1 or 3) Exceedences in FTP, or (1) Exceedence outside FTP. Continuous	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			OR (Lores_Decel AND Lores_Jerk) OR RevBalanceTime PAIRED CYLINDER MISFIRE If a cylinder & it's pair are above PAIR thresholds (Medres_Decel AND Medres_Jerk) OR (Medres_Decel AND Medres_Jerk) OR (Lores_Decel AND Lores_Jerk) OR (Lores_Decel AND Lores_Jerk)	> **CylModeDecel * RandomCylModDecel** > **CylModeJerk * RandomCylModJerk** > **RevMode_Decel * RandomRevModDecl** > **RufSCD_Decel * Pair_SCD_Decel** > **RufSCD_Jerk * Pair_SCD_Jerk** > **SCD_Decel * Pair_SCD_Decel** > **SCD_Jerk * Pair_SCD_Jerk** > **RufCyl_Decel * PairCylModeDecel** > **RufCyl_Jerk * PairCylModeJerk** > **CylModeDecel * PairCylModeDecel** > **CylModeJerk * PairCylModeJerk**				

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			OR (Revmode Active AND (within one engine cycle: 2nd largest Lores_Decel)	> **CylModeDecel * PairCylModeDecel**				
			AND Above TRUE for))	> 80 engine cycles out of 100 engine cycles				
			BANK MISFIRE Cylinders above Bank Thresholds	>= 4 cylinders				
			(Medres_Decel	> **RufSCD_Decel * Bank_SCD_Decel**				
			AND Medres_Jerk)	> **RufSCD_Jerk * Bank_SCD_Jerk**				
			OR (Medres_Decel	> **SCD_Decel * Bank_SCD_Decel**				
			AND Medres_Jerk)	> **SCD_Jerk * Bank_SCD_Jerk**				
			OR (Lores_Decel	> **RufCyl_Decel * BankCylModeDecel**				
			AND Lores_Jerk)	> **RufCyl_Jerk * BankCylModeJerk**				
			OR (Lores_Decel	> **CylModeDecel * BankCylModeDecel**				
			AND Lores_Jerk)	> **CylModeJerk * BankCylModeJerk**				

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			CONSECUTIVE CYLINDER MISFIRE 1st cylinder uses single cyl continuous misfire thresholds; 2nd Cylinder uses: (Medres_Decel AND Medres_Jerk)	> **RufSCD_Decel * ConsecSCD_Decel** > **RufSCD_Jerk * ConsecSCD_Jerk**				
			OR (Medres_Decel AND Medres_Jerk)	> **SCD_Decel * ConsecSCD_Decel** > **SCD_Jerk * ConsecSCD_Jerk**				
			OR (Lores_Decel AND Lores_Jerk)	> **RufCyl_Decel * ConsecCylModDecel** > **RufCyl_Jerk * ConsecCylModeJerk**				
			OR (Lores_Decel AND Lores_Jerk)	> **CylModeDecel * ConsecCylModDecel** > **CylModeJerk * ConsecCylModeJerk**				
			CYLINDER DEACTIVATION MODE (Active Fuel Managment)					

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			AFM: SINGLE CYLINDER CONTINUOUS MISFIRE (CylAfterDeacCyl_Decel AND CylAfterDeacCyl_Jerk) OR (CylBeforeDeacCylDecel AND CylBeforeDeacCyl_Jerk) AFM: RANDOM MISFIRE Use random misfire thresholds If no misfire for (CylAfterDeacCyl_Decel AND CylAfterDeacCyl_Jerk) (CylBeforeDeacCylDecel AND CylBeforeDeacCyl_Jerk)	> **CylModeDecel * ClyAfterAFM_Decel** > **CylModeJerk * CylAfterAFM_Jerk** > **CylModeDecel * CylBeforeAFM_Decel** > **CylModeJerk * ClyBeforeAFM_Jerk** > 6 Engine Cycles > **CylModeDecel * ClyAfterAFM_Decel * RandomAFM_Decl** > **CylModeJerk * CylAfterAFM_Jerk * RandomAFM_Jerk** > **CylModeDecel * CylBeforeAFM_Decel * RandomAFM_Decl** > **CylModeJerk * ClyBeforeAFM_Jerk * RandomAFM_Jerk** - see details on Supporting Tables Tab				

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Misfire Percent Emission Failure Threshold	≥ 2.13 % P0300				
			Misfire Percent Catalyst Damage	> **Catalyst_Damage_Misfire_Percentage** in Supporting Tables whenever secondary conditions are met.				
			When engine speed and load are less than the FTP cals (3) catalyst damage exceedences are allowed.	≤ 0 FTP rpm AND ≤ 0 FTP % load	(at low speed/loads, one cylinder may not cause cat damage) Engine Speed Engine Load Misfire counts	 > 1,250 rpm AND > 30 % load AND < 180 counts on one cylinder		
					Engine Speed	500 < rpm < ((Engine Over Speed Limit) - 400) OR 8,191) Engine speed limit is a function of inputs like Gear and temperature	4 cycle delay	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
						see **EngineOverSpeedLimit** in supporting tables		
					No active DTCs:	TPS_FA EnginePowerLimited MAF_SensorTFTKO MAP_SensorTFTKO IAT_SensorTFTKO ECT_Sensor_Ckt_TFTKO 5VoltReferenceB_FA CrankSensor_TFTKO CrankSensor_FA CamLctnIntFA CamLctnExhFA CamSensorAnyLctnTFTKO AnyCamPhaser_FA AnyCamPhaser_TFTKO AmbPresDfltdStatus	4 cycle delay	
					P0315 & engine speed	> 1,000 rpm	4 cycle delay	
					Fuel Level Low	LowFuelConditionDiagnostic	500 cycle delay	
					Cam and Crank Sensors	in sync with each other	4 cycle delay	
					Misfire requests TCC unlock	Not honored because Transmission in hot mode or POPD intrusive diagnostic running	4 cycle delay	
					Fuel System Status	≠ Fuel Cut	4 cycle delay	
					Active FuelManagement	Transition in progress	0 cycle delay	
					Undetectable engine	***Undetectable region***	4 cycle delay	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					speed and engine load region	from Malfunction Criteria		
					Abusive Engine Over Speed	> 7,000 rpm	0 cycle delay	
					Below zero torque (except CARB approved 3000 rpm to redline triangle.)	< **ZeroTorqueEngLoad** or <**ZeroTorqueAFM** if AFM is active in Supporting Tables	4 cycle delay	
					Below zero torque: TPS Vehicle Speed	≤ 2.0 % (≤ 2.0 % in AFM) > 318 mph (> 19 mph AFM)	4 cycle delay	
					NEGATIVE TORQ AFM If deactivated cylinders appear to make power, torque is negative: DeactivatedCyl_Decel AND DeactivatedCyl_Jerk AND # of Deact Cyls Inverted	<**DeacCylInversionDecel** <**DeacCylInversionJerk** > 4 cylinders	0 cycle delay	
					EGR Intrusive test	if Active	0 cycle delay	
					Manual Trans	Clutch shift	0 cycle delay	
					Accel Pedal Position AND Automatic transmission shift	> 100.00 %	7 cycle delay	
					After Fuel resumes on Automatic shift containing Fuel Cut		2 Cylinder delay	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Delay if PTO engaged	Enabled	4 cycle delay	
					******************************	******************************	*******************	
					This Feature not used on Gasoline engines			
					Combustion Mode	= **InfrequentRegen** value in Supporting Tables	0 cycle delay	
					Driver cranks before Wait to Start lamp extinguishes	IF TRUE	**WaitToStart** cycle delay	
					Brake Torque	> 199.99 % Max Torque	0 cycle delay	
					******************************	******************************	*******************	
					DRIVELINE RING FILTER After a low level misfire, another misfire may not be detectable until driveline ringing ceases. If no ringing seen, stop filter early.			
					Filter Driveline ring:	> "**Ring Filter**" # of engine cycles after misfire in Supporting Tables		
					Stop filter early:	> "**Number of Normals**" # of engine cycles after misfire in Supporting Tables tab		
					ABNORMAL ENGINE SPEED OSCILLATION: (checks each "misfire" candidate in 100 engine			

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Cycle test to see if it looks like some disturbance like rough road (abnormal).) Used Off Idle, and while not shifting, TPS Engine Speed Veh Speed Auto Transmission indivdual candidate deemed abnormal if number of consecutive decelerating cylinders after "misfire": (Number of decels can vary with misfire detection equation) Consecutive decels while in SCD Mode Cyl Mode Rev Mode At the end of 100 engine cycle test, the ratio of abnormal/candidate is checked to confirm if real misfire is present within the 100 engine cycles. abnormal candidates/ total candidates MISFIRE CRANKSHAFT	> 1 % > 1,000 rpm > 3 mph not shifting > **Abnormal SCD Mode** > **Abnormal Cyl Mode** > **Abnormal Rev Mode** in Supporting Tables > 0.50 ratio	discard 100 engine cycle test	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					PATTERN RECOGNITION checks each "misfire" candidate in 100 engine Cycle test to see if overall crankshaft pattern looks like real misfire (recognized), or some disturbance like rough road (unrecognized). At the end of 100 engine cycle test, the ratio of unrecog/recognized is checked to confirm if real misfire is present within the 100 engine cycles. Typically used for checking a single misfire per engine cycle but can support some other patterns on some packages			
					Pattern Recog Enabled:	Enabled		
					Pattern Recog Enabled during Cylinder Deac	Not Enabled		
					Pattern Recog Enabled consecutive cyl pattrn	Disabled		
					Engine Speed	500 < rpm < 6,000		
					Veh Speed	> 3.1 mph		
					The 1st check for "recognized" is the 1st fired cylinder after the misfire candidate should both accelerate and jerk an amount based acceleration and jerk of Single Cylinder Misfire			

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					thresholds in effect at that speed and load. (CylAfter_Accel AND CylAfter_Jerk)	> Misfire_ decel * **1st_FireAftrMisfr_Acel** > Misfire_Jerk * **1st_FireAftrMisfr_Jerk** Or if AFM mode is active: > Misfire_ decel * **1stFireAftrMisAcelAFM** > Misfire_Jerk * **1stFireAfterMisJerkAFM**		
					Addtionally, the crankhaft is checked again a small calibratible number of cylinders later to see if the distrubance is still large like rough road, or has calmed down like real misfire. The size of disturbance is compared to a multiplier times the ddt_jerk value used to detect misfire at that speed and load. If there is repetitive misfire on consecutive engine cycles, the expected snap is adjusted due to the higher expected disturbance.			
					Num of Cylinders after misfire to start check of crankshaft snap	2 Cylinders		
					"misfire" recognized if: Crankshaft snap after: isolated "misfire"	< Misfire_Jerk * **SnapDecayAfterMisfire**		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					repetative "misfire"	< Misfire_Jerk * **SnapDecayAfterMisfire** * **RepetSnapDecayAdjst** in Supporting Tables		
					At the end of 100 engine cycle test, the ratio of unrecog/recognized is checked to confirm if real misfire is present.			
					Ratio of Unrecog/Recog	> 1.00	discard 100 engine cycle test	
					******************************	******************************	*******************	
					NON-CRANKSHAFT BASED ROUGH ROAD:	Disabled		
					Rough Road Source	TOSS		
					******************************	******************************	*******************	
					IF Rough Road Source = WheelSpeedInECM ABS/TCS Wheel speed noise VSES AND No Emission Neutral Default Action DTCs	active > **WSSRoughRoadThres** active ABS Failed Vehicle Dynamics Control System Status Driven Wheel Rotation Status Non Driven Wheel Rotation Status	discard 100 engine cycle test	
					******************************	******************************	*******************	
					IF Rough Road Source = "FromABS" ABS/TCS		discard 100	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					RoughRoad	active	engine cycle test	
					VSES	detected active		
					AND No Emission Neutral Default Action DTCs	ABS Failed Vehicle Dynamics Control System Status		
					******************************	******************************	*******************	
					IF Rough Road Source = "TOSS" TOSS dispersion	>**TOSSRoughRoadThres** in supporting tables	discard 100 engine cycle test	
					AND No Active DTCs	Transmission Output Shaft Angular Velocity Validity TransmissionEngagedState_FA (Auto Trans only) ClutchPstnSnsr FA (Manual Trans only)	4 cycle delay	
					******************************		*******************	
					Default Action	******************************		
					Isolator Resonance Default Action Option			
					******************************	Not Enabled	*******************	
					If Isolator Resonance Option Enabled AND Misfire P030x TFTKO	****************************** Set engine speed limits: 0 < Eng RPM < 9,000		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Crankshaft Position System Variation Not Learned	P0315	This DTC determines if the crankshaft sensor learn values that are stored in memory are valid. The angle between each tooth of the reluctor wheel is learned, and the sum of all angles together should sum to 360° (one revolution of the reluctor wheel). Default values, or corrupted values will not sum to 360°.	The Crankshaft target wheel should be 360 degrees around in circumferance. Loss or controller non-volitile memory or an error in memory will cause the values of individual teeth learn to be defaulted or incorrect. Set the DTC if the Differance between the sum of the reluctor wheel's teeth and 360 degrees is greater than:	> 0.001 degrees	OBD Manufacturer Enable Counter	MEC = 0	0.50 seconds Frequency Continuous100 msec	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Knock Sensor (KS) Performance Per Cylinder	P0324	This diagnostic checks for knock sensor performance out of the normal expected range on a per cylinder basis due to Excessive Knock (either real or false knock). In the knock detection algorithm, the term "Knock Intensity" (KI) is used to define the relative size of a knock event, and is calculated as (KI = current knock event - knock threshold). This results in a KI amplitude that is proportional to the size of the knock event (as seen by the knock sensor). In addition, Knock Intensity cannot be less than zero as it is forced/limited to be = 0 with no knock detected (i.e. whenever the current knock event < knock threshold, KI = 0). This diagnostic calculates a first-order lag filter version of the Knock Intensity and sets a fault when: (Filtered KI) > (Excessive Knock Diagnostic Threshold)	Filtered Knock Intensity (where 'Knock Intensity' = 0 with no knock; and > 0 & proportional to knock magnitude with knock)	**> P0324_PerCyl_ExcessiveKnock_Threshold** (no units)	Diagnostic Enabled? Engine Run Time Engine Speed Engine Air Flow Engine Coolant Temperature or OBD Coolant Enable Criteria Inlet Air Temperature Cumlative Number of Engine Revs Above Min Eng Speed (per key cycle)	Yes ≥ 2.0 seconds ≥ 580 RPM AND ≤ 8,500 RPM ≥ 50 mg/cylinder AND ≤ 2,000 mg/cylinder ≥ -40 deg's C = TRUE ≥ -40 deg's C ≥ 100 revs	First Order Lag Filters with Weight Coefficient = 0.0200 Updated each engine event	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Knock Sensor (KS) Circuit Bank 1	P0325	This diagnostic checks for an open in the knock sensor circuit Sensor 1/Bank 1. There are two possible methods used: 1. **20 kHz Method**: This method injects a 20 kHz signal (internal to the ECU) onto one of the Knock Sensor inputs. For a normal/ good circuit the 20 kHz signal will propogate through the Knock sensor and back to the ECU through the sensor return circuit. The 20 kHz signal is processed through the Fast Fourier Transform (FFT) and then filtered with a first-order lag filter. Since the Knock Detection algorithm uses a Differential Op-Amp to compare the input from the two knock sensor wires, the FFT 20 kHz diagnostic signal will have either: A. Low output with a good circuit (because the 20 kHz injected signal is detected on both of the sensor inputs) or B, High output for an Open Circuit (because	Open Circuit Method chosen (2 possible methods: 20 kHz or Normal Noise): Filtered FFT Output Filtered FFT Output	= **P0325_P0330_OpenMethod_2** **<u>Case 1 (20 kHz Method):</u>** **> P0325_P0330_OpenCktThrshMin (20 kHz) AND < P0325_P0330_OpenCktThrshMax (20 kHz)** **<u>Case 2 (Normal Noise Method):</u>** **> P0325_P0330_OpenCktThrshMin (Normal Noise) AND < P0325_P0330_OpenCktThrshMax (Normal Noise)**	Diagnostic Enabled? Engine Run Time Engine Speed Cumulative Number of Engine Revs (per key cycle) within min/max Engine Speed enable (above) Engine Air Flow Engine Coolant Temperature or OBD Coolant Enable Criteria Inlet Air Temperature	Yes ≥ 2.0 seconds ≥ 580 RPM and ≤ 6,800 RPM ≥ 50 revs ≥ 40 mg/cylinder and ≤ 2,000 mg/cylinder ≥ -40 deg's C = TRUE ≥ -40 deg's C	First Order Lag Filter with Weight Coefficient Weight Coefficient = 0.0100 Updated each engine event	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		the 20 kHz injected signal is detected only on one of the sensor inputs). The 20 kHz method is typically used for the entire operating region of the engine. However, some engines may not have adequate separation between good and bad circuits at high engine speed. In these cases the 20 kHz method is used at low and medium engine speeds, and the "Normal Noise" method is used at high engine speed only. 2. **Normal Noise**: The Normal Noise method monitors the background engine noise level for a selected frequency range output of the knock detection FFT. The background noise (i.e. Normal Noise) is filtered with a first-order lag filter. A good circuit is determined when the filtered Normal Noise signal is greater than the threshold. See Supporting Tables for method definition: **P0325_P0330_OpenM**						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		ethod defines which of the two diagnostic methods is used as a fucntion of engine speed (RPM). Typical implementations: A. Use 20 kHz method at allengine RPM (used when acceptable separation achieved at all RPM) or B. Use 20 kHz method at low/medium RPM and Normal Noise at high RPM						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Knock Sensor (KS) Performance Bank 1	P0326	This diagnostic checks for knock sensor performance out of the normal expected range, on a per sensor basis. This diagnostic is specifically designed to identify the fault condition where the knock sensor is properly attached electrically, but produces an abnormally low output due to being unattached (or loosely attached) with the mounting bolt (and thus unable to properly transfer the engine vibration energy from the engine block to the knock sensor). The term "Abnormal (engine) Noise" is used to define this diagnostic method. A fault condition is identified when a first-order lag filtered version of the Abnormal Noise signal falls below the diagnostic threshold.	Filtered FFT Intensity (where 'FFT Intensity' = Non-knocking, background engine noise for a selected frequency) Filtered FFT Intensity	**Case 1: Engine not in AFM mode** < **P0326_P0331_AbnormalNoise_Threshold** (Supporting Table) OR **Case 2: Engine is in AFM mode** < **P0326_P0331_AbnormalNoise_Thresh_AFM** (Supporting Table; Engine is in AFM mode)	Diagnostic Enabled? Engine Run Time Engine Speed Engine Air Flow Engine Coolant Temperature or OBD Coolant Enable Criteria Inlet Air Temperature Individual Cylinders enabled for Abnormal Noise Cumlative Number of Engine Revs Above Min Eng Speed (per key cycle)	Yes ≥ 2.0 seconds ≥ 1,500 RPM (not in AFM mode) OR ≥ 1,500 (in AFM mode) AND ≤ 8,500 RPM ≥ 70 mg/cylinder AND ≤ 2,000 mg/cylinder ≥ -40 deg's C = TRUE ≥ -40 deg's C **P0326_P0331_AbnormalNoise_CylsEnabled** (Supporting Table) ≥ 251 Revs	First Order Lag Filters with Weight Coefficient = 0.0025 Updated each engine event	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Knock Sensor (KS) Circuit Low Bank 1	P0327	This diagnostic checks for an out of range low knock sensor signal. A 3-resistor bias network at each sensor input to the ECM provides a DC diagnostic voltage that will remain within a normal range when the external knock sensor circuit is free of short circuit faults. The diagnostic output is reported as a percentage (0 to 100%) when compared to the 5.0 volt reference voltage.	Sensor Input or Return Signal Line	< 8.0 Percent (of 5.0 Volt reference)	Diagnostic Enabled? Engine Speed	Yes > 0 RPM and < 8,500 RPM	50 Failures out of 63 Samples 100 msec rate	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Knock Sensor (KS) Circuit High Bank 1	P0328	This diagnostic checks for an out of range high knock sensor signal. A 3-resistor bias network at each sensor input to the ECM provides a DC diagnostic voltage that will remain within a normal range when the external knock sensor circuit is free of short circuit faults. The diagnostic output is reported as a percentage (0 to 100%) when compared to the 5.0 volt reference voltage.	Sensor Input or Return Signal Line	> 39.0 Percent (of 5 Volt Reference)	Diagnostic Enabled? Engine Speed	Yes > 0 RPM and < 8,500 RPM	50 Failures out of 63 Samples 100 msec rate	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Crankshaft Position (CKP) Sensor A Circuit	P0335	Diagnostic will fail if a crank sensor pulse was not received during a period of time; if crank sensor pulses are received the diagnostic will pass.	Time since last crankshaft position sensor pulse received	>= 4.0 seconds	Starter engaged AND (cam pulses being received OR (MAF_SensorFA AND Engine Air Flow	Test is Enabled = FALSE > 3.0 grams/second))	Continuous every 100 msec	Type A, 1 Trips
			No crankshaft pulses received	>= 0.3 seconds	Engine is Running Starter is not engaged	Test is Enabled	Continuous every 12.5 msec	
			No crankshaft pulses received		Engine is Running OR Starter is engaged No DTC Active:	Test is Enabled P0365 P0366	2 failures out of 10 samples One sample per engine revolution	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Crankshaft Position (CKP) Sensor A Performance	P0336	1. Fail counts will occur if the engine goes out of synchronization repeatedly over a period of time and will pass if the engine stays in synchronization. 2. Diagnostic will fail if synchronization gap is not found in a specified period of time and will pass if the synchronization gap is found. 3. Diagnostic will fail if the incorrect number of crank sensor teeth are detected in-between detecting the synchronization gap and will pass if the correct number of teeth are seen.	Time in which 4 or more crank re-synchronizations occur	< 4.0 seconds	Engine Air Flow Cam-based engine speed No DTC Active:	Test is Enabled >= 3.0 grams/second > 60 RPM P0335	Continuous every 250 msec	Type A, 1 Trips
			No crankshaft synchronization gap found	>= 0.4 seconds	Engine is Running Starter is not engaged	Test is Enabled	Continuous every 12.5 msec	
			Time since starter engaged without detecting crankshaft synchronization gap	>= 1.5 seconds	Starter engaged AND (cam pulses being received OR (MAF_SensorFA AND Engine Air Flow	Test is Enabled = FALSE > 3.0 grams/second))	Continuous every 100 msec	
			Crank pulses received in one engine revolution OR Crank pulses received in one engine revolution	< 1 pulses > 65,535 pulses	Engine is Running OR Starter is engaged No DTC Active:	Test is Enabled P0365 P0366	8 failures out of 10 samples One sample per engine revolution	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Camshaft Position (CMP) Sensor Circuit Bank 1 Sensor A	P0340	Diagnostic will fail if a cam sensor pulse was not received during a period of time; if cam sensor pulses are received the diagnostic will pass.	Time since last camshaft position sensor pulse received OR Time that starter has been engaged without a camshaft sensor pulse	>= 5.5 seconds >= 4.0 seconds	Starter engaged AND (crank pulses being received OR (MAF_SensorFA AND Engine Air Flow	Test is Enabled = FALSE > 3.0 grams/second))	Continuous every 100 msec	Type A, 1 Trips
			Fewer than 4 camshaft pulses received in a time	> 3.0 seconds	Engine is running Starter is not engaged	Test is Enabled	Continuous every 100 msec	
			No camshaft pulses received during 12 MEDRES events (There are 12 MEDRES events per engine cycle) Test begins when MEDRES region AND accumulated number of MEDRES events	= region 4 >= 0 counts	Crankshaft is synchronized Starter must be engaged to enable the diagnostic, but the diagnostic will not disable when the starter is disengaged No DTC Active:	Test is Enabled CrankSensor_FA	Continuous, every MEDRES event unitl test completes, one test at every start attempt	
			The number of camshaft pulses received during 100 engine cycles	= 0 pulses	Crankshaft is synchronized No DTC Active:	Test is Enabled CrankSensor_FA	8 failures out of 10 samples Continuous every engine cycle	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Camshaft Position (CMP) Sensor Performance Bank 1 Sensor A	P0341	Diagnostic will fail if an incorrect number of cam sensor pulses are detected over a number of engine cycles and will pass if the number of cam pulses is correct.	The number of camshaft pulses received during 12 MEDRES events is OR (There are 12 MEDRES events per engine cycle) Test begins when MEDRES region AND accumulated number of MEDRES events	< 4 pulses > 6 pulses = region 4 >= 0 counts	Crankshaft is synchronized Starter must be engaged to enable the diagnostic, but the diagnostic will not disable when the starter is disengaged No DTC Active:	Test is Enabled CrankSensor_FA	Continuous, every MEDRES event unitl test completes, one test at every start attempt	Type A, 1 Trips
			The number of camshaft pulses received during 100 engine cycles OR	< 398 pulses > 402 pulses	Crankshaft is synchronized No DTC Active:	Test is Enabled CrankSensor_FA	8 failures out of 10 samples Continuous every engine cycle	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
IGNITION CONTROL #1 CIRCUIT	P0351	Diagnoses Cylinder #1 Ignition Control (EST) output driver circuit for an Open Circuit fault. Controller specific output driver circuit diagnoses the low sided driver for an open circuit failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver off state indicates open circuit failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for an open circuit.	$\geq$ 30 kΩ impedance between signal and controller ground	Engine running Ignition Voltage	 > 11.0 Volts	50 Failures out of 63 Samples 100 msec rate	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
IGNITION CONTROL #2 CIRCUIT	P0352	Diagnoses Cylinder #2 Ignition Control (EST) output driver circuit for an Open Circuit fault. Controller specific output driver circuit diagnoses the low sided driver for an open circuit failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver off state indicates open circuit failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for an open circuit.	$\geq$ 30 kΩ impedance between signal and controller ground	Engine running Ignition Voltage	 > 11.0 Volts	50 Failures out of 63 Samples 100 msec rate	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
IGNITION CONTROL #3 CIRCUIT	P0353	Diagnoses Cylinder #3 Ignition Control (EST) output driver circuit for an Open Circuit fault. Controller specific output driver circuit diagnoses the low sided driver for an open circuit failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver off state indicates open circuit failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for an open circuit.	≥ 30 kΩ impedance between signal and controller ground	Engine running Ignition Voltage	 > 11.0 Volts	50 Failures out of 63 Samples 100 msec rate	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
IGNITION CONTROL #4 CIRCUIT	P0354	Diagnoses Cylinder #4 Ignition Control (EST) output driver circuit for an Open Circuit fault. Controller specific output driver circuit diagnoses the low sided driver for an open circuit failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver off state indicates open circuit failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for an open circuit.	$\geq$ 30 kΩ impedance between signal and controller ground	Engine running Ignition Voltage	 > 11.0 Volts	50 Failures out of 63 Samples 100 msec rate	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Camshaft Position (CMP) Sensor Circuit Bank 1 Sensor B	P0365	Diagnostic will fail if a cam sensor pulse was not received during a period of time; if cam sensor pulses are received the diagnostic will pass.	Time since last camshaft position sensor pulse received OR Time that starter has been engaged without a camshaft sensor pulse	>= 5.5 seconds >= 4.0 seconds	Starter engaged AND (crank pulses being received OR (MAF_SensorFA AND Engine Air Flow	Test is Enabled = FALSE > 3.0 grams/second))	Continuous every 100 msec	Type B, 2 Trips
			Fewer than 4 camshaft pulses received in a time	> 3.0 seconds	Engine is running Starter is not engaged	Test is Enabled	Continuous every 100 msec	
			No camshaft pulses received during 12 MEDRES events (There are 12 MEDRES events per engine cycle) Test begins when MEDRES region AND accumulated number of MEDRES events	= region 3 >= 0 counts	Crankshaft is synchronized Starter must be engaged to enable the diagnostic, but the diagnostic will not disable when the starter is disengaged No DTC Active:	Test is Enabled CrankSensor_FA	Continuous, every MEDRES event unitl test completes, one test at every start attempt	
			The number of camshaft pulses received during 100 engine cycles	= 0 pulses	Crankshaft is synchronized No DTC Active:	Test is Enabled CrankSensor_FA	8 failures out of 10 samples Continuous every engine cycle	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Camshaft Position (CMP) Sensor Performance Bank 1 Sensor B	P0366	Diagnostic will fail if an incorrect number of cam sensor pulses are detected over a number of engine cycles and will pass if the number of cam pulses is correct.	The number of camshaft pulses received during 12 MEDRES events is OR (There are 12 MEDRES events per engine cycle) Test begins when MEDRES region AND accumulated number of MEDRES events	< 4 pulses > 6 pulses = region 3 >= 0 counts	Crankshaft is synchronized Starter must be engaged to enable the diagnostic, but the diagnostic will not disable when the starter is disengaged No DTC Active:	Test is Enabled CrankSensor_FA	Continuous, every MEDRES event unitl test completes, one test at every start attempt	Type B, 2 Trips
			The number of camshaft pulses received during 100 engine cycles OR	< 398 pulses > 402 pulses	Crankshaft is synchronized No DTC Active:	Test is Enabled CrankSensor_FA	8 failures out of 10 samples Continuous every engine cycle	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Catalyst System Low Efficiency Bank 1	P0420	NOTE: The information below applies to applications that use the Decel Catalyst Monitor Algorithm Oxygen Storage. The catalyst washcoat contains Cerium Oxide. Cerium Oxide reacts with NO and O2 during lean A/F excursions to store the excess oxygen (I.e. Cerium Oxidation). During rich A/F excursions, Cerium Oxide reacts with CO and H2 to release this stored oxygen (I.e. Cerium Reduction). This is referred to as the Oxygen Storage Capacity, or OSC. CatMon's strategy is to "measure" the OSC of the catalyst through forced Rich (intrusive rich) and Lean (decel fuel cutoff) A/F excursions Normalized Ratio OSC Value Calculation Information and Definitions = 1. Raw OSC Calculation = (post cat O2 Resp time - pre cat O2 Resp time) 2. BestFailing OSC value from a calibration	Normalized Ratio OSC Value The EWMA calculation uses a 0.11 coefficient.	< 0.30	All enable criteria associated with P0420 can be found under P2270 - (O2 Sensor Signal Stuck Lean Bank 1 Sensor 2) Rapid Step Response (RSR) feature will initiate multiple tests: If the difference between current EWMA value and the current OSC Normalized Ratio value is and the current OSC Normalized Ratio value is Maximum number of RSR tests to detect failure when RSR is enabled. MAF Predicted catalyst temperature Front O2 Sensor or Front WRAF Rear O2 Sensor General Enable Criteria In addition to the p-codes listed under P2270, the following DTC's shall also	> 0.52 < 0.10 12 > 2.00 g/s < 10.50 g/s < 900 ° C > 775.00 mV or > 1.25 EQR > 775.00 mV	1 test attempted per valid decel period Minimum of 1 test per trip Maximum of 3 tests per trip Frequency: Fueling Related : 12.5 ms OSC Measurements: 100 ms Temp Prediction: 12.5ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		table (based on temp and exhaust gas flow) 3. WorstPassing OSC value (based on temp and exhaust gas flow) Normalized Ratio Calculation = (1-2) / (3-2) A Normalized Ratio of 1 essentially represents a good part and a ratio of 0 essentially represents a very bad part. Refer to the **P0420_WorstPassingOSCTableB1** and **P0420_BestFailingOSCTableB1** in Supporting Tables tab for details The Catalyst Monitoring Test is completed during a decel fuel cutoff event. This fuel cutoff event occurs following a rich instrusive fueling event initiated by the O2 Sensor Signal Stuck Lean Bank 1 Sensor 2 test (P2270). Several conditions must be met in order to execute this test. Additional conditions and their related values			not be set: For switching O2 sensors: For WRAF O2 sensors:	 O2S_Bank_1_Sensor_1_FA O2S_Bank_1_Sensor_2_FA O2S_Bank_2_Sensor_1_FA O2S_Bank_2_Sensor_2_FA WRAF_Bank_1_FA WRAF_Bank_2_FA **P0420_WorstPassingOSCTableB1** **P0420_BestFailingOSCTableB1**		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		are listed in the "Secondary Parameters" and "Enable Conditions" section of this document for P2270 (O2 Sensor Signal Stuck Lean Bank 1 Sensor 2)						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Evaporative Emission (EVAP) System Small Leak Detected (No ELCP - Conventional EVAP Diagnostic - without EAT using IAT Sensor - without Fuel Tank Zone Module (FTZM))	P0442	This DTC will detect a small leak (≥ 0.020") in the EVAP system between the fuel fill cap and the purge solenoid. On some applications a small leak is defined as ≥ 0.025", 0.030", or 0.150". The engine off natural vacuum method (EONV) is used. EONV is an evaporative system leak detection diagnostic that runs when the vehicle is shut off when enable conditions are met. Prior to sealing the system and performing the diagnostic, the fuel volatility is analyzed. In an open system (Canister Vent Solenoid [CVS] open) high volatility fuel creates enough flow to generate a measurable pressure differential relative to atmospheric.After the volatility check, the vent solenoid will close. After the vent is closed, typically a build up of pressure from the hot soak begins (phase-1). The pressure typically will peak and then begin to decrease as the fuel cools. When	The total delta from peak pressure to peak vacuum during the test is normalized against a calibration pressure threshold table that is based upon fuel level and ambient temperature. (Please see **P0442 EONV Pressure Threshold (Pascals)** in Supporting Tables). The normalized value is calculated by the following equation: 1 - (peak pressure - peak vacuum) / pressure threshold. The normalized value is entered into EWMA (with 0= perfect pass and 1= perfect fail). When EWMA is the DTC light is illuminated. The EWMA calculation uses a 0.13 weighting coefficient. The DTC light can be turned off if the EWMA is and stays below the EWMA fail threshold for 3 additional consecutive trips.	 > 0.60 (EWMA Fail Threshold), ≤ 0.35 (EWMA Re-Pass Threshold)	Fuel Level Drive Time Drive length (ECT OR OBD Coolant Enable Criteria Baro Distance since assembly plant Engine not run time before key off must be Time since last complete test if normalized result and EWMA is passing OR Time since last complete test if normalized result or EWMA is failing Estimated ambient temperature at end of drive Estimate of Ambient Air Temperature Valid ****************************** Conditions for Estimate of	10 % ≤ Percent ≤ 90 % ≥ 600 seconds ≥ 5.0 miles ≥ 63 °C = TRUE) ≥ 70 kPa ≥ 10.0 miles ≤ refer to **P0442 Engine Off Time Before Vehicle Off Maximum as a Function of Estimated Ambient Temperature** in Supporting Tables. ≥ 8 hours ≥ 8 hours 0 °C≤Temperature≤ 35 °C ******************************	Once per trip, during hot soak (up to 2,400 sec.). No more than 2 unsuccessful attempts between completed tests.	Type A, 1 Trips EWMA Average run length is 8 to 12 trips under normal conditions Run length is 3 to 6 trips after code clear or non-volatile reset

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		the pressure drops (-62) Pa from peak pressure, the vent is then opened for 60 seconds to normalize the system pressure. The vent is again closed to begin the vacuum portion of the test (phase-2). As the fuel temperature continues to fall, a vacuum will begin forming. The vacuum will continue until it reaches a vacuum peak. When the pressure rises 62 Pa from vacuum peak, the test then completes. If the key is turned on while the diagnostic test is in progress, the test will abort.			Ambient Air Temperature to be valid: 1. Cold Start Startup delta deg C (ECT-IAT) OR 2. Short Soak and Previous EAT Valid Previous time since engine off OR 3. Less than a short soak and Previous EAT Not Valid Previous time since engine off AND Vehicle Speed AND Mass Air Flow Must expire Estimate of Ambient Temperature Valid Conditioning Time. **P0442 Estimate of Ambient Temperature Valid Conditioning Time as a Function of Ign Off Time** in Supporting Tables. OR 4. Not a Cold Start and greater than a Short Soak Previous time since	 ≤ 8 °C ≤ 7,200 seconds ≤ 7,200 seconds ≥ 32 mph ≥ 7 g/sec		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					engine off AND Vehicle Speed AND Mass Air Flow Must expire maximum value in Estimate of Ambient Temperature Valid Conditioning Time. Please see **P0442 Estimate of Ambient Temperature Valid Conditioning Time as a Function of Ign Off Time** in Supporting Tables. ***************************** 1. High Fuel Volatility During the volatility phase, pressure in the fuel tank is integrated vs. volatility time. If the integrated pressure is then test aborts and unsuccessful attempts is incremented. This value equates to an average integrated fuel tank pressure > 1,245 Pa. Please see **P0442 Volatility Time as a Function of Estimate of Ambient Temperature** in Supporting Tables. OR 2. Vacuum Refueling Detected	> 7,200 seconds ≥ 32 mph ≥ 7 g/sec ***************************** < -5		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					See P0454 Fault Code for information on vacuum refueling algorithm. OR 3. Fuel Level Refueling Detected See P0464 Fault Code for information on fuel level refueling. OR 4. Vacuum Out of Range and No Refueling See P0451 Fault Code for information on vacuum sensor out of range and P0464 Fault Code for information on fuel level refueling. OR 5. Vacuum Out of Range and Refueling Detected See P0451 Fault Code for information on vacuum sensor out of range and P0464 Fault Code for information on fuel level refueling. OR 6. Vent Valve Override Failed Device control using an off-board tool to control the vent solenoid, cannot exceed	0.50 seconds		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					during the EONV test OR 7. Key up during EONV test			
					No active DTCs:	MAF_SensorFA ECT_Sensor_FA IAT_SensorFA VehicleSpeedSensor_FA IgnitionOffTimeValid AmbientAirDefault FuelLevelDataFault		
					No Active DTC's TFTKO	P0443 P0446 P0449 P0452 P0453 P0455 P0458 P0459 P0498 P0499 P0496		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Evaporative Emission (EVAP) Canister Purge Solenoid Valve Circuit (ODM) (No ELCP - Conventional EVAP Diagnostic)	P0443	Controller specific output driver circuit diagnoses the canister purge solenoid low sided driver for an open circuit failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver off state indicates open circuit failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for an open circuit.	≥ 200 K Ω impedance between output and controller ground.	Powertrain relay voltage	Voltage ≥ 11.0 volts	20 failures out of 25 samples 250 ms / sample	Type B, 2 Trips Note: In certain controllers P0458 may also set (Canister Purge Solenoid Short to Ground)

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Evaporative Emission (EVAP) Vent System Performance (No ELCP - Conventional EVAP Diagnostic - without Fuel Tank Zone Module (FTZM))	P0446	This DTC will determine if a restriction is present in the vent solenoid, vent filler, vent hose or EVAP canister. This diagnostic runs with normal purge control and canister vent solenoid commanded open. The diagnostic fails when the FTP sensor vacuum measurement is above a vacuum threshold before it accumulates purge volume above a threshold. The diagnostic passes when it accumulates purge volume above a threshold before the FTP sensor vacuum measurement is above a vacuum threshold.	Vent Restriction Prep Test: Vented Vacuum for OR Vented Vacuum for Vent Restriction Test: Tank Vacuum for before Purge Volume After setting the DTC for the first time, 0 liters of fuel must be consumed before setting the DTC for the second time.	 < -623 Pa 60 seconds > 1,245 Pa 60 seconds > 2,989 Pa 5 seconds ≥ 6 liters	Fuel Level System Voltage Startup IAT Startup ECT BARO No active DTCs: No Active DTC's TFTKO	10 % ≤ Percent ≤ 90 % ≥ 10.0 volts 4 °C≤Temperature≤ 35 °C ≤ 35 °C ≥ 70 kPa MAP_SensorFA TPS_FA VehicleSpeedSensor_FA IAT_SensorFA ECT_Sensor_FA AmbientAirDefault EnginePowerLimited FuelLevelDataFault P0443 P0449 P0452 P0453 P0454 P0458 P0459 P0498 P0499	Once per Cold Start Time is dependent on driving conditions Maximum time before test abort is 1,400 seconds	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Evaporative Emission (EVAP) Vent Solenoid Control Circuit (ODM) (No ELCP - Conventional EVAP Diagnostic - without Fuel Tank Zone Module (FTZM))	P0449	Controller specific output driver circuit diagnoses the vent solenoid low sided driver for an open circuit failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver off state indicates open circuit failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for an open circuit.	≥ 200 K Ω impedence between output and controller ground			50 failures out of 63 samples 100 ms / sample	Type B, 2 Trips Note: In certain controllers P0498 may also set (Vent Solenoid Short to Ground)

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Tank Pressure (FTP) Sensor Circuit Performance (No ELCP - Conventional EVAP Diagnostic)	P0451	The DTC will be set if the fuel tank vacuum sensor is out of range when it tries to re-zero prior to the phase-1 or phase-2 portions of the engine-off natural vacuum small leak test. During the EONV test, the fuel tank vacuum sensor is re-zeroed. A re-zero occurs: 1) At the transition from the volatility phase to the pressure phase. 2) At the transition from the pressure phase to the vacuum phase. The re-zero test determines if the tank vacuum signal falls within a calibratable window about atmospheric pressure. If after some time, the tank vacuum signal does not fall to within the window, the re-zero test exits to the refueling rationality test. The refueling rationality test determines if a refueling event caused the re-zero problem. If so, the re-zero problem is ignored. If a refueling event is not	The tank vacuum sensor voltage is compared to a window about the nominal sensor voltage offset (~1.5 volts) Upper voltage threshold (voltage addition above the nominal voltage) Lower voltage threshold (voltage subtraction below the nominal voltage) The difference between tank vacuum sensor voltage and the nominal offset voltage is then normalized against the appropriate threshold listed above to produce a ratio between 0.0 and 1.0. This normalized re-zero ratio is then filtered with a EWMA (with 0= perfect pass and 1=perfect fail). When EWMA is the DTC light is illuminated. The EWMA calculation uses a 0.20 weighting coefficient. The DTC light can be turned off if the EWMA is and stays below the	0.2 volts 0.2 volts > 0.73 (EWMA Fail Threshold), ≤ 0.40 (EWMA Re-Pass Threshold)	This test will execute whenever the engine-off natural vacuum small leak test (P0442) executes		This test is executed during an engine-off natural vacuum small leak test. The number of times that it executes can range from zero to two per engine-off period.The length of the test is determined by the refueling rationality test, which can take up to 600 seconds to complete.	Type A, 1 Trips EWMA Average run length: 6 Run length is 2 trips after code clear or non-volatile reset

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		detected, then the results of the re-zero test are used to determine if there is a re-zero problem. 1) An individual re-zero test generates a re-zero ratio. The ratio goes from 0.0 to 1.0. 2) A 0.0 means that the re-zero pressure signal achieved exactly atmospheric pressure. 3) A ratio of 1.0 means that the re-zero pressure did not get within the window. 4) Re-zero pressure within the window generates values between 0.0 and 1.0. If a refueling event is not detected, then the resulting re-zero ratio is filtered using an exponentially weighted moving average (EWMA). When the EWMA exceeds a fail threshold, the vacuum re-zero test reports a failure. Once the vacuum re-zero test fails, the EWMA fall below a lower re-pass threshold before it can pass the vacuum re-zero test again.	EWMA fail threshold for 3 additional consecutive trips.					

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Tank Pressure (FTP) Sensor Circuit Low Voltage (No ELCP - Conventional EVAP Diagnostic - without Fuel Tank Zone Module (FTZM))	P0452	This DTC will detect a Fuel Tank Pressure (FTP) sensor signal that is too low out of range. The FTP sensor circuit out of range diagnostic compares the raw sensor voltage to a lower voltage threshold. It is an X out of Y diagnostic that runs continuously anytime the controller is awake. If the sensor voltage is below the lower voltage threshold, the low fail counter then increments. If the low fail counter reaches its threshold then a fail is reported for P0452 DTC. A pass is reported for P0452 DTC if the low sample counter reaches its threshold.	FTP sensor signal The normal operating range of the FTP sensor is 0.5 volts (~1245 Pa) to 4.5 volts (~ -3736 Pa).	< 0.15 volts (3.0 % of Vref or ~ 1,495 Pa)			640 failures out of 800 samples 12.5 ms / sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Tank Pressure (FTP) Sensor Circuit High Voltage (No ELCP - Conventional EVAP Diagnostic - without Fuel Tank Zone Module (FTZM))	P0453	This DTC will detect a Fuel Tank Pressure (FTP) sensor signal that is too high out of range. The FTP sensor circuit out of range diagnostic compares the raw sensor voltage to an upper voltage threshold. It is an X out of Y diagnostic that runs continuously anytime the controller is awake. If the sensor voltage is above the upper voltage threshold, the high fail counter then increments. If the high fail counter reaches its threshold then a fail is reported for P0453 DTC. A pass is reported for P0453 DTC if the high sample counter reaches its threshold.	FTP sensor signal The normal operating range of the FTP sensor is 0.5 volts (~1245 Pa) to 4.5 volts (~ -3736 Pa).	> 4.85 volts (97.0 % of Vref or ~ -3,985 Pa)			640 failures out of 800 samples 12.5 ms / sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Tank Pressure (FTP) Sensor Circuit Intermittent (No ELCP - Conventional EVAP Diagnostic)	P0454	This DTC will detect intermittent tank vacuum sensor signals that would have caused the engine-off natural vacuum small leak test to abort due to an apparent re-fueling event. During the EONV test, an abrupt change in fuel tank vacuum is identified as a possible refueling event. If the abrupt change occurs while the vent valve is closed, the EONV small-leak test aborts and the refueling rationality test starts. If the refueling rationality test detects a refueling event, then the vacuum change is considered "rational." If the refueling rationality test does not detect a refueling event, then the vacuum change is considered "irrational." The vacuum change rationality diagnostic is an "X out of Y" test. 1) Each time the EONV test completes, the (Y) sample counter is incremented. 2) Each time the	If an abrupt change in tank vacuum is detected the engine-off natural vacuum test is aborted due to an apparent refueling event. Subsequent to the abort, a refueling rationality test is executed to confirm that a refueling event occurred. If a refueling is confirmed, then the test sample is considered passing. Otherwise, the sample is considered failing indicating an intermittent signal problem. An abrupt change is defined as a change in vacuum in the span of 1.0 seconds. But in 12.5 msec. A refueling event is confirmed if the fuel level has a persistent change of for 30 seconds during a 600 second refueling rationality test.	> 112 Pa < 249 Pa > 10 %	This test will execute whenever the engine-off natural vacuum small leak test (P0442) executes and the canister vent solenoid is closed		This test is executed during an engine-off natural vacuum small leak test. The test can only execute up to once per engine-off period.The length of the test is determined by the refueling rationality test, which can take up to 600 seconds to complete.The test will report a failure if 2 out of 3 samples are failures. 12.5 ms / sample	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		rationality test has an irrational result; the (X) fail counter is incremented. 3) If the (X) fail counter reaches the fail limit before the (Y) sample counter reaches the sample limit, the vacuum change rationality test fails. 4) If the (Y) sample counter reaches the limit before the (X) fail counter fails, the vacuum change rationality test passes.						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Evaporative Emission (EVAP) System Large Leak Detected (No ELCP - Conventional EVAP Diagnostic - without Fuel Tank Zone Module (FTZM))	P0455	This DTC will detect a weak vacuum condition (large leak or purge blockage) in the EVAP system. This mode checks for large leaks and blockages when proper driving conditions are met. If these conditions are met, the diagnostic commands the vent valve closed and controls the purge duty cycle to allow purge flow to purge the fuel tank and canister system while monitoring the fuel tank vacuum level. The algorithm accumulates purge flow during the test to determine a displaced purge volume as the test proceeds. If the displaced purge volume reaches a threshold before the fuel tank vacuum level reaches its passing threshold, then a large leak failure is detected. On fuel systems with fuel caps If the first failure of	Purge volume while Tank vacuum After setting the DTC for the first time, 0 liters of fuel must be consumed before setting the DTC for the second time. Weak Vacuum Follow-up Test (fuel cap replacement test) Weak Vacuum Test failed. Passes if tank vacuum Note: Weak Vacuum Follow-up Test can only report a pass.	> 10 liters ≤ 2,740 Pa ≥ 2,740 Pa	Fuel Level System Voltage BARO Purge Flow No active DTCs: No Active DTC's TFTKO If ECT > IAT, Startup temperature delta (ECT-IAT): Startup IAT Startup ECT Weak Vacuum Follow-up Test This test can run following a weak vacuum failure or on a hot restart.	10 % ≤ Percent ≤ 90 % ≥ 10.0 volts ≥ 70 kPa ≥ 1.55 % MAP_SensorFA TPS_FA VehicleSpeedSensor_FA IAT_SensorFA ECT_Sensor_FA AmbientAirDefault EnginePowerLimited FuelLevelDataFault P0443 P0449 P0452 P0453 P0454 P0458 P0459 P0498 P0499 ≤ 8 °C 4 °C≤Temperature≤ 35 °C ≤ 35 °C	Once per cold start Time is dependent on driving conditions Maximum time before test abort is 1,400 seconds Weak Vacuum Follow-up Test With large leak detected, the follow-up test is limited to 1,300 seconds. Once the MIL is on, the follow-up test runs indefinitely.	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		P0455 occurred after a refueling event was detected and the MIL is off for P0455, the MIL will be commanded off after the first pass of P0455 is reported. If the first failure of P0455 did not occur after a refueling event was detected, the MIL will be commanded off on the ignition cycle after the third consecutive pass of P0455 is reported.the MIL will be commanded off on the ignition cycle after the third consecutive pass of P0455 is reported. On fuel systems without fuel caps The P0455 MIL will be commanded off on the ignition cycle after the third consecutive pass of P0455 is reported.						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Evaporative Emission System Purge Control Valve Circuit Low (No ELCP - Conventional EVAP Diagnostic)	P0458	Controller specific output driver circuit diagnoses the canister purge solenoid low sided driver for a short to ground failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver off state indicates short to ground failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to ground.	 ≤ 0.5 Ω impedence between output and controller ground	Powertrain relay voltage	Voltage ≥ 11.0 volts	20 failures out of 25 samples 250 ms / sample	Type B, 2 Trips Note: In certain controllers P0443 may also set (Canister Purge Solenoid Open Circuit)

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Evaporative Emission System Purge Control Valve Circuit High (No ELCP - Conventional EVAP Diagnostic)	P0459	Controller specific output driver circuit diagnoses the canister purge solenoid low sided driver for a short to power failure when the output is powered on by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to power failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to power.	≤ 0.5 Ω impedence between output and controller power	Powertrain relay voltage	Voltage ≥ 11.0 volts	20 failures out of 25 samples 250 ms / sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Level Sensor 1 Performance (For use on vehicles with a single fuel tank)	P0461	This DTC will detect a primary fuel tank level sensor stuck in-range.	a) Sensed fuel volume change is b) while engine fuel consumption is	a) < 3 liters b) ≥ 12.30 liters	1. Diagnostic Enabled 2. Engine Operational State	1. == True 2. == Running	250 ms / sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Level Sensor 1 Circuit Low Voltage (For use on vehicles with a fuel float connected directly to the ECM)	P0462	This DTC will detect a primary fuel tank sensor out-of-range low.	Fuel level Sender % of 5V range	< 10 %	a) Diagnostic enabled status	a) == True	100 failures out of 125 samples 100 ms / sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Level Sensor 1 Circuit High Voltage (For use on vehicles with a fuel float connected directly to the ECM)	P0463	This DTC will detect a primary fuel tank level sensor out-of-range high.	Fuel level Sender % of 5V range	> 60 %	a) Diagnostic enabled status	a) == True	100 failures out of 125 samples 100 ms / sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Level Sensor 1 Circuit Intermittent (No ELCP - Conventional EVAP Diagnostic)	P0464	This DTC will detect intermittent fuel level sensor signals that would have caused the engine-off natural vacuum small leak test to abort due to an apparent re-fueling event. During the EONV test, a change in fuel level is identified as a possible refueling event. If the change occurs while the vent valve is closed, the EONV small-leak test aborts and the refueling rationality test starts. If the refueling rationality test detects a refueling event, the fuel level change is considered “rational.” If the refueling rationality test does not detect refueling, the fuel level change is considered “irrational.” The fuel level change rationality diagnostic is an “X out of Y” test. 1) Each time the EONV test completes, the (Y) sample counter is incremented. 2) Each time the rationality test has an	If a change in fuel level is detected, the engine-off natural vacuum test is aborted due to an apparent refueling event. Subsequent to the abort, a refueling rationality test is executed to confirm that an actual refueling event occurred. If a refueling event is confirmed, then the test sample is considered passing. Otherwise, if a refueilng event is not confirmed, then the test sample is considered failing which indicates an intermittent signal problem. An intermittent fuel level signal problem is defined as: The fuel level changes by and does not remain for 30 seconds during a 600 second refueling rationality test.	 > 10 % > 10 %	This test will execute whenever the engine-off natural vacuum small leak test (P0442) executes		This test is executed during an engine-off natural vacuum small leak test. The test can only execute up to once per engine-off period.The length of the test is determined by the refueling rationality test, which can take up to 600 seconds to complete.The test will report a failure if 2 out of 3 samples are failures. 100 ms / sample	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		irrational result; the (X) fail counter is incremented. 3) If the (X) fail counter reaches the fail limit before the (Y) sample counter reaches the sample limit, the fuel level change rationality test fails. 4) If the (Y) sample counter reaches the limit before the (X) fail counter fails, the fuel level change rationality test passes.						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cooling Fan 1 Relay Control Circuit Open (Output Driver Monitor) (Not used on EREV/ PHEV/ HEV)	P0480	Diagnoses the cooling fan 1 relay control low side driver circuit for circuit faults	Voltage low during driver off state (indicates open circuit)	Open Circuit: ≥ 200 K Ω impedance between signal and controller ground	Powertrain Relay Voltage	Voltage ≥ 11.00 volts	50.00 failures out of 63.00 samples 100 ms / sample	Type B, 2 Trips Note: In certain controllers P0691 may also set (Fan 1 Short to Ground).

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cooling Fan 2 Relay Control Circuit Open (ODM)	P0481	Diagnoses the cooling fan 2 relay control low side driver circuit for circuit faults	Voltage low during driver off state (indicates open circuit)	Open Circuit: ≥ 200 K Ω impedance between signal and controller ground	Powertrain Relay Voltage	Voltage ≥ 11.00 volts	50.00 failures out of 63.00 samples 100 ms / sample	Type B, 2 Trips Note: In certain controllers P0693 may also set (Fan 2 Short to Ground)

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Evaporative Emission (EVAP) System Flow During Non-Purge (No ELCP - Conventional EVAP Diagnostic - without Fuel Tank Zone Module (FTZM))	P0496	This DTC will determine if the purge solenoid is leaking to engine manifold vacuum. This test checks for purge valve leaks to intake manifold vacuum such that there would always be a small amount of purge flow present. It does this by sealing the EVAP system (purge and vent valve closed) and then monitors fuel tank vacuum level. The fuel tank vacuum level should not increase. If tank vacuum increases above a threshold, a malfunction is indicated. Additional Information This diagnostic test detects purge valve leaks to intake manifold vacuum. It is not intended to detect purge valve leaks to the atmosphere which are monitored by the EONV small leak diagnostic (P0442). The purge valve leak diagnostic exists to helps service replace	Tank Vacuum for Test time	> 2,491 Pa 5 seconds ≤ refer to **P0496 Purge Valve Leak Test Engine Vacuum Test Time (Cold Start) as a Function of Fuel Level** in Supporting Tables. Test time only increments when engine vacuum ≥ 10.0 kPa.	Fuel Level System Voltage BARO Startup IAT Startup ECT Engine Off Time No active DTCs: No Active DTC's TFTKO	10 % ≤ Percent ≤ 90 % ≥ 10.0 volts ≥ 70 kPa 4 °C≤Temperature≤ 35 °C ≤ 35 °C ≥ 28,800.0 seconds MAP_SensorFA TPS_FA VehicleSpeedSensor_FA IAT_SensorFA ECT_Sensor_FA AmbientAirDefault EnginePowerLimited FuelLevelDataFault P0443 P0449 P0452 P0453 P0454 P0458 P0459 P0498 P0499	Once per cold start Cold start: max time is 1,400 seconds	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		leaking purge valves that could otherwise be detected with the EONV small leak diagnostic (P0442).						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Evaporative Emission System Vent Solenoid Control Circuit Low (No ELCP - Conventional EVAP Diagnostic - without Fuel Tank Zone Module (FTZM))	P0498	Controller specific output driver circuit diagnoses the vent solenoid low sided driver for a short to ground failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver off state indicates short to ground failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to ground.	≤ 0.5 Ω impedence between output and controller ground			50 failures out of 63 samples 100 ms / sample	Type B, 2 Trips Note: In certain controllers P0449 may also set (Vent Solenoid Open Circuit)

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Evaporative Emission System Vent Solenoid Control Circuit High (No ELCP - Conventional EVAP Diagnostic - without Fuel Tank Zone Module (FTZM))	P0499	Controller specific output driver circuit diagnoses the vent solenoid low sided driver for a short to power failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds. If the P0499 is active, an intrusive test is performed with the vent solenoid commanded closed for 15 seconds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to power failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to power.	 ≤ 0.5 Ω impedence between output and controller power			50 failures out of 63 samples 100 ms / sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Low Engine Speed Idle System	P0506	This DTC indicates that actual engine speed is lower than desired engine speed at idle so that it is out of speed control capability. Testing is performed when basic conditions are met. If filtered engine speed error exceeds a calibrated threshold for a calibrated duration, code is set. This testing is performed continuously per trip if basic conditions are met	Filtered Engine Speed Error. It is calculated with a calibrated filter coefficient	> 91.00 rpm	Baro	> 70 kPa	Diagnostic runs in every 12.5 ms loop	Type B, 2 Trips
			Filter coefficient	0.00300	Coolant Temp	> 60 °C and < 125 °C	Diagnostic reports pass or fail in 10 seconds once all enable conditions are met	
					Engine run time	≥ 30 sec		
					Ignition voltage	32 ≥ volts ≥ 11		
					Time since gear change	≥ 3 sec		
					Time since a TCC mode change	> 3 sec		
					IAT	> -20 °C		
					Vehicle speed	≤ 1.24 mph, 2kph		
					Commanded RPM delta	≤ 25 rpm		
					Idle time	> 5 sec		
					For manual transmissions: Clutch Pedal Position	> 12.00 pct		
					or Clutch Pedal Position	< 75.00 pct		
						PTO not active		
						Transfer Case not in 4WD LowState		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
						Off-vehicle device control (service bay control) must not be active. following conditions not TRUE: (VeTESR_e_EngSpdReqIntvType = CeTESR_e_EngSpdMinLimit AND VeTESR_e_EngSpdReqRespType = CeTESR_e_NoSuggestion) Clutch is not depressed		
					No active DTCs	TC_BoostPresSnsrFA ECT_Sensor_FA EnginePowerLimited EGRValveCircuit_FA EGRValvePerformance_FA IAT_SensorCircuitFA EvapFlowDuringNonPurge_FA FuelTrimSystemB1_FA FuelTrimSystemB2_FA FuelInjectorCircuit_FA MAF_SensorFA EngineMisfireDetected_FA IgnitionOutputDriver_FA TPS_FA TPS_Performance_FA VehicleSpeedSensor_FA FuelLevelDataFault LowFuelConditionDiagnostic Clutch Sensor FA AmbPresDfltdStatus		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
						P2771		
					All of the above met for Idle time	> 5 sec		
						The diagnostic does not run during autostop as engine is shutdown during that time (occurs in a hybrid or 12v start stop vehicle)		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
High Engine Speed Idle System	P0507	This DTC indicates that actual engine speed is higher than desired engine speed at idle so that it is out of speed control capability. Testing is performed when basic conditions are met. If filtered engine speed error exceeds a calibrated threshold for a calibrated duration, code is set. This testing is performed continuously per trip if basic conditions are met	Filtered Engine Speed Error. It is calculated with a calibrated filter coefficient Filter coefficient	< -182.00 rpm 0.00300	Baro Coolant Temp Engine run time Ignition voltage Time since gear change Time since a TCC mode change IAT Vehicle speed Commanded RPM delta For manual transmissions: Clutch Pedal Position or Clutch Pedal Position	> 70 kPa > 60 °C and < 125 °C Must verify ≥ 30 sec 32 ≥ volts ≥ 11 ≥ 3 sec > 3 sec > -20 °C ≤ 1.24 mph, 2kph ≤ 25 rpm > 12.00 pct < 75.00 pct PTO not active Transfer Case not in 4WD LowState Off-vehicle device control (service bay control) must not be active.	Diagnostic runs in every 12.5 ms loop Diagnostic reports pass or fail in 10 seconds once all enable conditions are met	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
						following conditions not TRUE: (VeTESR_e_EngSpdReqIntvType = CeTESR_e_EngSpdMinLimit AND VeTESR_e_EngSpdReqRespType = CeTESR_e_NoSuggestion)		
						Clutch is not depressed		
					No active DTCs	TC_BoostPresSnsrFA ECT_Sensor_FA EnginePowerLimited EGRValveCircuit_FA EGRValvePerformance_FA IAT_SensorCircuitFA EvapFlowDuringNonPurge_FA FuelTrimSystemB1_FA FuelTrimSystemB2_FA FuelInjectorCircuit_FA MAF_SensorFA EngineMisfireDetected_FA IgnitionOutputDriver_FA TPS_FA TPS_Performance_FA VehicleSpeedSensor_FA FuelLevelDataFaultLow FuelConditionDiagnostic Clutch SensorFA AmbPresDfltdStatus P2771		
					All of the above met	> 5 sec		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					for Idle time	The diagnostic does not run during autostop as engine is shutdown during that time (occurs in a hybrid or 12v start stop vehicle)		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cold Start Rough Idle	P050D	Monitors the combustion performance when the cold start emission reduction strategy is active by accumulating and determining the percentage of engine cycles that have less than complete combustion relative to the total number of engine cycles in which Dual Pulse is active.	Deceleration index vs. Engine Speed Vs Engine load Deceleration index calculation is tailored to specific vehicle. Tables used are 1st tables encountered that are not max of range. Undetectable region at a given speed/load point is where all tables are max of range point. Incomplete combustion identified by P0300 threshold tables:	(>Idle SCD AND >Idle SCD ddt Tables) OR (>Idle Cyl Mode AND > Idle Cyl Mode ddt Tables)	Misfire Algorithm Enabled (Refer to P0300 for Enablement Requirements) OBD Manufacturer Enable Counter To enable the diagnostic, the Cold Start Emission Reduction Strategy Must Be Active per the following: Catalyst Temperature AND Engine Coolant AND Engine Coolant AND Barometric Pressure In addition, Dual Pulse Strategy Is Enabled and Active Per the following: Engine Speed Accel Position Engine Run Time For the engine speeds and loads in which Dual Pulse is active:	= 0 < 350.00 degC > 16.00 degC <= 50.00 degC >= 70.00 KPa >= 7,000.00 RPM <= 7,001.00 RPM <= 0.00 Pct < 0 seconds	Runs once per trip when the cold start emission reduction strategy is active and Dual Pulse is enabled and active. Frequency: 100ms Test completes after Dual Pulse is no longer active OR The first 500 engine cycles have been reached	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Dual Pulse Error induced misfires percentage	>= catalyst damaging misfire		
					Dual Pulse Error induced misfires percentage	< 90% of the maximum achieveable catalyst damaging misfire.		
					Engine Cycles	>= 50.00 < 501		
					The Cold Start Emission Reduction strategy must not be exiting. The strategy will exit per the following:			
					Catalyst Temperature AND	>= 900.00 degC		
					Engine Run Time	>= 20.00 seconds		
					OR			
					Engine Run Time	> **P050D_P1400_CatalystLightOffExtendedEngineRunTimeExit** This Extended Engine run time exit table is a function of percent ethanol and Catmons NormRatioEWMA. Refer to "Supporting Tables" for details.		
					OR			
					Barometric Pressure	< 70.00 KPa		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Dual Pulse Strategy will exit per the following:			
					Engine Speed	> 0.00 RPM		
					OR			
					Accel Position	> 100.00 Pct		
					Engine Run Time	>= 0 seconds		
					Dual Pulse Strategy will also exit if the any of the "Additional Dual Pulse Enabling Criteria" is not satisfied:			
					"Additional Dual Pulse Enabling Criteria":			
					Green Engine Enrichment	Not Enabled		
					Misfire Converter Protection strategy	Not being requested		
					Engine Metal Overtemp strategy	Not being requested		
					Fuel control state	Open Loop		
					Output State Control	Not being requested for fuel		
					DOD Or DFCO	Not Active		
					Power Enrichment	Not Active		
					Dynamic Power Enrichment	Not Active		
					Piston Protection	Not Active		
					Hot Coolant Enrichment	Not Active		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Injector Flow Test General Enable DTC's Not Set:	Not Active AcceleratorPedalFailure ECT_Sensor_FA IAT_SensorCircuitFA MnfdTempSensorCktFA CrankSensor_FA FuelInjectorCircuit_FA MAF_SensorFA MAP_SensorFA AnyCamPhaser_TFTKO ClutchPstnSnsr FA IAC_SystemRPM_FA IgnitionOutputDriver_FA TPS_FA VehicleSpeedSensor_FA FuelInjectorCircuit_TFTKO FHPR_b_FRP_SnsrCkt_FA FHPR_b_FRP_SnsrCkt_TFTKO FHPR_b_PumpCkt_FA FHPR_b_PumpCkt_TFTKO TransmissionEngagedState_FA EngineTorqueEstInaccurate FuelPumpRlyCktFA		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Engine Oil Pressure (EOP) Sensor Performance - Two Stage Oil Pump	P0521	Determines if the Engine Oil Pressure (EOP) Sensor is stuck or biased in range. The engine oil pressure is compared against thresholds when engine is running and when engine is off.The engine oil pressure rationality diagnostic has two parts: engine runing test and engine off test. The engine running test compares the measured oil pressure to threshold. If the measured oil pressure is out of the thresholds, then the error counter increments. The engine off test compares the measured oil pressure against thresholds after the engine has stopped rotating. If the measured oil pressure is out of the thresholds, then the error counter increments.	**Two Stage Oil Pump EOP Sensor Test with Engine Running, High Pressure State** To Fail when previously passing with the engine running: Filtered Engine Oil Pressure below expected threshold OR Filtered Engine Oil Pressure above expected threshold To pass when previously failing: Filtered Engine Oil Pressure above low threshold plus an offset OR	Filtered Oil Pressure < (**P0521_P06DD_P06DE_OP_HiStatePressure** * 0.95 - 110.0 kPa) OR Filtered Oil Pressure > (**P0521_P06DD_P06DE_OP_HiStatePressure** * 1.05 + 110.0 kPa) Filtered Oil Pressure > **P0521_P06DD_P06DE_OP_HiStatePressure** (**re** * 0.95 - 110.0 kPa + 10.0 kPa) OR Filtered Oil Pressure < (	Two Stage Oil Pump is Present = TRUE Pump is in high pressure state Engine Running Diagnostic Status Engine Off Rationality Test Diagnostic Reporting Status Oil Pressure Sensor In Use Engine Running Ambient Air Pressure Oil Aeration (= TRUE if engine speed > 10,000 RPM for longer than 30.0 seconds) Filtered Engine Speed within range Modelled Oil Temperature within range Pump state change complete No active DTC's	TRUE Enabled Test not report a fail state Yes ≥ 10.0 seconds ≥ 70.0 kPa FALSE 1,000 RPM ≤ Filtered Engine Speed ≤ 4,500 RPM 40.0 deg C ≤ Oil Temp ≤ 120.0 deg C Time since state change > 1.00 s Fault bundles: MAF_SensorFA ECT_Sensor_FA IAT_SensorFA EngOilPressureSensorCktFA AmbientAirDefault	≥ 40 errors out of 50 samples. Performed every 100 msec ≥ 10 passes out of 50 samples. Performed every 100 msec	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Filtered Engine Oil Pressure below high threshold minus an offset	**P0521_P06DD_P06DE_OP_HiStatePressure** * 1.05 + 110.0 kPa - 10.0 kPa) (Details on Supporting Tables Tab: **P0521_P06DD_P06DE_OP_HiStatePressure**)		EngOilTempFA CrankSensor_FA		
			Two Stage Oil Pump EOP Sensor Test with Engine Running, Low Pressure State To Fail when previously passing with the engine running: Filtered Engine Oil Pressure below expected threshold OR Filtered Engine Oil Pressure above expected threshold	Filtered Oil Pressure < (**P0521_P06DD_P06DE_OP_LoStatePressure** * 0.95 - 115.0 kPa) OR Filtered Oil Pressure > (**P0521_P06DD_P06DE_OP_LoStatePressure** * 1.05 + 115.0 kPa)	Two Stage Oil Pump is Present = TRUE Pump is in low pressure state Engine Running Diagnostic Status Engine Off Rationality Test Diagnostic Reporting Status Oil Pressure Sensor In Use Engine Running Ambient Air Pressure Oil Aeration (= TRUE if engine speed > 10,000 RPM for longer than 30.0 seconds) Filtered Engine Speed within range	TRUE Enabled Test not report a fail state Yes ≥ 10.0 seconds ≥ 70.0 kPa FALSE 1,000 RPM ≤ Filtered Engine Speed ≤ 4,500 RPM	≥ 40 errors out of 50 samples. Performed every 100 msec	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			To pass when previously failing: Filtered Engine Oil Pressure above low threshold plus an offset OR Filtered Engine Oil Pressure below high threshold minus an offset	Filtered Oil Pressure > (**P0521_P06DD_P06DE_OP_LoStatePressure** * 0.95 - 115.0 kPa + 10.0 kPa) OR Filtered Oil Pressure < (**P0521_P06DD_P06DE_OP_LoStatePressure** * 1.05 + 115.0 kPa - 10.0 kPa) (Details on Supporting Tables Tab: **P0521_P06DD_P06DE_OP_LoStatePressure**)	Modelled Oil Temperature within range Pump state change complete No active DTC's	40.0 deg C ≤ Oil Temp ≤ 120.0 deg C Time since state change > 1.00 s Fault bundles: MAF_SensorFA ECT_Sensor_FA IAT_SensorFA EngOilPressureSensorCktFA AmbientAirDefault EngOilTempFA CrankSensor_FA	≥ 10 passes out of 50 samples. Performed every 100 msec	
			Two Stage Oil Pump EOP Sensor Test with Engine Off If enabled: To Fail when previously passing with the engine off: Filtered Engine Oil Pressure greater than threshold	 Filtered Oil Pressure ≥ 40.0 kPa	Two Stage Oil Pump is Present = TRUE Engine Off Rationality Test Diagnostic Status Engine Running Rationality Test Diagnostic Status Modelled Oil Temperature No Engine Movement No active DTC's	TRUE Enabled Test not report a fail state ≥ 70.0 deg C > 10.0 seconds EngineModeNotRunTimer_FA EngOilTempFA	≥ 20 errors out of 40 samples. Run once per trip	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
						EngOilPressureSensorCkt FA CrankSensor_FA		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Engine Oil Pressure (EOP) Sensor Circuit Low Voltage	P0522	Determines if the Engine Oil Pressure (EOP) Sensor circuit voltage is too low. This diagnostic compares the EOP circuit voltage to the reference voltage.	(Engine Oil Pressure Sensor Circuit Voltage) ÷ 5 Volts) *100	< 5.00 percent Deadband: < 5 percent or > 95 percent	Engine Speed Enable Engine Speed Disable Oil Pressure Sensor In Use Diagnostic Status	> 400 rpm < 350 rpm Yes Enabled	1,280 failures out of 1,600 samples Performed every 3.125 msec	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Engine Oil Pressure (EOP) Sensor Circuit High Voltage	P0523	Determines if the Engine Oil Pressure (EOP) Sensor circuit voltage is too high. This diagnostic compares the EOP circuit voltage to the reference voltage.	(Engine Oil Pressure Sensor Circuit Voltage) ÷ 5 Volts) *100	> 95.00 percent Deadband: < 5 percent or > 95 percent	Oil Pressure Sensor In Use Diagnostic Status	Yes Enabled	1,280 failures out of 1,600 samples Performed every 3.125 msec	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cruise Control Mutil-Functon Switch Circuit	P0564	Detect when cruise control multi-function switch circuit (analog) voltage is in an invalid range. "Emissions Neutral Default Action : When the BCM tells the ECM that the cruise control analog input voltage is in an invalid range, ECM sets the code and cruise control will be disabled and disengaged for the remainder of the key cycle regardless of current pass/fail condition once it fails."Detect when cruise control multi-function switch circuit (analog) voltage is in an invalid range	Cruise Control analog circuit voltage must be "between ranges" for greater than a calibratable period of time.	The cruise control analog voltage A/D count ratio is considerred to be "between ranges" when the ratio is measured in the following ranges: 0.28 -0.31, 0.415-0.445, 0.585 - 0.615 0.78 - 0.81, 1.005 - 1.035	Diagnostic is Enabled. CAN cruise switch diagnostic enable in ECM	1.00	fail continuously for greater than 0.500 seconds	Type C, No SVS , "Emissions Neutral Diagnostics – special type C" "Neutral Default State - When the BCM tells the ECM that the cruise control analog input voltage is in an invalid range, ECM sets the code and cruise control is disabled "

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cruise Control On Switch Circuit	P0565	Detects a failure of the cruise on/off switch in a continously applied state "Emissions Neutral Default Action - When the BCM tells the ECM that the cruise control analog input voltage is in the Momentary Cruise On/Off range for too long, the code is set and cruise control is disabled and disengaged for the remainder of the key cycle regardless of current pass/fail condition once it fails." Only applicable for vehicles with a momentary on/off cruise switch architecture.	Cruise Control On switch remains applied for greater than a calibratable period of time.	fail continuously in the applied state for greater than 20.00 seconds	Diagnostic is Enabled. CAN cruise switch diagnostic enable in ECM	1.00	fail continuously for greater than 20.00 seconds	Type C, No SVS , "Emissions Neutral Diagnostics – special type C"

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cruise Control Resume Circuit	P0567	Detects a failure of the cruise resume switch in a continously applied state "Emissions Neutral Default Action : When the BCM tells the ECM that the cruise control analog input voltage is in the Resume range for too long, the code is set and cruise control is disabled and disengaged for the remainder of the key cycle regardless of current pass/fail condition once it fails."	Cruise Control Resume switch remains applied for greater than a calibratable period of time.	fail continuously in the applied state for greater than 89.000 seconds	Diagnostic is Enabled. CAN cruise switch diagnostic enable in ECM	1.00	fail continuously for greater than 89.000 seconds	Type C, No SVS , "Emissions Neutral Diagnostics – special type C"

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cruise Control Set Circuit	P0568	Detects a failure of the cruise set switch in a continously applied state "Emissions Neutral Default Action : When the BCM tells the ECM that the cruise control analog input voltage is in the Set range for too long, the code is set and cruise control will be disabled and disengaged for the remainder of the key cycle regardless of current pass/fail condition once it fails."	Cruise Control Set switch remains applied for greater than a calibratable period of time.	fail continuously in the applied state for greater than 89.000 seconds	Diagnostic is Enabled. CAN cruise switch diagnostic enable in ECM	1.00	fail continuously for greater than 89.000 seconds	Type C, No SVS , "Emissions Neutral Diagnostics – special type C"

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cruise Control Cancel Switch Circuit	P056C	Detects a failure of the cruise cancel switch in a continously applied state "Emissions Neutral Default Action : When the BCM tells the ECM that the cruise control analog input voltage is in the Cancel range for too long, ECM sets the code and cruise control will be disabled and disengaged for the remainder of the key cycle regardless of current pass/fail condition once it fails."	Cruise Control Cancel switch remains applied for greater than a calibratable period of time.	fail continously in the applied state for greater than 20.00 seconds	Diagnostic is Enabled. CAN cruise switch diagnostic enable in ECM	1.00	fail continuously for greater than 20.00 seconds	Type C, No SVS , "Emissions Neutral Diagnostics – special type C"

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cruise Control Input Circuit	P0575	Determines if cruise switch state received from the BCM is valid. "Emissions Neutral Default Action : When the ECM determines that a serial communication fault from the BCM has occurred with frame $1E1, ECM sets the code and cruise control will be disabled and disengaged for the remainder of the key cycle regardless of current pass/fail condition once it fails."	If x of y rolling count / protection value faults occur, disable cruise for duration of fault	Message <> 2's complement of message Message rollling count<>previous message rolling count value plus one	Diagnostic is Enabled. Cruise Control Switch Serial Data Error Diagnostic Enable Serial communication to BCM Power Mode Engine Running	1.00 No loss of communication = RUN = TRUE	9 failures out of / 17 samples Performed on every received message 9 rolling count failures out of / 17 samples Performed on every received messagw	Type C, No SVS , "Emissions Neutral Diagnostics – special type C"

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Brake Pedal Position Sensor Circuit Range/ Performance	P057B	This diagnostic monitors the Brake Pedal Position Sensor for a stuck in range failure	.Brake pedal position sensor movement diagnostic cal is enabled 1.00	True	Diagnostic is Enabled. Brake Pedal Position Sensor Circuit Range / Performance Diagnostic Enable	1.00 ignition voltage > 10.00		MIL: Type A, 1 Trips
			Calculated EWMA value must be greater than calibratable theshold after calibratable number of tests have completed to report a "test passed" for P057B	EWMA value looked up in supporting table **P057B KtBRKI_K_FastTestPointWeight** P057B as a function of calculated brake pedal position delta EWMA value is > 0.80	calculated brake pedal position delta sample counter > 50.00 for fast test OR calculated brake pedal position delta sample counter > 1,000.00 for slow test	calculated brake pedal position delta > 4.00 OR (for slow test) shift lever has been in park once this key cycle vehicle speed >= 5.00 accelerator pedal position < 5.00	total number of EWMA tests > 20.00	
			Calculated EWMA Value must be less than calibratable threshold after calibratable number of tests have completed to report a "test failed" for P057B. This test runs once per key cycle	EWMA value looked up in supporting table **P057B KtBRKI_K_CmpltTestPointWeight** P057B as a function of calculated brake pedal position delta EWMA value is less thatn 0.40	no DTC's active (P057C, P057D)	shift lever has been in park once this key cycle vehicle speed >= 5.00 accelerator pedal position < 5.00	total number of EWMA tests > 2.00	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Brake Pedal Position Sensor Circuit Low	P057C	detects short to ground for brake pedal position sensor	If x of y samples are observed below failure threshold, default brake pedal position to zero percent.	5.00	Diagnostic is Enabled. Brake Pedal Position Sensore Low Voltage Diagnostic Enable	1.00	20 / 32.00 counts	MIL: Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Brake Pedal Position Sensor Circuit High	P057D	detects open circuit for brake pedal position sensor	If x of y samples are observed above failure threshold, default brake pedal position to zero percent and set DTC	95.00	Diagnostic is Enabled. Brake Pedal Position Sensore High Voltage Diagnostic Enable	1.00	20.00 / 32.00 counts	MIL: Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Brake Pedal Position Sensor Circuit Intermittent/ Erratic	P057E	detects noisy / erratic ouput for brake pedal position sensor	If x of y samples are observed above failure threshold, default brake pedal position to zero percent and set DTC	25.00	Diagnostic is Enabled. Brake Pedal Position Sensor Circuit Intermittent / Erratic Diagnostic Enable	1.00	5.00 / 20.00 counts	MIL: Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cruise Control Multi-function Circuit Low Voltage	P0580	detects short to ground failure for cruise multi-function switch circuit "Emissions Neutral Default Action : When the BCM tells the ECM that the cruise switch circuit voltage is too low for too long, ECM sets the code and cruise control will be disabled and disengaged for the remainder of the key cycle regardless of current pass/fail condition once it fails." Only applicable for vehicles with a momentary on/off cruise switch architecture.	Cruise Control analog circuit voltage must be in an "Open Short To Ground" range for greater than a calibratable period of time.	The cruise control analog voltage A/D count ratio is considerred to be "open short to ground when the ratio is measured in the following rangs: 0 - 0.185	Diagnostic is Enabled. CAN cruise switch diagnostic enable in ECM	1.00	fail continuously for greater than 2.00 seconds	Type C, No SVS , "Emissions Neutral Diagnostics – special type C"

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cruise Control Multi-function Circuit High Voltage	P0581	detects short to power failure for cruise multi-function switch circuit "Emissions Neutral Default Action : When the BCM tells the ECM that the cruise switch circuit voltage is too high for too long, ECM sets the code and cruise control will be disabled and disengaged for the remainder of the key cycle regardless of current pass/fail condition once it fails." Only applicable for vehicles with a momentary on/off cruise switch architecture.	Cruise Control analog circuit voltage must be in "Short To Power" range for greater than a calibratable period of time.	The cruise control analog voltage A/D count ratio is considered to be "short to power" when the ratio is measured in the following range: 1.005 - 1.035	Diagnostic is Enabled. CAN cruise switch diagnostic enable in ECM	1.00	fail continuously for greater than 2.00 seconds	Type C, No SVS , "Emissions Neutral Diagnostics – special type C"

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Control Module Read Only Memory (ROM)	P0601	This DTC will be stored if the calibration check sum is incorrect or the flash memory detects an uncorrectable error via the Error Correcting Code.	The Primary Processor's calculated checksum does not match the stored checksum value. Covers all software and calibrations.	1 failure if the fault is detected during the first pass. 5.00 failures if the fault occurs after the first pass is complete.			Diagnostic runs continuously in the background.	Type A, 1 Trips
			The Primary Processor's Error Correcting Code hardware in the flash memory detects an error. Covers all software and calibrations.	254 failures detected via Error Correcting Code			Diagnostic runs continuously via the flash hardware.	
			The Primary Processor's calculated checksum does not match the stored checksum value for a selected subset of the calibrations.	2 consecutive failures detected or 5 total failures detected.			Diagnostic runs continuously. Will report a detected fault within 200 ms.	
			The Secondary Processor's calculated checksum does not match the stored checksum value. Covers all software and calibrations.	1 failure if the fault is detected during the first pass. 5 failures if the fault occurs after the first pass is complete.			Diagnostic runs continuously in the background.	
				In all cases, the failure count is cleared when controller shuts down				

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Control Module Not Programmed	P0602	This DTC will be stored if the ECU is a service part that has not been programmed.	Service (reflash) controller calibration present	= 1		none	Diagnostic runs at powerup and once per second continuously after that	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
ECM Long Term Memory Reset	P0603	This DTC detects an invalid NVM which includes a Static NVM, Perserved NVM, ECC ROM in NVM Flash Region, and Perserved NVM during shut down.	Static NVM region error detected during initialization				Diagnostic runs at controller power up.	Type A, 1 Trips
			Perserved NVM region error detected during initialization				Diagnostic runs at controller power up.	
			ECC ROM fault detected in NVM Flash region ECC ROM Error Count >	 3			Diagnostic runs at controller power up.	
			Perserved NVM region error detected during shut down.				Diagnostic runs at controller power down.	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
ECM RAM Failure	P0604	Indicates that the ECM has detected a RAM fault. This includes Primary Processor System RAM Fault, Primary Processor Cache RAM Fault, Primary Processor TPU RAM Fault, Primary Processor Update Dual Store RAM Fault, Primary Processor Write Protected RAM Fault, and Secondary Processor RAM Fault. This diagnostic runs continuously.	Indicates that the primary processor is unable to correctly read data from or write data to system RAM. Detects data read does not match data written >=	254 counts			Will finish first memory scan within 30 seconds at all engine conditions - diagnostic runs continuously (background loop)	Type A, 1 Trips
			Indicates that the primary processor is unable to correctly read data from or write data to cached RAM. Detects data read does not match data written >=	254 counts			Will finish first memory scan within 30 seconds at all engine conditions - diagnostic runs continuously (background loop)	
			Indicates that the primary processor is unable to correctly read data from or write data to TPU RAM. Detects data read does not match data written >=	5 counts			Will finish first memory scan within 30 seconds at all engine conditions - diagnostic runs continuously (background loop)	
			Indicates that the primary processor detects a mismatch between the data and dual data is found during RAM updates. Detects a mismatch in data and dual data updates >	0.45588 s			When dual store updates occur.	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Indicates that the primary processor detects an illegal write attempt to protected RAM. Number of illegal writes are >	65,534 counts			Diagnostic runs continuously (background loop)	
			Indicates that the secondary processor is unable to correctly read data from or write data to system RAM. Detects data read does not match data written >=	5 counts			Will finish first memory scan within 30 seconds at all engine conditions - diagnostic runs continuously (background loop)	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Internal ECM Processor Integrity Fault	P0606	Indicates that the ECM has detected an internal processor integrity fault. These include diagnostics done on the SPI Communication as well as a host of diagnostics for both the primary and secondary processsors.	Loss or invalid message of SPI communication from the Secondary Processor at initialization detected by the Primary Processor or loss or invalid message of SPI communication from the Secondary Processor after a valid message was received by the Primary Processor	Loss or invalid message at initialization detected or loss or invalid message after a valid message was recieved	Run/Crank voltage Run/Crank voltage	>= 6.41 Volts or >= 11.00 Volts, else the failure will be reported for all conditions	In the primary processor, 159 / 399 counts intermittent or 39 counts continuous; 39 counts continuous @ initialization. 12.5 ms /count in the ECM main processor	Type A, 1 Trips
			Loss or invalid message of SPI communication from the Primary Processor at initialization detected by the Secondary Processor or loss or invalid message of SPI communication from the Primary Processor after a valid message was received by the Secondary Processor	Loss or invalid message at initialization detected or loss or invalid message after a valid message was recieved			In the secondary processor, 20 / 200 counts intermittent or 0.1875 s continuous; 0.4750 s continuous @ initialization. 12.5 ms /count in the ECM secondary processor	
			Checks for stack over or underflow in secondary processor by looking for corruption of known pattern at stack boundaries. Checks number of stack over/ under flow since last powerup reset >=	5		KeMEMD_b_StackLimitTestEnbl == 1 Value of KeMEMD_b_StackLimitTestEnbl is: 1 . (If 0, this test is disabled)	variable, depends on length of time to corrupt stack	
			MAIN processor is verified by responding to a seed sent from the secondary with a key response to secondary. Checks number of incorrect keys	2 incorrect seeds within 8 messages, 0.2000 seconds		ignition in Run or Crank	150 ms for one seed continually failing	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			received > or Secondary processor has not received a new within time limit					
			Time new seed not received exceeded			always running	0.450 seconds	
			MAIN processor receives seed in wrong order			always running	3 / 17 counts intermittent. 50 ms/count in the ECM main processor	
			2 fails in a row in the Secondary processor's ALU check			KePISD_b_ALU_TestEnbld == 1 Value of KePISD_b_ALU_TestEnbld is: 1 . (If 0, this test is disabled)	25 ms	
			2 fails in a row in the Secondary processor's configuration register masks versus known good data			KePISD_b_ConfigRegTestEnbld == 1 Value of KePISD_b_ConfigRegTestEnbld is: 1 . (If 0, this test is disabled)	12.5 to 25 ms	
			Secondary processor detects an error in the toggling of a hardware discrete line controlled by the MAIN processor: number of discrete changes > = or < = over time window(50ms)	7 17		KePISD_b_MainCPU_SOH_FltEnbld == 1 Value of KePISD_b_MainCPU_SOH_FltEnbld is: 0 . (If 0, this test is disabled) time from initialization >= 0.4875 seconds	50 ms	
			Software background task first pass time to complete exceeds			Run/Crank voltage > 6.41	360.000 seconds	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			2 fails in a row in the MAIN processor's ALU check			KePISD_b_ALU_TestEnbld == 1 Value of KePISD_b_ALU_TestEnbld is: 1 . (If 0, this test is disabled)	25 ms	
			2 fails in a row in the MAIN processor's configuration register masks versus known good data			KePISD_b_ConfigRegTestEnbld == 1 Value of KePISD_b_ConfigRegTestEnbld is: 1 . (If 0, this test is disabled)	12.5 to 25 ms	
			Checks number of stack over/under flow since last powerup reset >=	3		KeMEMD_b_StackLimitTestEnbl == 1 Value of KeMEMD_b_StackLimitTestEnbl is: 1 . . (If 0, this test is disabled)	variable, depends on length of time to corrupt stack	
			Voltage deviation >	0.4950		KePISD_b_A2D_CnvrtrTestEnbld == 1 Value of KePISD_b_A2D_CnvrtrTestEnbld is: 1 . (If 0, this test is disabled)	5 / 10 counts or 0.150 seconds continuous; 50 ms/count in the ECM main processor	
			Checks for ECC (error correcting code) circuit test errors reported by the hardware for flash memory. Increments counter during controller initialization if ECC error occured since last controller initialization. Counter >=	3 (results in MIL), 5 (results in MIL and remedial action)		KeMEMD_b_FlashECC_CktTestEnbl == 1 Value of KeMEMD_b_FlashECC_CktTestEnbl is: 1 . (If 0, this test is disabled)	variable, depends on length of time to access flash with corrupted memory	
			Checks for ECC (error	3 (results in MIL),		KeMEMD_b_RAM_ECC_	variable,	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			correcting code) circuit test errors reported by the hardware for RAM memory circuit. Increments counter during controller initialization if ECC error occured since last controller initialization. Counter >=	5 (results in MIL and remedial action)		CktTestEnbl == 1 Value of KeMEMD_b_RAM_ECC_CktTestEnbl is: 1 . (If 0, this test is disabled)	depends on length of time to write flash to RAMvariable, depends on length of time to write flash to RAM	
			MAIN processor DMA transfer from Flash to RAM has 1 failure			KePISD_b_DMA_XferTestEnbld == 1 Value of KePISD_b_DMA_XferTestEnbld is: 0 . (If 0, this test is disabled)	variable, depends on length of time to write flash to RAM	
			Safety critical software is not executed in proper order.	>= 1 incorrect sequence.		KaPISD_b_ProgSeqWatchEnbl[x][y] == 1 Value of KaPISD_b_ProgSeqWatchEnbl[x][y] is: 1 (If 0, this test is disabled)	Fail Table, f(Loop Time). See supporting tables: **P0606_PSW Sequence Fail f (Loop Time)** / Sample Table, f (Loop Time)See supporting tables: **P0606_PSW Sequence Sample f(Loop Time)** counts 50 ms/count in the ECM main processor	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			MAIN processor determines a seed has not changed within a specified time period within the 50ms task.	Previous seed value equals current seed value.		KePISD_b_SeedUpdKeyStorFltEnbl == 1 Value of KePISD_b_SeedUpdKeyStorFltEnbl is: 1 . (If 0, this test is disabled)	Table, f(Loop Time). See supporting tables: **P0606_Last Seed Timeout f (Loop Time)**	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Starter Relay Control Circuit Open (Conventional)	P0615	Controller specific output driver circuit diagnoses the Starter relay (Conventional) high sided driver for an open circuit failure when the output is powered on by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates open circuit failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for an open circuit.	>= 200 KOhms impedance between signal and controller ground.	Starter control diag enable Engine speed Run Crank voltage	Enabled >= 0.00 RPM >= 11.00 volts	40 failures out of 50 samples 50 ms / sample	Type C, No SVS

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Starter Relay Control Circuit Low Voltage (Conventional)	P0616	Controller specific output driver circuit diagnoses the Starter relay (Conventional) high sided driver for a short to ground failure when the output is powered on by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to ground failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to ground.	<= 0.5 Ohms impedance between signal and controller ground	Starter control diag enable Engine speed Run Crank voltage	Enabled >= 0.00 RPM >= 6.41 volts	8 failures out of 10 samples 50 ms / sample	Type C, No SVS

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Starter Relay Control Circuit High Voltage (Conventional)	P0617	Controller specific output driver circuit diagnoses the Starter Relay high sided driver for a short to power failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver off state indicates short to power failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to power.	<= 0.5 Ohms impedance between signal and controller power	Starter control diag enable = TRUE Engine speed Run Crank voltage	Enabled >= 0.00 RPM >= 6.41 volts	40 failures out of 50 samples 50 ms / sample	Type C, No SVS

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Pump Relay Control Circuit Low Voltage	P0628	Controller specific output driver circuit diagnoses the Feed Fuel Pump Relay high sided driver for a short to ground failure when the output is powered on by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to ground failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to ground.	<= 0.5 Ohms impedance between signal and controller ground	Run/Crank Voltage Engine Speed	Voltage 11.00 volts 0 RPM	8 failures out of 10 samples 250 ms / sample	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Powertrain Internal Control Module EEPROM Error	P062F	This DTC detects a NVM long term performance. There are two types of diagnostics that run during controller power up. One for HWIO reports that writing to NVM (at shutdown) will not succeed, and the other HWIO reports the assembly calibration integrity check has failed.	HWIO reports that writing to NVM (at shutdown) will not succeed				Diagnostic runs at controller power up.	Type B, 2 Trips
			HWIO reports the assembly calibration integrity check has failed				Diagnostic runs at controller power up.	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
VIN Not Programmed or Mismatched - Engine Control Module (ECM)	P0630	This DTC checks that the VIN is correctly written	At least one of the programmed VIN digits	= 00 or FF	OBD Manufacturer Enable Counter	= 0	250 ms / test Continuous	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
5 Volt Reference #1 Circuit	P0641	Detects a continuous or intermittent short on the 5 volt reference circuit #1 by monitoring the reference percent Vref1 and failing the diagnostic when the percent Vref1 is too low or too high or if the delta between the filtered percent Vref1 and non-filtered percent Vref1 is too large. This diagnostic only runs when battery voltage is high enough.	ECM percent Vref1 < or ECM percent Vref1 > or the difference between ECM filtered percent Vref1 and percent Vref1 >	4.875 % Vref1 5.125 % Vref1 0.0495 % Vref1	Diagnostic enabled AND [(Run/Crank voltage for Time period AND Starter engaged) OR (Run/Crank voltage AND Starter engaged)]	= 1 > 6.41 Volts = 0.02 Seconds = FALSE > 8.41 Volts = TRUE	19 / 39 counts; or 0.1875 sec continuous; 12.5 ms/count in main processor	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Malfunction Indicator Lamp (MIL) Control Circuit (ODM) Open	P0650	Detects an inoperative malfunction indicator lamp control low side driver circuit. This diagnostic reports the DTC when an open circuit is detected.	Voltage low during driver off state (indicates open circuit)	Open circuit: ≥ 200 K Ω impedance between signal and controller ground	Run/Crank Voltage Remote Vehicle Start is not active	Voltage ≥ 11.00 volts	1 failures out of 1 samples 50 ms / sample	Type B, No MIL NO MIL Note: In certain controllers P263A may also set (MIL Control Short to Ground)

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
5 Volt Reference #2 Circuit	P0651	Detects a continuous or intermittent short on the 5 volt reference circuit #2 by monitoring the reference percent Vref2 and failing the diagnostic when the percent Vref2 is too low or too high or if the delta between the filtered percent Vref2 and non-filtered percent Vref2 is too large. This diagnostic only runs when battery voltage is high enough.	ECM percent Vref2 < or ECM percent Vref2 > or the difference between ECM filtered percent Vref2 and percent Vref2 >	4.875 % Vref2 5.125 % Vref2 0.0495 % Vref2	Diagnostic enabled AND [(Run/Crank voltage for Time period AND Starter engaged) OR (Run/Crank voltage AND Starter engaged)]	= 1 > 6.41 Volts = 0.02 Seconds = FALSE > 8.41 Volts = TRUE	19 / 39 counts; or 0.1875 sec continuous; 12.5 ms/count in main processor	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Powertrain Relay Control (ODM) Open	P0685	Detects an open circuit in the Powertrain Relay driver. This diagnostic reports the DTC when an open circuit failure is present. Monitoring occurs when the output is powered off. A decision is made by comparing a voltage measurement to a controller specific voltage threshold.	Voltage measurement outside of controller specific acceptable range during driver off state indicates open circuit failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for an open circuit.	Open Circuit: ≥ 200 K Ω ohms impedance between output and controller ground	Run/Crank Voltage	Voltage ≥ 11.00 volts	8 failures out of 10 samples 250 ms / sample	Type B, 2 Trips Note: In certain controllers P0686 may also set (Powertrain Relay Control Short to Ground).

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Powertrain Relay Control (ODM) Low	P0686	Detects a short to ground in the Powertrain Relay low side driver. This diagnostic reports the DTC when a short to ground failure is present. Monitoring occurs when the output is powered off. A decision is made by comparing a voltage measurement to a controller specific voltage threshold.	Voltage measurement outside of controller specific acceptable range during driver off state indicates short to ground failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to ground.	Short to ground: ≤ 0.5 Ω impedance between output and controller ground	Run/Crank Voltage	Voltage ≥ 11.00 volts	8 failures out of 10 samples 250 ms / sample	Type B, 2 Trips Note: In certain controllers P0685 may also set (Powertrain Relay Control Open Circuit).

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Powertrain Relay Control (ODM) High	P0687	Detects a short to power in the Powertrain Relay low side driver. This diagnostic reports the DTC when a short to power failure is present. Monitoring occurs when the output is powered off. A decision is made by comparing a voltage measurement to a controller specific voltage threshold.	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to power failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to power.	Short to power: ≤ 0.5 Ω impedance between output and controller power	Run/Crank Voltage	Voltage ≥ 11.00 volts	8 failures out of 10 samples 250 ms / sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Control Module Power Relay Feedback Circuit Low Voltage	P0689	Detects low voltage in the control module relay feedback circuit. This diagnostic reports the DTC when low voltage is present. Monitoring occurs when run crank voltage is above a calibrated value.	Control module relay feedback circuit low voltage	Powertrain relay voltage <= 5.00	Powertrain relay short low diagnostic enable Run Crank voltage Powertrain relay state	= 1.00 > 9.00 = ON	5 failures out of 6 samples 1000 ms / sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Powertrain Relay Feedback Circuit High	P0690	Detects higher than expected voltage in the powertrain relay feedback circuit. This diagnostic reports the DTC when higher than expected voltage is present. For example, the powertrain relay could be stuck on. Monitoring occurs when the relay is commanded "off" for a calibrated duration.	Powertrain Relay Voltage	>= 4.00 volts will increment the fail counter	Powertrain relay commanded “OFF” No active DTCs:	>= 2.00 seconds PowertrainRelayStateOn_FA	50 failures out of 63 samples 100ms / Sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cooling Fan 1 Relay Control Circuit Low Voltage (Output Driver Monitor)	P0691	Diagnoses the cooling fan 1 relay control low side driver circuit for circuit faults	Voltage low during driver off state (indicates short-to-ground)	Short to ground: ≤ 0.5 Ω impedance between signal and controller ground	Powertrain Relay Voltage	Voltage ≥ 11.00 volts	50.00 failures out of 63.00 samples 100 ms / sample	Type B, 2 Trips Note: In certain controllers P0480 may also set (Fan 1 Open Circuit).

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cooling Fan 1 Relay Control Circuit High Voltage (ODM)	P0692	Diagnoses the cooling fan 1 relay control low side driver circuit for circuit faults	Voltage high during driver on state (indicates short to power)	Short to power: ≤ 0.5 Ω impedance between signal and controller power	Powertrain Relay Voltage	Voltage ≥ 11.00 volts	50.00 failures out of 63.00 samples 100 ms / sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cooling Fan 2 Relay Control Circuit Low Voltage (ODM)	P0693	Diagnoses cooling fan 2 relay control low side driver circuit for circuit faults	Voltage low during driver off state (indicates short-to-ground)	Short to ground: ≤ 0.5 Ω impedance between signal and controller ground	Powertrain Relay Voltage	Voltage ≥ 11.00 volts	50.00 failures out of 63.00 samples 100 ms / sample	Type B, 2 Trips Note: In certain controllers P0481 may also set (Fan 2 Open Circuit).

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cooling Fan 2 Relay Control Circuit High Voltage (ODM)	P0694	Diagnoses the cooling fan 2 relay control low side driver circuit for circuit faults	Voltage high during driver on state (indicates short to power)	Short to power: ≤ 0.5 Ω impedance between signal and controller power	Powertrain Relay Voltage	Voltage ≥ 11.00 volts	50.00 failures out of 63.00 samples 100 ms / sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
5 Volt Reference #3 Circuit	P0697	Detects a continuous or intermittent short on the 5 volt reference circuit #3 by monitoring the reference percent Vref3 and failing the diagnostic when the percent Vref3 is too low or too high or if the delta between the filtered percent Vref3 and non-filtered percent Vref3 is too large. This diagnostic only runs when battery voltage is high enough.	ECM percent Vref3 < or ECM percent Vref3 > or the difference between ECM filtered percent Vref3 and percent Vref3 >	4.875 % Vref3 5.125 % Vref3 0.0495 % Vref3	Diagnostic enabled AND [(Run/Crank voltage for Time period AND Starter engaged) OR (Run/Crank voltage AND Starter engaged)]	= 1 > 6.41 Volts = 0.02 Seconds = FALSE > 8.41 Volts = TRUE	19 / 39 counts; or 0.1875 sec continuous; 12.5 ms/count in main processor	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
5 Volt Reference #4 Circuit	P06A3	Detects a continuous or intermittent short on the 5 volt reference circuit #4 by monitoring the reference percent Vref4 and failing the diagnostic when the percent Vref4 is too low or too high or if the delta between the filtered percent Vref4 and non-filtered percent Vref4 is too large. This diagnostic only runs when battery voltage is high enough.	ECM percent Vref4 < or ECM percent Vref4 > or the difference between ECM filtered percent Vref4 and percent Vref4 >	4.875 % Vref4 5.125 % Vref4 0.0495 % Vref4	Diagnostic enabled AND [(Run/Crank voltage for Time period AND Starter engaged) OR (Run/Crank voltage AND Starter engaged)]	= 1 > 6.41 Volts = 0.02 Seconds = FALSE > 8.41 Volts = TRUE	19 / 39 counts; or 0.1875 sec continuous; 12.5 ms/count in main processor	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Internal Control Module Knock Sensor Processor 1 Performance	P06B6	This diagnostic checks for a fault with the internal test circuit (sensor #1) used only for the '20 kHz' method of the Open Circuit Diagnostic. A fault is present when the signal level from the 20 kHz range of the FFT output falls between the Open Test Circuit thresholds.	FFT Diagnostic Output	> **P06B6_P06B7_OpenTestCktThrshMin** **AND** < **P06B6_P06B7_OpenTestCktThrshMax** **See Supporting Tables**	Diagnostic Enabled? Engine Run Time Engine Speed Cumlative Number of Engine Revs (per key cycle) within min/max Engine Speed enable (above) Engine Air Flow	Yes ≥ 2.0 seconds > 600 RPM and < 6,750 RPM ≥ 200 Revs ≥ 40 mg/cylinder and ≤ 2,000 mg/cylinder	First Order Lag Filter with Weight Coefficient Weight Coefficient = 0.0100 Updated each engine event	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Two Stage Oil Pump Control Circuit Open	P06DA	Controller specific output driver circuit diagnoses the two stage oil pump low sided driver for an open circuit failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver off state indicates open circuit failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for an open circuit.	Open Circuit ≥ 200 k Ω impedance between output and controller ground	Diagnostic Status Powertrain Relay Voltage Run/Crank Active Cranking State	Enabled ≥ 11.00 = True = False	>= 40 errors out of 50 samples. Performed every 100 msec	Type B, 2 Trips Note: In certain controllers P06DB may also set (Two Stage Oil Pump Control Circuit Short To Ground)

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Two Stage Oil Pump Control Circuit Short To Ground	P06DB	Controller specific output driver circuit diagnoses the two stage oil pump low sided driver for a short to ground failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver off state indicates short to ground failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to ground.	Short to Ground Circuit ≤ 0.5 Ω impedance between output and controller ground	Diagnostic Status Powertrain Relay Voltage Run/Crank Active Cranking State	Enabled ≥ 11.00 = True = False	>= 40 errors out of 50 samples. Performed every 100 msec	Type A, 1 Trips Note: In certain controllers P06DA may also set (Two Stage Oil Pump Control Circuit Open)

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Two Stage Oil Pump Control Circuit Short To Power	P06DC	Controller specific output driver circuit diagnoses the two stage oil pump low sided driver for a short to power failure when the output is powered on by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to power failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to power.	Short to Power ≤ 0.5 Ω impedance between output and controller power	Diagnostic Status Powertrain Relay Voltage Run/Crank Active Cranking State	Enabled ≥ 11.00 = True = False	>= 40 errors out of 50 samples. Performed every 100 msec	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Two Stage Oil Pump Control Circuit Performance - Two Sided	P06DD	Diagnoses the two stage oil pump is stuck in the high pressure state. This diagnostic includes an intrusive test and a passive test. Intrusive test: The oil pump control is cycled off (high pressure) and on (low pressure) Y = 15 times at calibratable intervals. If a change in oil pressure above a calibration is not detected then the oil pressure is checked to determine if it is stuck. It takes X-out-of-Y failures to fail and set the appropriate code. Passive test: After the intrusive test passes, then a passive test will begin to run. The passive test will monitor the oil pressure changes associated with oil pump control state changes. If the passive test determines that the oil pressure change was less then desired then the intrusive test is retriggered.	Fail from passing state: Oil Pressure delta is less than a minimum delta pressure on a state change and the measured filtered oil pressure is above a threshold	Oil Pressure delta = ABS [Filtered Oil Pressure at beginning of state change - filtered oil pressure after 1.0 seconds] Oil Pressure delta < **P06DD_P06DE_OP_StateChangeMin** AND Filtered Oil Pressure ≥ (**P0521_P06DD_P06DE_OP_HiStatePressure** + **P0521_P06DD_P06DE_OP_LoStatePressure**) ÷ 2 (see P06DD details on Supporting Tables Tab **P06DD_P06DE_OP_StateChangeMin** **P0521_P06DD_P06DE_OP_HiStatePressure** **P0521_P06DD_P06DE_OP_LoStatePressure**)	Common Criteria: Two Stage Oil Pump is Present Engine Running Ambient Air Pressure Oil Aeration (= TRUE if engine speed > 10,000 RPM for longer than 30.0 seconds) No active DTC's for diagnsotic enable: Check oil pump TFTKO as a diagnostic enable when Enabled. No active DTC's for control enable: Active Criteria: One Sided Performance Test = Disabled	 TRUE ≥ 10.0 seconds ≥ 70.0 kPa FALSE Fault bundles: MAF_SensorFA ECT_Sensor_FA IAT_SensorFA CrankSensor_FA EngOilPressureSensorCktFA AmbientAirDefault EngOilTempFA OilPmpTFTKO Enabled : OilPmpTFTKO Enabled Fault bundles for control disable : OilPmpTFTKO EngineTorqueEstInaccurate EngOilPressureSensorFA PowertrainRelayFault CrankSensor_FA EngOilTempFA Disabled	≥ 12 errors out of 15 samples. Run once per trip or activiated by the Passive Test	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Oil Pump in Low State	> 1.0 seconds		
					Modelled Oil Temperature within range	70.0 deg C ≤ Oil Temp ≤ 100.0 deg C		
					Filtered Engine Speed within range	1,200 RPM ≤ Filtered Engine Speed ≤ 2,500 RPM		
					Delta Filtered Engine Speed within a range	ABS [Filtered RPM at beginning of State change - Filtered RPM after 1.0 seconds] ≤ 50 RPM		
					Engine Torque within range	**P06DD_P06DE_MinEnableTorque_OP** ≤ Indicated Requested Engine Torque ≤ **P06DD_P06DE_MaxEnableTorque_OP** (see P06DD details on Supporting Tables Tab **P06DD_P06DE_MinEnableTorque_OP** **P06DD_P06DE_MaxEnableTorque_OP**)		
					Filtered Oil Pressure within range	Filtered Engine Oil Pressure > **P06DD_P06DE_MinOilPressThresh** (see P06DD details on Supporting Tables Tab **P06DD_P06DE_MinOilPressThresh**)		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Expected Oil Pressure Delta within range <u>Passive Criteria:</u> Active Test Passed Filtered Engine Speed within range Modelled Oil Temperature within range Delta Filtered Engine Speed within a range Oil Pressure Delta within a range	30.0 kPa < ABS [**P0521_P06DD_P06DE_ OP_HiStatePressure** - **P0521_P06DD_P06DE_ OP_LoStatePressure**] < 250.0 kPa TRUE 1,000 RPM ≤ Filtered Engine Speed ≤ 4,500 RPM 40.0 deg C ≤ Oil Temp ≤ 120.0 deg C ABS [Filtered RPM at beginning of State change - Filtered RPM after 1.00 seconds] ≤ 1,000 RPM Oil Pressure Delta < **P06DD_P06DE_OP_Stat eChangeMin** (see P06DD details on Supporting Tables Tab **P06DD_P06DE_OP_Stat eChangeMin**)		
			<u>Fast Pass Condition</u> Oil Pressure delta is less than a minimum delta pressure on a state change and the measured filtered oil pressure is	Oil Pressure delta = ABS [Filtered Oil Pressure at beginning of state change -	<u>Common Criteria:</u> Two Stage Oil Pump is Present Engine Running	TRUE ≥ 10.0 seconds	0 errors out of 5 samples. Run once per trip or activiated by the Passive Test	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			above a threshold	filtered oil pressure after 1.0 seconds] Oil Pressure delta < **P06DD_P06DE_OP_StateChangeMin** AND Filtered Oil Pressure ≥ (**P0521_P06DD_P06DE_OP_HiStatePressure** - **P0521_P06DD_P06DE_OP_LoStatePressure**) ÷ 2 (see P06DD details on Supporting Tables Tab **P06DD_P06DE_OP_StateChangeMin** **P0521_P06DD_P06DE_OP_HiStatePressure** **P0521_P06DD_P06DE_OP_LoStatePressure**)	Ambient Air Pressure Oil Aeration (= TRUE if engine speed > 10,000 RPM for longer than 30.0 seconds) No active DTC's for diagnsotic enable: Check oil pump TFTKO as a diagnostic enable when Enabled. No active DTC's for control enable: <u>Active Criteria:</u> One Sided Performance Test = Disabled Oil Pump in Low State Modelled Oil Temperature within range Filtered Engine Speed within range	≥ 70.0 kPa FALSE Fault bundles: MAF_SensorFA ECT_Sensor_FA IAT_SensorFA EngOilPressureSensorCktFA AmbientAirDefault EngOilTempFA OilPmpTFTKO CrankSensor_FA Enabled : OilPmpTFTKO Enabled Fault bundles for control disable : OilPmpTFTKO EngineTorqueEstInaccurate EngOilPressureSensorFA PowertrainRelayFault CrankSensor_FA EngOilTempFA Disabled > 1.0 seconds 70.0 deg C ≤ Oil Temp ≤ 100.0 deg C 1,200 RPM ≤ Filtered Engine Speed ≤ 2,500		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
						RPM		
					Engine Torque within range	**P06DD_P06DE_MinEnableTorque_OP** ≤ Indicated Requested Engine Torque ≤ **P06DD_P06DE_MaxEnableTorque_OP** (see P06DD details on Supporting Tables Tab **P06DD_P06DE_MinEnableTorque_OP** **P06DD_P06DE_MaxEnableTorque_OP**)		
					Delta Filtered Engine Speed within a range	ABS [Filtered RPM at beginning of State change - Filtered RPM after 1.0 seconds] ≤ 50 RPM		
					Filtered Oil Pressure within range	Filtered Engine Oil Pressure > **P06DD_P06DE_MinOilPressThresh** (see P06DD details on Supporting Tables Tab **P06DD_P06DE_MinOilPressThresh**)		
					Expected Oil Pressure Delta within range	30.0 kPa < ABS [**P0521_P06DD_P06DE_OP_HiStatePressure** - **P0521_P06DD_P06DE_OP_LoStatePressure**] < 250.0 kPa		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Two Stage Oil Pump Control Circuit StuckOn - Two Sided	P06DE	Diagnoses the two stage oil pump is stuck in the low pressure state. This diagnostic includes an intrusive test and a passive test. Intrusive test: The oil pump control is cycled off (high pressure) and on (low pressure) Y times at calibratable intervals. If a change in oil pressure above a calibration is not detected then the oil pressure is checked to determine if it is stuck. It takes X-out-of-Y failures to fail and set the appropriate code. Passive test: After the intrusive test passes, then a passive test will begin to run. The passive test will monitor the oil pressure changes associated with oil pump control state changes. If the passive test determines that the oil pressure change was less then desired then the intrusive test is retriggered.	Fail from a passing state: Oil Pressure delta is less than a minimum delta pressure on a state change and the measured filtered oil pressure is below a threshold	Oil Pressure delta = ABS [Filtered Oil Pressure at beginning of state change - filtered oil pressure after 1.0 seconds] Oil Pressure delta < **P06DD_P06DE_OP_StateChangeMin** (see P06DE details on Supporting Tables Tab) Filtered Oil Pressure ≤ **P0521_P06DD_P06DE_OP_HiStatePressure** **-** **P0521_P06DD_P06DE_OP_LoStatePressure** **) ÷ 2** (see P06DE details on Supporting Tables Tab)	Common Criteria: Two Stage Oil Pump is Present Engine Running Ambient Air Pressure Oil Aeration (= TRUE if engine speed > 10,000 RPM for longer than 30.0 seconds) No active DTC's for diagnsotic enable: Check oil pump TFTKO as a diagnostic enable when Enabled. No active DTC's for control enable: Active Criteria: One Sided Performance	TRUE ≥ 10.0 seconds ≥70.0 kPa FALSE Fault bundles: MAF_SensorFA ECT_Sensor_FA IAT_SensorFA CrankSensor_FA EngOilPressureSensorCktFA AmbientAirDefault EngOilTempFA Enabled : OilPmpTFTKO Enabled Fault bundles for control disable : OilPmpTFTKO EngineTorqueEstInaccurate EngOilPressureSensorFA PowertrainRelayFault CrankSensor_FA EngOilTempFA Disabled	≥ 12 errors out of 15 samples. Run once per trip or activiated by the Passive Test	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Test = Disabled			
					Oil Pump in Low State	> 1.0 seconds		
					Modelled Oil Temperature within range	70.0 deg C ≤ Oil Temp ≤ 100.0 deg C		
					Filtered Engine Speed within range	1,200 RPM ≤ Filtered Engine Speed ≤ 2,500 RPM		
					Engine Torque within range	**P06DD_P06DE_MinEnableTorque_OP** ≤ Indicated Requested Engine Torque ≤ **P06DD_P06DE_MaxEnableTorque_OP** (see P06DE details on Supporting Tables Tab)		
					Delta Filtered Engine Speed within a range	ABS [Filtered RPM at beginning of State change - Filtered RPM after 1.0 seconds] ≤ 50 RPM		
					Filtered Oil Pressure within range	Filtered Engine Oil Pressure > **P06DD_P06DE_MinOilPressThresh** (see P06DD details on Supporting Tables Tab)		
					Expected Oil Pressure Delta within range	30.0 kPa < ABS [**P0521_P06DD_P06DE_OP_HiStatePressure** - **P0521_P06DD_P06DE_OP_LoStatePressure**] < 250.0 kPa		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Passive Criteria: Active Test Passed Filtered Engine Speed within range Modelled Oil Temperature within range Delta Filtered Engine Speed within a range Oil Pressure Delta < **P06DD_P06DE_OP_StateChangeMin** (see P06DE details on Supporting Tables Tab)	 TRUE 1,000 RPM ≤ Filtered Engine Speed ≤ 4,500 RPM 40.0 deg C ≤ Oil Temp ≤ 120.0 deg C ABS [Filtered RPM at beginning of State change - Filtered RPM after 1.00 seconds] ≤ 1,000 RPM TRUE		
			Fast Pass Condition Oil Pressure delta is less than a minimum delta pressure on a state change and the measured filtered oil pressure is below a threshold	Oil Pressure delta = ABS [Filtered Oil Pressure at beginning of state change - filtered oil pressure after 1.0 seconds] Oil Pressure delta <	Common Criteria: Two Stage Oil Pump is Present Engine Running Ambient Air Pressure Oil Aeration (= TRUE if engine speed	 TRUE ≥ 10.0 seconds ≥ 70.0 kPa FALSE	0 errors out of 5 samples. Run once per trip or activiated by the Passive Test	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
				P06DD_P06DE_OP_StateChangeMin (P06DD Performance Test Details on Supporting Tables Tab) Filtered Oil Pressure ≤ **P0521_P06DD_P06DE_OP_HiStatePressu** (**re** - **P0521_P06DD_P06DE_OP_LoStatePressure**) / 2 (P06DD Performance Test Details on Supporting Tables Tab)	> 10,000 RPM for longer than 30.0 seconds) No active DTC's for diagnsotic enable: Check oil pump TFTKO as a diagnostic enable when Enabled. No active DTC's for control : Active Criteria: One Sided Performance Test = Disabled Oil Pump in Low State Modelled Oil Temperature within range Filtered Engine Speed within range Engine Torque within range	Fault bundles: MAF_SensorFA ECT_Sensor_FA IAT_SensorFA CrankSensor_FA EngOilPressureSensorCktFA AmbientAirDefault EngOilTempFA Enabled : OilPmpTFTKO Enabled Fault bundles for control disable : OilPmpTFTKO EngineTorqueEstInaccurate EngOilPressureSensorFA PowertrainRelayFault CrankSensor_FA EngOilTempFA Disabled > 1.0 seconds 70.0 deg C ≤ Oil Temp ≤ 100.0 deg C 1,200 RPM ≤ Filtered Engine Speed ≤ 2,500 RPM **P06DD_P06DE_MinEnableTorque_OP** ≤		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
						Indicated Requested Engine Torque ≤ **P06DD_P06DE_MaxEnableTorque_OP** (P06DD Performance Test Details on Supporting Tables Tab)		
					Delta Filtered Engine Speed within a range	ABS [Filtered RPM at beginning of State change - Filtered RPM after 1.0 seconds] ≤ 50 RPM		
					Filtered Oil Pressure within range	Filtered Engine Oil Pressure > **P06DD_P06DE_MinOilPressThresh** (see P06DD details on Supporting Tables Tab)		
					Expected Oil Pressure Delta within range	30.0 kPa < ABS [**P0521_P06DD_P06DE_OP_HiStatePressure** - **P0521_P06DD_P06DE_OP_LoStatePressure**] < 250.0 kPa		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Traction Control Torque Request Circuit	P0856	Determines if torque request from the EBCM is valid	Serial Communication 2's complement message - ($1C7/$1C9 for engine torque, $1CA/$1C6 for axle torque)	Message <> 2's complement of message	Active Communication Power Mode Engine Running Status of traction in GMLAN message ($4E9)	Serial data has been received = Run = True = Traction Present	>= 6 failures out of 10 Performed on every received message	Type C, No SVS Emissions Neutral Diagnostic - Type C
			OR Serial Communication message ($1C7/$1C9 for engine torque, $1CA/ $1C6 for axle torque) rolling count index value	Message rolling count value <> previous message rolling count value plus one	Ignition Voltage Run/Crank Active	> 6.41 volts > 0.50 seconds	6 rolling count failures out of 10 samples Performed on every received message	
			OR Too many minimum limit torque request transitions occur from TRUE to FALSE to TRUE within a time period	Requested torque intervention type toggles from not increasing request to increasing request			>= 3 multi-transitions out of 5 samples. Performed every 200 ms	
			Torque request greater than torque request diagnostic maximum threshold	> 250 Nm for engine torque based traction torque system, OR > 4,000 Nm for axle torque based traction torque system			>= 4 out of 10 samples Performed on every received message	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
O2 Sensor Heater Supply Voltage Sense Circuit Range/ Performance	P103B	The P103B diagnostic determines if the heater supply circuit is rational by comparing the heater supply voltage to the run crank voltage and calculating the difference. The heater supply voltage input is connected to the O2 heater supply circuit inside the vehicle relay center. It is representative of the voltage supplied to the O2 heaters. The O2 heater voltage is used by the HWIO to calculate the O2 heater resistance on switching type O2 sensors (non-WRAF). With a fault set, the resistance calculation is performed with run crank voltage. The diagnostic failure counter is incremented if the voltage difference is greater than the threshold. This DTC is set based on the fail and sample counters.	The absolute value of Heater Supply Voltage delta from Run Crank voltage	> 2.00 volts	Powertrain relay in range (Relay in range is defined as relay voltage Run Crank signal active	= True > 11.00 volts) = True (Please see "**Run/Crank Active conditiions**" in Supporting Tables)	8 failures out of 10 samples 250 ms / sample Continuous	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
O2 Sensor Heater Supply Voltage Sense Circuit Low	P103C	The P103C diagnostic determines if the heater supply circuit is low by comparing the heater supply voltage to the threshold. The heater supply voltage input is connected to the O2 heater supply circuit inside the vehicle relay center. It is representative of the voltage supplied to the O2 heaters. The O2 heater voltage is used by the HWIO to calculate the O2 heater resistance on switching type O2 sensors (non-WRAF). With a fault set, the resistance calculation is performed with run crank voltage. The diagnostic failure counter is incremented if the heater supply voltage is less than the threshold. This DTC is set based on the fail and sample counters.	Heater Supply Voltage	< 8.00 volts	Powertrain relay in range (Relay in range is defined as relay voltage Run Crank signal active	= True > 11.00 volts) = True (Please see "**Run/Crank Active conditiions**" in Supporting Tables)	8 failures out of 10 samples 250 ms / sample Continuous	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Inlet Airflow System Performance (naturally aspirated)	P1101	Detects a performance failure in the Manifold Pressure (MAP) sensor, Throttle Position sensor (TPS) or Mass Air Flow (MAF) sensor that cannot be uniquely identified as a failure in one individual sensor. This diagnostic can set when more than one of these sensors has a performance concern. This diagnostic is performed using the Intake Flow Rationality Diagnostic (IFRD). IFRD calculates modeled values of sensors from these three sensors. These modeled values are compared against the actual sensor values to see if they are similar. If they are similar, then the model passes. If they are not similar, then that model is considered to be failed. Certain combinations of model passes and model failures can be interpreted to be caused by a performance issue with the system, but no	Filtered Throttle Model Error AND ABS(Measured Flow – Modeled Air Flow) Filtered OR ABS(Measured MAP – MAP Model 1) Filtered AND ABS(Measured MAP – MAP Model 2) Filtered	> 130 kPa*(g/s) > 11.0 grams/sec > 19.0 kPa) > 19.0 kPa	Engine Speed Engine Speed (Coolant Temp OR OBD Coolant Enable Criteria (Coolant Temp OR OBD Max Coolant Achieved Intake Air Temp Intake Air Temp Minimum total weight factor (all factors multiplied together) See Residual Weight Factor tables.	>= 400 RPM <= 6,500 RPM >= -9 Deg C = TRUE) <= 130 Deg C = FALSE) >= -20 Deg C <= 125 Deg C >= 0.50 Filtered Throttle Model Error multiplied by **P0101, P0106, P0121, P012B, P0236, P1101: TPS Residual Weight Factor based on RPM** Modeled Air Flow Error multiplied by **P0101, P0106, P010B, P0121, P012B, P0236, P1101: MAF1 Residual Weight Factor based on RPM** and **P0101, P0106, P010B, P0121, P012B, P0236, P1101: MAF1 Residual Weight Factor based on MAF Est**	Continuous Calculation are performed every 12.5 msec	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		single failed sensor can uniquely be identified. In this case, the Inlet Airflow System Performance diagnostic will fail.				MAP Model 1 Error multiplied by **P0101, P0106, P0121, P012B, P0236, P1101: MAP1 Residual Weight Factor based on RPM** MAP Model 2 Error multiplied by **P0101, P0106, P0121, P012B, P0236, P1101: MAP2 Residual Weight Factor based on RPM**		
					No Active DTCs:	MAP_SensorCircuitFA EGRValvePerformance_FA MAF_SensorCircuitFA CrankSensor_FA ECT_Sensor_FA IAT_SensorFA		
					No Pending DTCs:	EGRValve_FP ECT_Sensor_Ckt_FP IAT_SensorCircuitFP		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cold Start Emissions Reduction System Fault	P1400	Model based test computes power from exhaust flow and thermal energy resulting from elevated idle speed and retarded spark advance. Detects if the cold start emission reduction system has failed resulting in the delivered power being out of range.	Average desired accumulated exhaust power - Average actual accumulated exhaust power (too much energy delivered to catalyst) Average desired accumulated exhaust power - Average actual accumulated exhaust power (too little energy delivered to catalyst) (EWMA filtered) Average Power = output of **P1400_EngineSpeedResidual_Table** * output of **P1400_SparkResidual_Table** NOTE: Desired accumulated power would use the desired catalyst light off spark and desired engine speed and the actual accumuated power would use the final commanded spark and actual engine speed. Refer to the Supporting Tables for details	< -32.00 KJ/s (high RPM failure mode) > 5.00 KJ/s (low RPM failure mode)	To enable the diagnostic, the Cold Start Emission Reduction Strategy must be Active per the following: Catalyst Temperature AND Engine Coolant AND Engine Coolant AND Barometric Pressure The Cold Start Emission Reduction strategy must not be exiting. The strategy will exit per the following: Catalyst Temperature AND Engine Run Time OR Engine Run Time OR Barometric Pressure	< 350.00 degC > 16.00 degC <= 50.00 degC >= 70.00 KPa >= 900.00 degC >= 20.00 seconds > **P1400_CatalystLightOffExtendedEngineRunTimeExit** This Extended Engine run time exit is a function of percent ethanol and Catmons NormRatioEWMA. Refer to "Supporting Tables" for details. < 70.00 KPa	Runs once per trip when the cold start emission reduction strategy is active Frequency: 100ms Loop Test completes after 10 seconds of accumulated qualified data.	EWMA Based - Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Other Enable Criteria:			
					OBD Manufacturer Enable Counter	0		
					Vehicle Speed	< 1.24 MPH		
					Allow diagnostic to calculate residual in an off-idle state. If the value of the OffIdleEnable is equal to 1 then the "DriverOffAccelPedal" will not be checked. However, if the value of OffIdleEnable is 0 then driver must be off the accel pedal	0 (A value of 1 allows diagnostic to run and calculate the residual while off idle. A value of 0 requires calculation of the residual at idle)		
					A change in throttle position (tip-in/tip-out) will initiate a delay in the calculation of the average qualified residual value. Therefore when the:			
					Pedal Close Delay Timer	> 5.00 seconds		
					the diagnostic will continue the calculation.			
					A change in gear will initiate a delay in the calculation of the average qualified residual value to			

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					allow time for the actual engine speed and actual final commanded spark to achieve their desired values. Therefore, when the:			
					Gear Shift Delay Timer	> 2.00 seconds		
					the diagnostic will continue the calculation			
					For Manual Transmission vehicles:			
					Clutch Pedal Position	> 12.00 %		
					Clutch Pedal Position	< 75.00 %		
					The diagnostic will delay calculation of the residual value and potentially weight the residual calculation differently based on engine run time. This is to ensure the diagnostic is operating in idle speed control as well as during the peak catalyst light off period.			
					The time weighting factor must be :	> 0 These are scalar values that are a function of engine run time. Refer to		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
						P1400_ColdStartDiagnosticDelayBasedOnEngineRunTime and the cal axis, **P1400_ColdStartDiagnosticDelayBasedOnEngineRunTimeCalAxis** in the "Supporting Tables" for details.		
					General Enable:			
					DTC's Not Set:	AcceleratorPedalFailure ECT_Sensor_FA IAT_SensorCircuitFA MnfdTempSensorCktFP CrankSensor_FA FuelInjectorCircuit_FA MAF_SensorFA MAP_SensorFA EngineMisfireDetected_FA ClutchPstnSnsr FA IAC_SystemRPM_FA IgnitionOutputDriver_FA TPS_FA VehicleSpeedSensor_FA 5VoltReferenceMAP_OOR_Flt TransmissionEngagedState_FA EngineTorqueEstInaccurate		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Transmission Engine Speed Request Circuit	P150C	This DTC monitors for an error in communication with the Transmission Engine Speed Request signal in $19D	Communication of the Alive Rolling Count or Protection Value in the Transmission Engine Speed signal over CAN bus is incorrect for out of total samples	 >= 8 counts >= 10 counts	Message frame All the following conditions are met for Power Mode Powertrain Relay Voltage Run/Crank Ignition Voltage	= Is available >= 3,000.00 milliseconds = Run >= 11.00 Volts >= 11.00 Volts	Executes in 25ms loop.	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Throttle Position Steady State Actuation Fault	P1516	Detect an inablity to maintain a steady state throttle position.	The absolute difference between desired and indicated throttle position is >	2.00 percent	Run/Crank voltage TPS minimum learn is not active AND Throttle is being Controlled Throttle is considered in a steady state condition when the desired throttle position over a 12.5 ms period is For a settling time period Ignition voltage failure is false	> 6.41 Volts < 0.25 percent > 4.00 seconds P1682	0.49 ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cruise Control Switch State Undertermined	P155A	Detects when cruise switch state cannot be determined, such as low voltage conditions "Emissions Neutral Default Action : When the BCM tells the ECM that the cruise switch “Data Invalid” (latched on/off switch architectures) or “Indeterminate” (momentary on/off switch architectures) is detected for too long, ECM sets the code and cruise control will be disabled and disengaged for the remainder of the key cycle regardless of current pass/fail condition once it fails."	cruise switch state is received as "undetermined" for greater than a calibratable time	fail continuously for greater than 0.5 seconds			fail continuously for greater than 0.5 seconds	Type C, No SVS , "Emissions Neutral Diagnostics – special type C"

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cruise Control Calibration Incorrect	P158A	Type of cruise in Body Control Module does not match that in the Engine Control Module for 2.5 seconds "Emissions Neutral Default Action : This diagnostic compares the BCM and the ECM configuration calibrations of whether No Cruise, Conventional Cruise Control, or ACC is available on the vehicle. If the calibration for the cruise system type in the ECM does not match the value in $4E9 signal Vehicle Speed Control System Type, a P158A DTC is set and cruise control is disabled."	Type of cruise system in GMLAN $4E9 does not match with that in the Engine Control Module for a fix time.	2.5 seconds	Diagnostic is Enabled. DID $40 from BCM says cruise system is present (ECM recieves programmble information from Body Control Module) OR ECM will not receive Programmable information for Cruise from Body Control Module	True	fail continuously for greater than 2.5 seconds.	Type C, No SVS "Emissions Neutral Diagnostics – Special Type C"

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Front Object Detection Control Module Torque Request Signal Message Counter Incorrect	P15F6	Detects rolling count or protection value errors in Collision Preparation System Axle Torque Command serial data signal "Emissions Neutral Default Action : When the ECM determines that a serial communication fault has occurred with the EOCM in frame $2CD, the code is set and the Collision Preparation System is disabled." Only applicable for applications with Full Speed Range Adaptive Cruise Control and Collision Preparation System feature.	If x of y rolling count / protection value faults occur, disable collision preparation system for duration of fault		Diagnostic is Enabled. Front Object Detection Module Torque Request Serial Data Error Diagnostic Enable	1.00	4 / 10 counts	Type C, No SVS , "Emissions Neutral Diagnostics – special type C"

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Automatic Braking Engine Torque Request Signal Message Incorrect	P15F8	Detects rolling count or protection value errors Rear Virtual Bumper Axle Torque Command serial data signal "Emissions Neutral Default Action : When the ECM determines that a serial communication fault has occurred with the EOCM in frame $2F9, the code is set and the auto braking feature is disabled for the remainder of the key cycle." Only applicable for applications with Full Speed Range Adaptive Cruise Control and Collision Preparation System feature.	If x of y rolling count / protection value faults occur, disable rear virtual bumper or collision preparation system for duration of fault		Diagnostic is Enabled. Automatic Braking Engine Torque Request Serial Data Error Diagnostic Enable	1.00	4 / 10 counts	Type C, No SVS , "Emissions Neutral Diagnostics – special type C"

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Ignition Voltage Correlation	P1682	Detect a continuous or intermittent out of correlation between the Run/Crank Ignition Voltage and the Powertrain Relay Ignition Voltage. The diagnostic monitors the difference in voltage between Run/Crank Voltage and the Powertrain Relay Ignition Voltage and fails the diagnostic when the voltage difference is too high. This diagnostic only runs when the powertrain is commanded on and the Run/Crank Voltage is greater than a threshold based on IAT or the powertrain ignition voltage is high enough the Run/Crank voltage is high enough.	|Run/Crank – PT Relay Ignition| >	3.00 Volts		Powertrain Relay commanded on AND (Run/Crank voltage > Table, f(IAT). See supporting tables: **P1682_PT Relay Pull-in Run/Crank Voltage f(IAT)** OR PT Relay Ignition voltage > 5.50 Volts) AND Run/Crank voltage > 5.50 Volts	240 / 480 counts; or 0.175 sec continuous; 12.5 ms/count in main processor	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Control Module Serial Peripheral Interface Bus 1	P16F0	This DTC detects intermitent and continuous invalid SPI messages. This is based on the detection of missing or invalid receive message within the main processor before receiving a valid message.	This function detects a serial communications fault based upon the detection of missing or invalid (receive) message within the main processor before receiving a valid message.		Run/Crank voltage	> 6.41 Volts	39 / 399 counts continuous; 12.5 ms /count in the ECM main processor	Type A, 1 Trips
			This function detects a serial communications fault based upon the detection of missing or invalid (receive) message within the main processor after receiving a valid message.		Run/Crank voltage	> 6.41 Volts	159 / 399 counts continuous; 12.5 ms /count in the ECM main processor	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Internal Control Module Redundant Memory Performance (Gasoline applications ONLY)	P16F3	Detect Processor Calculation faults due to RAM corruptions, ALU failures and ROM failures For all of the following cases: If the individual diagnostic threshold is equal to 2048 ms, this individual case is not applicable. If any of the following cases are X out of Y diagnostics and the fail (x) is greater than the sample (Y), this individual case is also not applicable.	Equivance Ratio torque compensation exceeds threshold	-38.30 Nm	Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	Type A, 1 Trips
			Absolute difference between Equivance Ratio torque compensation and its dual store out of bounds given by threshold	38.30 Nm	Ignition State	Accessory, run or crank	Up/down timer 175 ms continuous, 0.5 down time multipier	
			Absolute difference of Accessory torque and its redundant calculation is out of bounds given by threshold range	38.30 Nm	Ignition State	Accessory, run or crank	Up/down timer 175 ms continuous, 0.5 down time multipier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Absolute difference of Filtered Air-per-cylinder and its redundant calculation is out of bounds given by threshold range	89.54 mg	Ignition State	Accessory, run or crank	Up/down timer 175 ms continuous, 0.5 down time multipier	
			Absolute difference between the previous Final Advance and the current Final Advance not Adjusted for Equivalence Ratio is out of bounds given by threshold range	15.00 degrees		Engine speed >0rpm	Up/down timer 425 ms continuous, 0.5 down time multipier	
			Torque Learn offset is out of bounds given by threshold range	High Threshold 0.00 Nm Low Threshold 0.00	Ignition State	Accessory, run or crank	Up/down timer 175 ms continuous, 0.5 down time multipier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
				Nm				
			One step ahead calculation of air-per-cylinder and two step ahead is greater than threshold	80.00 mg		Engine speed > 680 rpm	Up/down timer 443 ms continuous, 0.5 down time multipier	
			Difference between Unmanaged Spark and PACS Spark is greater than threshold	15.00 degrees	Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	
			Commanded Predicted Engine Torque and its dual store do not match	N/A	Ignition State	Accessory, run or crank	Up/down timer 2,048 ms continuous, 0.5 down time multipier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Zero pedal axle torque is out of bounds given by threshold range	High Threshold 495.50 Nm Low Threshold -65,535.00 Nm	Ignition State	Accessory, run or crank	Up/down timer 175 ms continuous, 0.5 down time multipier	
			Creep Coast Axle Torque is out of bounds given by threshold range	High Threshold 495.50 Nm Low Threshold -65,535.00 Nm	Ignition State	Accessory, run or crank	Up/down timer 2,048 ms continuous, 0.5 down time multipier	
			Absolute difference of Friction torque and its redundant calculation is out of bounds given by threshold range	38.30 Nm	Ignition State	Accessory, run or crank	Up/down timer 175 ms continuous, 0.5 down time multipier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Arbitrated Air-Per-Cylinder filter coefficient is out of bounds given by threshold range	High Threshold 1.000 Low Threshold 0.074	Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	
			Launch spark is active but the launch spark redundant path indicates it should not be active	N/A		Engine speed < 7,800.00 or 7,900.00 rpm (hysteresis pair)	Up/down timer 143 ms continuous, 0.5 down time multipier	
			Rate limited vehicle speed and its dual store do not equal	N/A		Time since first CAN message with vehicle speed >= 0.500 sec	10 / 20 counts; 25.0msec/count	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Commanded engine torque due to fast actuators and its dual store do not equal	N/A	Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	
			Commanded engine torque due to slow actuators and its dual store do not equal	N/A	Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	
			TOS to wheel speed conversion factor is out of bounds given by threshold range	High Threshold: 1.10 T/C Range Hi 0.10 T/C Range Lo Low Threshold: 1.10 T/C Range Hi 0.10 T/C Range Lo	Ignition State	Accessory, run or crank	255 / 6 counts; 25.0msec/count	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Cylinders active greater than commanded	2 cylinders		Engine run flag = TRUE > 2.00 s Number of cylinder events since engine run > 24 No fuel injector faults active	Up/down timer 443 ms continuous, 0.5 down time multipier	
			Transfer case neutral request from four wheel drive logic does not match with operating conditions	N/A	Ignition State	Accessory, run or crank Transfer case range valid and not over-ridden FWD Apps only	7.00 / 10.00 counts; 25.0msec/count	
			Driver progression mode and its dual store do not equal	N/A	Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
							multipier	
			Predicted torque for uncorrected zero pedal determination is greater than calculated limit.	Table, f(Engine, Oil Temp). **P16F3_Speed Control External Load f(Oil Temp, RPM)** + 38.30 Nm	Ignition State	Accessory, run or crank	Up/down timer 2,048 ms continuous, 0.5 down time multipier	
			Engine Predicted Request Without Motor is greater than its redundant calculation plus threshold	37.30 Nm	Ignition State	Accessory, run or crank	Up/down timer 175 ms continuous, 0.5 down time multipier	
			Engine Immediate Request Without Motor is greater than its redundant calculation plus threshold	37.30 Nm	Ignition State	Accessory, run or crank	Up/down timer 175 ms continuous, 0.5	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
							down time multipier	
			Positive Torque Offset is greater than its redundant calculation plus threshold OR Positive Torque Offset is less than its redundant calculation minus threshold	38.30 Nm	Ignition State	Accessory, run or crank	Up/down timer 175 ms continuous, 0.5 down time multipier	
			Commanded Predicted Engine Request is greater than its redundant calculation plus threshold	38.30 Nm	Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, down time	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
							multipier 0.5	
			Commanded Hybrid Predicted Crankshaft Request is greater than its redundant calculation plus threshold	4,096.00 Nm	Ignition State	Accessory, run or crank	Up/down timer 2,048 ms continuous, 0.5 down time multipier	
			Commanded Hybrid Immediate Crankshaft Request is less than its redundant calculation minus threshold	4,096.00 Nm	Ignition State	Accessory, run or crank	Up/down timer 2,048 ms continuous, 0.5 down time multipier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Regeneration Brake Assist is not within a specified range	Brake Regen Assist < 0 Nm or Brake Regen Assist > 0.00 Nm	Ignition State	Accessory, run or crank	Up/down timer 2,048 ms continuous, 0.5 down time multipier	
			Cylinder Spark Delta Correction exceeds the absolute difference as compared to Unadjusted Cylinder Spark Delta	15.00 degrees	Ignition State	Accessory, run or crank	Up/down timer 175 ms continuous, 0.5 down time multipier	
			1. Cylinder Torque Offset exceeds step size threshold OR	1. 38.30 Nm	Ignition State	Accessory, run or crank	Up/down timer 175 ms continuous, 0.5 down time multipier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			2. Sum of Cylinder Torque Offset exceeds sum threshold	2. 38.30 Nm				
			Engine Capacity Minimum Immediate Without Motor is greater than its dual store plus threshold	38.30 Nm	Ignition State	Accessory, run or crank	Up/down timer 175 ms continuous, 0.5 down time multipier	
			Engine Capacity Minimum Engine Off is greater than threshold	0 Nm	Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Engine Capacity Minimum Engine Immediate Without Motor is greater than threshold	0 Nm	Ignition State	Accessory, run or crank	Up/down timer 2,048 ms continuous, 0.5 down time multipier	
			Commanded Immediate Engine Request is greater than its redundant calculation plus threshold	38.30 Nm	Ignition State	Accessory, run or crank	Up/down timer 2,048 ms continuous, 0.5 down time multipier	
			Engine Speed Lores Intake Firing (event based) calculation does not equal its redundant calculation	N/A		Engine speed greater than 0rpm	Up/down timer 143 ms continuous, 0.5 down time multipier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Engine Speed Lores Intake Firing timing (event based) calculation does not equal its redundant calculation	N/A		Engine speed greater than 0rpm	Up/down timer 143 ms continuous, 0.5 down time multipier	
			Idle speed control calculated predicted minimum torque request exceeds calculated torque limit	Table, f(Oil Temp, RPM). See supporting tables: **P16F3_Speed Control External Load f(Oil Temp, RPM)** + 38.30 Nm	Ignition State	Accessory, run or crank	Up/down timer 2,048 ms continuous, 0.5 down time multipier	
			Idle speed control calculated predicted minimum torque without reserves exceeds calculated torque limit	Table, f(Oil Temp, RPM). See supporting tables: **P16F3_Speed Control External Load f(Oil Temp, RPM)** +	Ignition State	Accessory, run or crank	Up/down timer 2,048 ms continuous, 0.5 down time multipier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
				38.30 Nm				
			Difference between Driver Requested Immediate Torque primary path and its secondary exceeds threshold	495.50 Nm	Ignition State	Accessory, run or crank	Up/down timer 2,048 ms continuous, 0.5 down time multipier	
			Driver Immediate Request is less than its redundant calculation minus threshold	495.50 Nm	Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	
			Commanded Immediate Request is greater than its redundant calculation plus threshold	495.50 Nm	Ignition State	Accessory, run or crank	Up/down timer 2,048 ms continuous, 0.5 down time	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			OR Commanded Immediate Request is less than its redundant calculation minus threshold				multipier	
			Commanded Immediate Response Type is set to Inactive	N/A	Ignition State	Accessory, run or crank	Up/down timer 2,048 ms continuous, 0.5 down time multipier	
			Difference between Cruise Axle Torque Arbitrated Request and Cruise Axle Torque Request exceeds threshold	18.58 Nm		Cruise has been engaged for more than 4.00 seconds	Up/down timer 2,048 ms continuous, 0.5 down time multipier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Desired engine torque request greater than redundant calculation plus threshold	37.30 Nm	Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	
			Engine min capacity above threshold	38.30 Nm	Ignition State	Accessory, run or crank	Up/down timer 120 ms continuous, 0.5 down time multipier	
			No fast unmanaged retarded spark above the applied spark plus the threshold	15.00 Degree		Engine speed greater than 0rpm	Up/down timer 425 ms continuous, 0.5 down time multipier	
			Absolute difference of adjustment factor based on temperature and its dual store above threshold	2.76 m/s	Ignition State	Accessory, run or crank	Up/down timer 164 ms continuous, 0.5 down time multipier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			1. Absolute difference of redundant calculated engine speed above threshold	1,090 RPM		Engine speed greater than 0 RPM	Up/down timer 143 ms continuous, 0.5 down time multipier	
			After throttle blade pressure and its dual store do not match	N/A	Ignition State	Accessory, run or crank	Up/down timer 175 ms continuous, 0.5 down time multipier	
			Speed Control's Preditcted Torque Request and its dual store do not match	N/A	Ignition State	Accessory, run or crank	Up/down timer 2,048 ms continuous, 0.5 down time multipier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Engine oil temperature and its dual store do not match	N/A	Ignition State	Accessory, run or crank	Up/down timer 385 ms continuous, 0.5 down time multipier	
			Desired throttle position greater than redundant calculation plus threshold	6.31 percent	Ignition State	Accessory, run or crank	Up/down timer 175 ms continuous, 0.5 down time multipier	
			Absolute difference of the rate limited pre-throttle pressure and its redundant calculation greater than threshold	0.06 kpa	Ignition State	Accessory, run or crank	Up/down timer 175 ms continuous, 0.5 down time multipier	
			Throttle desired torque above desired torque plus threshold	38.30 Nm	Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Desired filtered throttle torque exceeds the threshold plus the higher of desired throttle torque or modeled throttle torque	38.30 Nm	Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	
			Torque feedback proportional term is out of allowable range or its dual store copy does not match	High Threshold 19.15 Nm Low Threshold -19.15 Nm	Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	
			Torque feedback integral term magnitude or rate of change is out of allowable range or its dual store	High Threshold 35.91 Nm	Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			copy do not match	Low Threshold -38.30 Nm Rate of change threshold 2.39 Nm/loop			down time multipier	
			Difference of Final Torque feedback proportional plus integral term and its redundant calculation is out of bounds given by threshold range	High Threshold 38.30 Nm Low Threshold - 38.30 Nm	Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	
			Difference of torque desired throttle area and	High Threshold	Ignition State	Accessory, run or crank	Up/down timer 475	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			its redundant calculation is out of bounds given by threshold range	0.50 % Low Threshold - 0.50 %			ms continuous, 0.5 down time multipier	
			Difference of torque model coefficients and its redundant calculation is out of bounds given by threshold range	High Threshold 0.0002227 Low Threshold - 0.0002227	Ignition State	Accessory, run or crank	Up/down timer 175 ms continuous, 0.5 down time multipier	
			Difference of base friction torque and its redundant calculation is out of bounds given by threshold range	High Threshold 38.30 Nm Low Threshold - 38.30 Nm	Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Accessory drive friction torque is out of bounds given by threshold range	High Threshold 38.30 Nm Low Threshold 0.00 Nm	Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	
			AC friction torque is greater than commanded by AC control software or less than threshold limit	High Threshold 40.00 Nm Low Threshold 0.00 Nm	Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	
			Difference of Oil temperature delta friction torque and its redundant calculation is out of bounds given by threshold range	High Threshold 38.30 Nm	Ignition State	Accessory, run or crank	Up/down timer 2,048 ms continuous, 0.5 down time multipier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
				Low Threshold - 38.30 Nm				
			Generator friction torque is out of bounds given by threshold range	High Threshold 38.30 Nm Low Threshold 0.00 Nm	Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	
			Absolute difference between the Supercharger friction torque and its redundant calculation greater than threshold	38.30 Nm	Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	
			Filtered Torque error magnitude or its increase rate of change is out of	High Threshold 38.30		Engine speed >0rpm MAF, MAP and Baro DTCs are false	Up/down timer 475 ms continuous,	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			allowable range or its dual store copy do not match	Nm Low Threshold -38.30 Nm Rate of change threshold 2.39 Nm/loop			0.5 down time multipier	
			Torque error compensation is out of bounds given by threshold range	High Threshold 38.30 Nm Low Threshold 0.00 Nm	Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	
			Delta Torque Baro compensation is out of bounds given by threshold	High Threshold 2.18	Ignition State	Accessory, run or crank	Up/down timer 175 ms continuous,	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			range	Nm Low Threshold -4.47 Nm			0.5 down time multipier	
			1. Difference of reserve torque value and its redundant calculation exceed threshold OR 2. Reserve request does not agree with operating conditions or Difference of final predicted torque and its redundant calculation exeed threshold OR 3. Rate of change of reserve torque exceeds threshold, increasing direction only OR 4. Reserve engine torque above allowable capacity threshold	1. 37.30 Nm 2. N/A 3. 37.30 Nm 4. 37.30 Nm	3. & 4.: Ignition State	1. & 2.: Torque reserve (condition when spark control greater than optimum to allow fast transitions for torque disturbances) > 38.30 Nm 3. & 4.: Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Engine Vacuum and its dual store do not match	N/A	Ignition State	Accessory, run or crank	Up/down timer 175 ms continuous, 0.5 down time multipier	
			Absolute difference of the calculated Intake Manifold Pressure during engine event versus during time event is greater than threshold	Table, f(Desired Engine Torque). See supporting tables: **P16F3_Delta MAP Threshold f(Desired Engine Torque)**		Engine speed >0rpm	Up/down timer 143 ms continuous, 0.5 down time multipier	
			Min. Axle Torque Capacity is greater than threshold	0.00 Nm	Ignition State	Accessory, run or crank	Up/down timer 175 ms continuous, 0.5 down time multipier	
			Driver Predicted Request is greater than its redundant calculation plus threshold OR	495.50 Nm	Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Driver Predicted Request is less than its redundant calculation minus threshold					
			Cold Delta Friction Torque and its dual store do not match	N/A	Ignition State	Accessory, run or crank	Up/down timer 175 ms continuous, 0.5 down time multipier	
			Predicted torque for zero pedal determination is greater than calculated limit.	Table, f(Oil Temp, RPM). See supporting tables: **Speed Control External Load f(Oil Temp, RPM)** + 38.30 Nm	Ignition State	Accessory, run or crank	Up/down timer 2,048 ms continuous, 0.5 down time multipier	
			Commanded Predicted	1 Nm	Ignition State	Accessory, run or crank	Up/down timer	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Axle Torque and its dual store do not match				475 ms continuous, 0.5 down time multipier	
			Steady State Estimated Engine Torque and its dual store are not equal	N/A		AFM not changing from Active to Inactive and preload torque not changing and one loop after React command Engine speed >0rpm	Up/down timer 2,048 ms continuous, 0.5 down time multipier	
			Difference of Weighting factor for number of cylinders fueled and its redundant calculation is above threshold	0.26		Engine run flag = TRUE > 10.00 s	Up/down timer 175 ms continuous, 0.5 down time multipier	
			Difference of minimum spark advance limit and its redundant calculation is out of bounds given by threshold range	15.00 degrees	Ignition State	Accessory, run or crank	Up/down timer 143 ms continuous, 0.5 down time multipier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Difference of commanded spark advance and adjusted delivered is out of bounds given by threshold range	15.00 degrees		Engine speed >0rpm	Up/down timer 425 ms continuous, 0.5 down time multipier	
			Absolute difference between Estimated Engine Torque and its dual store are above a threshold	38.30 Nm		Engine speed >0rpm	Up/down timer 475 ms continuous, 0.5 down time multipier	
			Absolute difference between Estimated Engine Torque without reductions due to torque control and its dual store are above a threshold	38.30 Nm		Engine speed >0rpm	Up/down timer 475 ms continuous, 0.5 down time multipier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Difference of desired spark advance for managed torque and its redundant calculation is out of bounds given by threshold range	15.00 degrees		Torque reserve (condition when spark control greater than optimum to allow fast transitions for torque disturbances) > 38.30 Nm	Up/down timer 443 ms continuous, 0.5 down time multipier	
			Absolute difference of Engine Capacity Minimum Running Immediate Brake Torque Excluding Cylinder Sensitivity and its redundant calculation is out of bounds given by threshold range	38 Nm		Engine speed >0rpm	Up/down timer 175 ms continuous, 0.5 down time multipier	
			One step ahead calculation of air-per-cylinder greater than two step ahead calculation by threshold for time	Threshold: Dynamically calculated based on current engine conditions Fault Pending Threshold: 100		Engine speed > 680 rpm	Up/down timer 443 ms continuous, 0.5 down time multipier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
				ms				
			Rate limited cruise axle torque request and its dual store do not match within a threshold	18.58 Nm	Ignition State	Accessory, run or crank	Up/down timer 163 ms continuous, 0.5 down time multipier	
			1. Absolute difference of Calculated accelerator pedal position compensated for carpet learn and error conditions and its redundant calculation is out of bounds given by threshold range OR 2. Absolute difference of Calculated accelerator pedal position compensated for carpet learn and error conditions and its dual store do not equal OR	1. 5.00 % 2. N/A 3. N/A	Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			3. Absolute difference of Calculated accelerator pedal position and its dual store do not equal					
			Commanded axle torque is greater than its redundant calculation by threshold	495.50 Nm	Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	
			Commanded axle torque is less than its redundant calculation by threshold	743.25 Nm	Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	
			Preload timer and its redundant calculation do not equal	N/A	Ignition State	Accessory, run or crank AFM apps only	Up/down timer 2,048 ms continuous, 0.5 down time multipier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			AC friction torque is greater than commanded by AC control software	40.00 Nm	Ignition State	Accessory, run or crank	Up/down timer 2,048 ms continuous, 0.5 down time multipier	
			Engine Speed Lores Intake Firing (time based) calculation does not equal its redundant calculation	N/A		Engine speed >0rpm	Up/down timer 175 ms continuous, 0.5 down time multipier	
			Absolute difference of the calculated spark offset for equivalence ratio and its redundant cacluation is greater than a threshold	15.00 degrees		Engine speed >0rpm	Up/down timer 143 ms continuous, 0.5 down time multipier	
			Transmission Torque Request cacluations do not equal their dual stores	N/A		Run or Crank = TRUE > 0.50 s	16 / 32 counts; 25.0msec/count	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Absolute difference of the predicted motor torque ACS and its redundant cacluation is greater than a threshold	0.01 Nm			Up/down timer 2,048 ms continuous, 0.5 down time multipier	
			Absolute difference of maximum throttle area and its redundant cacluation is greater than a threshold	15 mm2			Up/down timer 164 ms continuous, 0.5 down time multipier	
			Absolute difference of Desired TIAP and its redundant cacluation is greater than a threshold	5.00 kPa			Up/down timer 475 ms continuous, 0.5 down time multipier	
			Pedal learns and their redundant calculation do not equal		Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	
			Throttle learns and their redundant calculation do not equal		Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Desired Throttle Position and its redundant calculation do not equal		Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Park Assistance System Performance	P18CB	Determines if Park assist active bit from EBCM is valid	Speed Error - APA active ($1C6/$1C7) above a vehicle speed threshold OR Initialization Error - APA active ($1C6/$1C7) without an active torque request OR Exit Error - APA transitions to inactive during active torque request above a vehicle speed threshold	> 10.00 APA active boolean transitions from False to True with Torque Intervention = No request APA active boolean transitions from True to False with Torque Intervention <> No request when vehicle speed is > 1.00	Power Mode Engine Running Status of traction in GMLAN message ($4E9) Ignition Voltage Run/Crank Activ	= Run = True = Traction Present > 6.41 volts > 0.50 seconds	>= 6 failures out of 10 Performed every 12.5ms >= 6 failures out of 10 Performed every 12.5ms When transition occurs, no number of samples Performed every 12.5ms	Type C, No SVS Emissions Neutral Diagnostic - Type C

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Intake Camshaft Actuator Solenoid Circuit Low– Bank 1	P2088	Controller specific output driver circuit diagnoses the CAM phaser oil control valve solenoid high sided driver for a short to ground failure when the output is powered on by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to ground failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to ground.	≤ 0.5 Ω impedance between signal and controller ground	System supply voltage Output driver is commanded on Ignition switch is in crank or run position	> 11.00 Volts	20 failures out of 25 samples 250 ms /sample, continuous	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Intake Camshaft Actuator Solenoid Circuit High – Bank 1	P2089	Controller specific output driver circuit diagnoses the CAM phaser oil control valve solenoid high sided driver for a short to power failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver off state indicates short to power failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to power.	≤ 0.5 Ω impedance between signal and controller power	System supply Output driver is commanded on Ignition switch is in crank or run position	> 11.00 Volts	20 failures out of 25 samples 250 ms /sample, continuous	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust Camshaft Actuator Solenoid Circuit Low – Bank 1	P2090	Controller specific output driver circuit diagnoses the CAM phaser oil control valve solenoid high sided driver for a short to ground failure when the output is powered on by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to ground failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to ground.	≤ 0.5 Ω impedance between signal and controller ground	System supply voltage Output driver is commanded on Ignition switch is in crank or run position	> 11.00 Volts	20 failures out of 25 samples 250 ms /sample, continuous	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust Camshaft Actuator Solenoid Circuit High – Bank 1	P2091	Controller specific output driver circuit diagnoses the CAM phaser oil control valve solenoid high sided driver for a short to power failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver off state indicates short to power failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to power.	≤ 0.5 Ω impedance between signal and controller power	System supply voltage Output driver Ignition switch	> 11.00 Volts On Crank or Run	20 failures out of 25 samples 250 ms /sample, continuous	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Post Catalyst Fuel Trim System Too Lean Bank 1	P2096	Determines if the post catalyst O2 sensor based fuel control system is indicating a lean exhaust gas condition. If the lean condition is such that the control system utilizes all or most of its available high limit authority (high limit = 100% authority), then P2096 will set. The monitor can be calibrated to fail based on the Average Integral Offset % Authority, the Average Total Offset % Authority or both combined. The Average Total Offset metric consists of the average of the Integral Offset+ Proportional Offset. Note: When the post catalyst O2 voltage is too lean, the post catalyst O2 integral and proportional offset control is increased (positive % authority). This applies a rich bias to fuel control in an attempt to counteract the lean condition. A perfectly balanced control system (no rich or lean bias required) is represented by integral	The Average Integral Offset % Authority AND The Average Total Offset % Authority (Note: any value greater than or equal to +100% effectively nullifies the Average Total Offset % Authority criteria) High Vapor Feature: The diagnostic is at risk of reporting a false fail when excessively High Vapor (HV) conditions are present. This HV condition is indicated when the purge valve is open AND percent vapor is >= 18 % for >= 5.0 seconds AND the % Authority metric is approaching the failure threshold. Diagnosis resumes if the purge valve is closed OR the percent vapor is <= 14 % for >= 5.0 seconds. This was done to minimize disabling the diagnostic for longer than necessary.	>= 97.0 % >= 58.0 % If the P2096 is actively failing then the Average Integral Offset must be < 50.0 % and the Average Total Offset must be < 40.0 % for the diagnostic to report a pass.	The post cat fuel trim diagnostic is enabled The diagnostic is enabled during: Deceleration Idle Cruise Light Acceleration Heavy Acceleration Ambient Air Pressure Engine AirFlow Intake Manifold Pressure Induction Air Temperature Start-up Coolant Temp. PTO Intrusive diag. fuel control Ethanol Estimation in Progress O2 Heater Learned Resistance Long Term Secondary Fuel Trim Enabled for (see "**Long Term Secondary Fuel Trim Enable Criteria**" in Supporting Tables) High Vapor Conditions Green Cat System	 No No Yes Yes Yes >= 70 kPa >= 0.0 g/s <= 10,000.0 >= 20 kPa <= 200 >= -20 deg. C <= 200 >= -20 deg. C (or OBD Coolant Enable Criteria = TRUE) Not Active Not Active Not Active = Valid (the heater resistance has learned since NVM reset, see enable conditions for "HO2S Heater Resistance DTC's") >= 5.0 seconds Not Present = Not Valid,	Frequency: Continuous Monitoring in 100ms loop. The Integral and Total Offset % Authority metrics are sampled every 100ms and an average is calculated every 30.0 seconds (300 samples) before comparing to their respective failure thresholds.	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		and proportional offset values of "0" (i.e. 0% authority) and a post catalyst O2 sensor that is within its optimal operating range (neither rich nor lean).			Condition	Green Cat System condition is considered valid until the accumulated air flow is greater than 360,000 grams. Airflow accumulation is only enabled when estimated Cat temperature is above 600 Deg C and airflow is above 18 grams/sec.		
					No Fault Active for:	AmbientAirDefault AIR System FA Ethanol Composition Sensor FA ECT_Sensor_FA EGRValveCircuit_FA EGRValvePerformance_FA IAT_SensorFA CamSensorAnyLocationFA EvapEmissionSystem_FA EvapFlowDuringNonPurge_FA FuelTankPressureSnsrCkt_FA EvapPurgeSolenoidCircuit_FA EvapSmallLeak_FA EvapVentSolenoidCircuit_FA FuelInjectorCircuit_FA MAF_SensorFA MAF_SensorTFTKO MAP_SensorFA MAP_EngineVacuumStatus EngineMisfireDetected_FA		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
						A/F Imbalance Bank1 O2S_Bank_1_Sensor_1_ FA O2S_Bank_1_Sensor_2_ FA		
					For the cells identified as enabled (i.e. those containing a "Yes" at the beginning of the Enable Conditions column), the minimum accumulated samples required before the fuel control metric is considered usable for that cell (1 sample = 100ms):			
					Deceleration	300		
					Idle	300		
					Cruise	300		
					Light Acceleration	300		
					Heavy Acceleration	300		
					(Note: A value in any of the above operating "cells" that is an order of magnitude (or more) higher than other cells is an indication that the diagnostic is not capable of diagnosing in that cell).			

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Post Catalyst Fuel Trim System Too Rich Bank 1	P2097	Determines if the post catalyst O2 sensor based fuel control system is indicating a rich exhaust gas condition. If the rich condition is such that the control system utilizes all or most of its available low limit authority (low limit = -100% authority), then P2097 will set. The monitor can be calibrated to fail based on the Average Integral Offset % Authority, the Average Total Offset % Authority or both combined. The Average Total Offset metric consists of the average of the Integral Offset+ Proportional Offset. Note: When the post catalyst O2 voltage is too rich, the post catalyst O2 integral and proportional offset control is decreased (negative % authority). This applies a lean bias to fuel control in an attempt to counteract the rich condition. A perfectly balanced control system (no rich or lean bias required) is represented by integral	The Average Integral Offset % Authority AND The Average Total Offset % Authority (Note: any value less than or equal to -100% effectively nullifies the Average Total Offset % Authority criteria) High Vapor Feature: The diagnostic is at risk of reporting a false fail when excessively High Vapor (HV) conditions are present. This HV condition is indicated when the purge valve is open AND percent vapor is >= 18 % for >= 5.0 seconds. Diagnosis resumes if the purge valve is closed OR the percent vapor is <= 14 % for >= 5.0 seconds. This was done to minimize disabling the diagnostic for longer than necessary.	<= -97.0 % <= -58.0 % If the P2097 is actively failing then the Average Integral Offset must be > -50.0 % and the Average Total Offset must be > -40.0 % for the diagnostic to report a pass.	Same as P2096	Same as P2096	Frequency: Continuous Monitoring in 100ms loop. The Integral and Total Offset % Authority metrics are sampled every 100ms and an average is calculated every 30.0 seconds (300 samples) before comparing to their respective failure thresholds.	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		and proportional offset values of “0” (i.e. 0% authority) and a post catalyst O2 sensor that is within its optimal operating range (neither rich nor lean).						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Control Module Throttle Actuator Position Performance	P2101	1) Detect a throttle positioning error. This is determined if the difference between measured throttle position and modeled throttle position is greater than a threshold or less than a threshold. This diagnostic only runs when the engine is running and the voltage is high enough and there is not a voltage failure and the throttle position minimum learn is not active and the throttle is being controlled 2) Throttle control is driving the throttle in the incorrect direction. This is determined if the throttle position is greater than a threshold percent and the powertrain relay voltage is high enough and the throttle position minimum learn is active.	Difference between measured throttle position and modeled position, (modeled = MAX (Commanded vs. Commanded Filtered)) > OR Difference between modeled position (modeled = MIN (Commanded vs. Commanded Filtered)) and measured throttle position >	6.31 percent 6.31 percent	TPS minimum learn is not active AND Powertrain Relay Contact1 Fault is FALSE (no P1682 fault) AND Throttle Control is not in Service or DVT control AND Throttle is being Controlled AND ((Engine Running AND Run/Crank Voltage) OR Run Crank Voltage)	> 5.50 Volts > 8.41 Volts	15 counts; 12.5 ms/count in the primary processor	Type A, 1 Trips
			Throttle Position >	36.00 percent	TPS minimum learn active AND Powertrain Relay Contact1 Fault is FALSE (no P1682 fault) AND Throttle Control is not in Service or DVT control	= TRUE	11 counts; 12.5 ms/count in the primary processor	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Accelerator Pedal Position (APP) Sensor 1 Lo	P2122	Detects a continuous or intermittent short low or open in the APP sensor #1 by monitoring the APP1 sensor percent Vref and failing the diagnostic when the APP1 percent Vref is too low. This diagnostic only runs when battery voltage is high enough. Detects a continuous or intermittent short low or open in the APP sensor #1 on the Main processor.	APP1 percent Vref	< 0.4625 % Vref	Run/Crank voltage No 5V reference error or fault for # 4 5V reference circuit	> 6.41 Volts P06A3	19 / 39 counts; or 14 counts continuous; 12.5 ms/count in the main processor	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Accelerator Pedal Position (APP) Sensor 1 Hi	P2123	Detects a continuous or intermittent short high in the APP sensor #1 by monitoring the APP1 sensor percent Vref and failing the diagnostic when the APP1 percent Vref is too high. This diagnostic only runs when battery voltage is high enough. Detect a continuous or intermittent short high in the APP sensor #1 on the Main processor.	APP1 percent Vref >	4.7500 % Vref	Run/Crank voltage No 5V reference error or fault for # 4 5V reference circuit	> 6.41 Volts P06A3	19 / 39 counts; or 14 counts continuous; 12.5 ms/count in the main processor	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Accelerator Pedal Position (APP) Sensor 2 Lo	P2127	Detects a continuous or intermittent short low or open in the APP sensor #2 by monitoring the APP2 sensor percent Vref and failing the diagnostic when the APP2 percent Vref is too low. This diagnostic only runs when battery voltage is high enough. Detects a continuous or intermittent short low or open in the APP sensor #2 on the Main processor.	APP2 percent Vref <	0.3250 % Vref	Run/Crank voltage No 5V reference error or fault for # 4 5V reference circuit	> 6.41 Volts P0697	19 / 39 counts; or 14 counts continuous; 12.5 ms/count in the main processor	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Accelerator Pedal Position (APP) Sensor 2 Hi	P2128	Detects a continuous or intermittent short high in the APP sensor #2 by monitoring the APP2 sensor percent Vref and failing the diagnostic when the APP2 percent Vref is too high. This diagnostic only runs when battery voltage is high enough. Detect a continuous or intermittent short high in the APP sensor #2 on the Main processor.	APP2 percent Vref >	2.6000 % Vref	Run/Crank voltage No 5V reference error or fault for # 4 5V reference circuit	> 6.41 Volts P0697	19 / 39 counts; or 14 counts continuous; 12.5 ms/count in the main processor	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Throttle Position (TP) Sensor 1-2 Correlation	P2135	Detect a continuous or intermittent correlation fault between TPS sensors #1 and #2 on Main processor. 1.) The diagnostic monitors the difference in position between TPS1 and the TPS2 and fails the diagnostic when the difference is too high. This diagnostic only runs when the battery voltage is high enough. 2.) The diagnostic monitors the difference in reference voltage between normalized min TPS1 and the normalized min TPS2 and fails the diagnostic when the difference is too high. This diagnostic only runs when the battery voltage is high enough. Detects a continuous or intermittent correlation fault between TPS sensors #1 and #2 on Main processor	Difference between TPS1 displaced and TPS2 displaced >	6.797 % offset at min. throttle position with a linear threshold to 9.720 % at max. throttle position	Run/Crank voltage No TPS sensor faults No 5V reference error or fault for # 4 5V reference circuit	> 6.41 Volts (P0122, P0123, P0222, P0223) P06A3	79 / 159 counts; or 58 counts continuous; 3.125 ms/count in the main processor	Type A, 1 Trips
			Difference between (normalized min TPS1) and (normalized min TPS2) >	5.000 % Vref	Run/Crank voltage No TPS sensor faults No 5V reference error or fault for # 4 5V reference circuit	> 6.41 Volts (P0122, P0123, P0222, P0223) P06A3	79 / 159 counts; or 58 counts continuous; 3.125 ms/count in the main processor	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Accelerator Pedal Position (APP) Sensor 1-2 Correlation	P2138	Detect a continuous or intermittent correlation fault between APP sensors #1 and #2 on Main processor. 1.) The diagnostic monitors the difference in position between APP1 and the APP2 and fails the diagnostic when the difference is too high. This diagnostic only runs when the battery voltage is high enough. 2.) The diagnostic also monitors the difference in reference voltage between normalized min APP1 and the normalized min APP2 and fails the diagnostic when the difference is too high. This diagnostic only runs when the battery voltage is high enough. Detects a continuous or intermittent correlation fault between APP sensors #1 and #2 on Main processor	Difference between APP1 displaced and APP2 displaced >	5.000 % offset at min. pedal position with a linear threshold to 10.001 % at max. pedal position	Run/Crank voltage No APP sensor faults No 5V reference errors or faulst for # 3 & # 4 5V reference circuits	> 6.41 Volts (P2122, P2123,P2127, P2128) (P06A3, P0697)	19 / 39 counts intermittent; or 15 counts continuous, 12.5 ms/count in the main processor	Type A, 1 Trips
			Difference between (normalized min APP1) and (normalized min APP2) >	5.000 % Vref	Run/Crank voltage No APP sensor faults No 5V reference errors or faulst for # 3 & # 4 5V reference circuits	> 6.41 Volts (P2122, P2123,P2127, P2128) (P06A3, P0697)	19 / 39 counts intermittent; or 15 counts continuous, 12.5 ms/count in the main processor	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Minimum Throttle Position Not Learned	P2176	Detect when the throttle position minimum learn on the main processor is not learned. This diagnostic detects this by monitoring if the throttle position is greater than a threshold and the number of learn attempts is greater than a threshold. This diagnostic only runs when the battery voltage is high enough and the throttle position minimum learn is active. Throttle position sensors were not in the minmum learn window after multiple attempts to learn the minimum.	During TPS min learn on the Main processor, TPS percent Vref > AND Number of learn attempts >	0.5740 % Vref 10 counts	Run/Crank voltage TPS minimum learn is active No previous TPS min learn values stored in long term memory	> 6.41 Volts = TRUE	2.0 secs	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Intake Air Temperature Sensor 1 / 2 Correlation	P2199	Detects when the Intake Air Temperature (IAT) sensor and IAT2 sensor values do not correlate with each other. These two temperature sensors are both in the induction system, although they do have different sensor time constants and different positional relationships with components that produce heat. If these two temperature values differ by a large enough amount, the Intake Air Temperature 1 / 2 Correlation Diagnostic will fail. This diagnostic is enabled if the Powertrain Relay voltage is high enough.	ABS (IAT - IAT2)	> 55.0 deg C	Powertrain Relay Voltage for a time No Active DTCs:	>= 11.0 Volts >= 0.9 seconds PowertrainRelayFault	40 failures out of 50 samples 1 sample every 100 msec	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Bank 1 Air-Fuel Ratio Imbalance	P219A	This monitor determines if there is an Air Fuel Imbalance in the fueling system for a cylinder on a Bank 1. Detection is based on a the pre catalyst oxygen sensor voltage. The pre catalyst O2 voltage is used to generate a variance metric that represents the statistical variation of the O2 sensor voltage over a given engine cycle. This metric is proportional to the air-fuel ratio imbalance (variance is higher with an imbalance than without). The observed Variance is dependent on engine speed and load and is normalized by comparing it to a known "good system" result for that speed and load, and generating a Ratio metric. The Ratio metric is calculated by selecting the appropriate threshold calibration from a 17x17 table (see Supporting Table	Filtered Ratio > The EWMA calculation uses the weighting coefficient from the following supporting table: **P219A EWMA Coefficient** The Ratio metric is calculated by selecting the appropriate threshold calibration from a 17x17 table (see Supporting Table **P219A Variance Threshold Bank1 Table**) and subtracting it from the measured Variance. The result is then divided by a normalizer calibration from another 17 x 17 table (see Supporting Table **P219A Normalizer Bank1 Table**). This quotient is then multiplied by a quality factor calibration from a 17 x 17 table (see Supporting Table **P219A Quality Factor Bank1 Table**). This result is referred to as the Ratio. Note that the quality factor ranges between 0 and 1 and represents robustness to false diagnosis in the current operating region. Regions with low quality factors are not used.	0.35 If the diagnostic has reported a failure on the prior trip, the Filtered Ratio must fall below 0.28 in order to report a pass. This feature prevents the diagnostic from toggling between failing and passing when the Filtered Ratio remains near the initial failure threshold of 0.35 .	The A/F imbalance diagnostic is enabled System Voltage Fuel Level Engine Coolant Temperature Cumulative engine run time Diagnostic enabled at Idle (regardless of other operating conditions) Engine speed range Engine speed delta during a short term sample period Mass Airflow (MAF) range Cumulative delta MAF during a short term sample period Filtered MAF delta between samples Note: first order lag filter coefficient applied to MAF = 0.050	 no lower than 11.0 Volts for more than 0.2 seconds > 10.0 % The diagnostic will disregard the fuel level criteria if the fuel sender is faulty. > -20 deg. C (or OBD Coolant Enable Criteria = TRUE) > 0.0 seconds No 1,200 to 7,000 RPM < 150 RPM 0 to 200 g/s < 2 g/s < 0.25 g/s	Minimum of 1 test per trip, up to 3 tests per trip during RSR or FIR. The front O2 sensor voltage is sampled once per cylinder event. Therefore, the time required to complete a single test (when all enable conditions are met) decreases as engine speed increases. For example, 14.10 seconds of data is required at 1000 rpm while double this time is required at 500 rpm and half this time is required at 2000 rpm. This data is collected only when enable conditions are met, and as such significantly more operating time is required than is indicated above. Generally, a report will be	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		P219A Variance Threshold Bank1 Table) and subtracting it from the measured Variance. The result is then divided by a normalizer calibration from another 17 x 17 table (see Supporting Table **P219A Normalizer Bank1 Table**). This quotient is then multiplied by a quality factor calibration from a 17 x 17 table (see Supporting Table **P219A Quality Factor Bank1 Table**) . This result is referred to as the Ratio. Note that the quality factor ranges between 0 and 1 and represents robustness to false diagnosis in the current operating region. Regions with low quality factors are not used. Finally, a EWMA filter is applied to the Ratio metric to generate the Filtered Ratio malfunction criteria metric. Generally, a normal system will result in a negative Filtered Ratio while a failing system will result in a positive Filtered			Air Per Cylinder (APC) APC delta during short term sample period Filtered APC delta between samples Note: first order lag filter coefficient applied to APC = 0.050 Spark Advance Throttle Area (percent of max) Intake Cam Phaser Angle Exhaust Cam Phaser Angle Quality Factor (QF) QF calibrations are located in a 17x17 lookup table versus engine speed and load (see Supporting Table **P219A Quality Factor Bank1 Table**). QF values less than "1" indicate that we don't have 4sigma/2sigma robustness in that region. The quality of the data is determined via statistical analysis of Variance data. Fuel Control Status Closed Loop and Long Term FT Enabled for:	100 to 500 mg/cylinder < 50 mg/cylinder < 0.30 percent 5 to 55 degrees 3 to 200 percent 5 to 35 degrees 5 to 35 degrees >= 0.99 >= 1.2 seconds (Please see "**Closed Loop Enable**	made within 5 minutes of operation. For RSR or FIR, 6 tests must complete before the diagnostic can report.	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		Ratio. The range of the Filtered Ratio metric is application specific since both the emissions sensitivity and relationship between imbalance and the Variance metric are application specific. Some applications may need to command a unique cam phaser value before performing the above calculations since cam phasing has been shown to have an impact on overall signal quality. This application Does Not Use this feature.			 Device Control AIR pump CASE learn EGR EVAP Engine Over Speed Protection Idle speed control PTO Injector base pulse width O2 learned htr resistance Rapid Step Response (RSR): RSR will trigger if the Ratio result from the last test is AND it exceeds the last Filtered ratio by Once triggered, the filtered ratio is reset to: Fast Initial Response (FIR): FIR will trigger when an NVM reset or code clear occurs. Once triggered, the filtered ratio is reset to: No Fault Active for:	**Clarification**" and "**Long Term FT Enable Criteria**" in Supporting Tables) Not active Not on Not active Not intrusive Not intrusive Not Active Normal Not Active Above min pulse limit = Valid (the O2 heater resistance has learned since NVM reset) >= 0.32 >= 0.32 0.00 0.00		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
						EngineMisfireDetected_FA MAP_SensorFA MAF_SensorFA ECT_Sensor_FA TPS_ThrottleAuthorityDefaulted FuelInjectorCircuit_FA AIR System FA EvapExcessPurgePsbl_FA CamSensorAnyLocationFA FuelTrimSystemB1_FA O2S_Bank_1_Sensor_1_FA O2S_Bank_1_Sensor_2_FA WRAF_Bank_1_FA		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Barometric Pressure (BARO) Sensor Performance (naturally aspirated)	P2227	Detects a performance failure in the Barometric Pressure (BARO) sensor, such as when a BARO value is stuck in range. If the engine has been off for a sufficient amount of time, the pressure values in the induction system will have equalized. The BARO sensor value is checked to see if it is within the normal expected atmospheric pressure range. If it is not, then the BARO performance diagnostic will fail. When the engine is running, there is an estimate of barometric pressure that is determined with the Manifold Pressure (MAP) sensor, throttle position, engine air flow and engine speed. If the BARO value from the sensor is not similar to this barometric pressure estimate, then the BARO performance diagnostic will fail.	**Engine Running:** Difference between Baro Pressure reading and Estimated Baro when distance since last Estimated Baro update OR Difference between Baro Pressure reading and Estimated Baro when distance since last Estimated Baro update	> 15.0 kPa <= 0.31 miles > 20.0 kPa > 0.31 miles	No Active DTCs:	AmbPresSnsrCktFA IAT_SensorFA MAF_SensorFA AfterThrottlePressureFA TPS_FA TPS_Performance_FA VehicleSpeedSensor_FA	320 failures out of 400 samples 1 sample every 12.5 msec	Type B, 2 Trips
			Engine Not Rotating: Barometric Pressure OR Barometric Pressure	< 50.0 kPa > 115.0 kPa	Time between current ignition cycle and the last time the engine was running Engine is not rotating No Active DTCs: No Pending DTCs:	> 10.0 seconds EngineModeNotRunTimer Error MAP_SensorCircuitFA AAP_SnsrCktFA MAP_SensorCircuitFP AAP_SnsrCktFP	4 failures out of 5 samples 1 sample every 12.5 msec	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Barometric Pressure (BARO) Sensor Circuit Low (non-boosted applications, Gen III)	P2228	Detects a continuous short to ground in the Barometric Pressure (BARO) signal circuit by monitoring the BARO sensor output voltage and failing the diagnostic when the BARO voltage is too low. The BARO sensor is a pressure transducer which outputs a voltage proportional to the absolute pressure.	BARO Voltage	< 39.3 % of 5 Volt Range (This is equal to 50.0 kPa)			320 failures out of 400 samples 1 sample every 12.5 msec	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Barometric Pressure (BARO) Sensor Circuit High (non-boosted applications, Gen III)	P2229	Detects a continuous short to power or open circuit in the Barometric Pressure (BARO) signal circuit by monitoring the BARO sensor output voltage and failing the diagnostic when the BARO voltage is too high. The BARO sensor is a pressure transducer which outputs a voltage proportional to the absolute pressure.	BARO Voltage	> 90.0 % of 5 Volt Range (This is equal to 115.0 kPa)			320 failures out of 400 samples 1 sample every 12.5 msec	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Barometric Pressure (BARO) Sensor Circuit Intermittent	P2230	Detects a noisy or erratic signal in the barometric pressure (BARO) circuit by monitoring the BARO sensor and failing the diagnostic when the BARO signal has a noisier output than is expected. When the value of BARO in kilopascals (kPa) is determined, a delta is calculated between the current reading and the previous reading. The absolute value of these deltas is summed over a number of BARO readings. The result of this summation is called a “string length”. Since the BARO signal is anticipated to be relatively smooth, a string length of a particular magnitude indicates a noisy or erratic BARO signal. The diagnostic will fail if the string length is too high.	String Length Where: "String Length" = sum of "Diff" calculated over And where: "Diff" = ABS(current BARO reading - BARO reading from 12.5 milliseconds previous)	> 140 kPa 80 consecutive BARO readings			4 failures out of 5 samples Each sample takes 1.0 seconds	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
O2 Sensor Signal Stuck Lean Bank 1 Sensor 2	P2270	The P2270 diagnostic is the first in a sequence of six intrusive secondary O2 monitors which include DTCs P2270, P013E, P013A, P2271, P013F, & P013B. This DTC determines if the secondary O2 sensor is stuck in a normal lean voltage range and thereby can no longer be used for secondary O2 sensor fuel control or for catalyst monitoring. This diagnostic increases the delivered fuel while monitoring the sensor signal and the accumulated mass air flow. This fault is set if the secondary O2 sensor does not achieve the required rich voltage before the accumulated mass air flow threshold is reached.	Post O2 sensor signal AND The Accumulated mass air flow monitored during the Stuck Lean Voltage Test	< 775 mvolts > 40 grams	No Active DTC's B1S2 DTC's Not active this key cycle System Voltage Learned heater resistance Green O2S Condition	TPS_ThrottleAuthorityDefaulted ECT_Sensor_FA IAT_SensorFA MAF_SensorFA MAP_SensorFA AIR System FA FuelInjectorCircuit_FA FuelTrimSystemB1_FA FuelTrimSystemB2_FA EngineMisfireDetected_FA Ethanol Composition Sensor FA O2S_Bank_ 1_TFTKO O2S_Bank_ 2_TFTKO P013A, P013B, P013E, P013F, P2270 or P2271 > 10.0 Volts = Valid (the heater resistance has learned since NVM reset, see enable conditions for "HO2S Heater Resistance DTC's") = Not Valid, Green O2S condition is considered valid until the accumulated air flow is greater than **Multiple DTC Use_Green Sensor Delay Criteria - Limit** for the following locations: B1S2, B2S2 (if applicable) in Supporting Tables tab. Airflow accumulation is only enabled when airflow	Frequency: Once per trip Note: if NaPOPD_b_ResetFastRespFunc = FALSE for the given Fuel Bank OR NaPOPD_b_RapidResponseActive = TRUE, multiple tests per trip are allowed.	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
						is above 18.0 grams/sec.		
					Low Fuel Condition	= False		
					Only when FuelLevelDataFault	= False		
					Pedal position	≤ 1.0 %		
					Engine Airflow	2.0 ≤ gps ≤ 10.5		
					Closed loop integral	0.92 ≤ C/L Int ≤ 1.08		
					Closed Loop Active	= TRUE (Please see "**Closed Loop Enable Clarification**" in Supporting Tables).		
					Decel Fuel Cut Off	not inhibited		
					Evap	not in control of purge		
					Ethanol Estimation in Progress	= Not Active (Please see "**Ethanol Estimation in Progress**" in Supporting Tables).		
					Post fuel cell	= Enabled, refer to **Multiple DTC Use - Block learn cells to enable Post oxygen sensor tests** for additional info.		
					Crankshaft Torque	< 100.0 Nm		
					EGR Intrusive diagnostic	= not active		
					All post sensor heater delays	= not active		
					O2S Heater (post sensor) on Time	≥ 60.0 sec		
					Transmission Temp	≥ -255.0 °C		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Predicted Catalyst temp Fuel State ================= All of the above met for at least 0.0 seconds, and then check the following Engine Speed to initially enable test Engine Speed range to keep test enabled (after initially enabled) Vehicle Speed to initially enable test Vehicle Speed range to keep test enabled (after initially enabled) ================= All of the above met for at least 2.0 seconds, and then the Force Cat Rich intrusive stage is requested. ================= During Stuck Lean test the following must stay TRUE or the test will abort: Commanded Fuel Crankshaft Torque	650 ≤ ºC ≤ 900 = DFCO possible ================== 1,150 ≤ RPM ≤ 3,500 1,000 ≤ RPM ≤ 3,650 43.5 ≤ MPH ≤ 77.7 40.4 ≤ MPH ≤ 80.8 0.96 ≤ EQR ≤ 1.08 < 110.0 Nm		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
O2 Sensor Signal Stuck Rich Bank 1 Sensor 2	P2271	The P2271 diagnostic is the fourth in a sequence of six intrusive secondary O2 monitors which include DTCs P2270, P013E, P013A, P2271, P013F, & P013B. This DTC determines if the secondary O2 sensor is stuck in a normal rich voltage range and thereby can no longer be used for secondary O2 sensor fuel control or for catalyst monitoring. This diagnostic commands fuel cut off while monitoring the sensor signal and the accumulated mass air flow. This fault is set if the secondary O2 sensor does not achieve the required lean voltage before the accumulated mass air flow threshold is reached.	Post O2 sensor signal AND The Accumulated mass air flow monitored during the Stuck Rich Voltage Test	> 100 mvolts > 10.0 grams	No Active DTC's B1S2 DTC's Not Active this key cycle System Voltage Learned heater resistance Green O2S Condition	TPS_ThrottleAuthorityDefaulted ECT_Sensor_FA IAT_SensorFA MAF_SensorFA MAP_SensorFA AIR System FA FuelInjectorCircuit_FA FuelTrimSystemB1_FA FuelTrimSystemB2_FA EngineMisfireDetected_FA Ethanol Composition Sensor FA O2S_Bank_ 1_TFTKO O2S_Bank_ 2_TFTKO P013A, P013B, P013E, P013F or P2270 > 10.0 Volts = Valid (the heater resistance has learned since NVM reset, see enable conditions for "HO2S Heater Resistance DTC's") = Not Valid, Green O2S condition is considered valid until the accumulated air flow is greater than **Multiple DTC Use_Green Sensor Delay Criteria - Limit** for the following locations: B1S2, B2S2 (if applicable) in Supporting Tables tab. Airflow accumulation is only enabled when airflow	Frequency: Once per trip Note: if NaPOPD_b_ResetFastRespFunc = FALSE for the given Fuel Bank OR NaPOPD_b_RapidResponseActive = TRUE, multiple tests per trip are allowed.	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
						is above 18.0 grams/sec.		
					Low Fuel Condition	= False		
					Only when FuelLevelDataFault	= False		
					Fuel State	= DFCO possible		
					DTC's Passed	= P2270 = P013E = P013A		
					================== After above conditions are met: DFCO mode is continued (w/o driver initiated pedal input).	=================		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
IGNITION CONTROL #1 CIRCUIT LOW	P2300	Diagnoses Cylinder #1 Ignition Control (EST) output driver circuit for a Short to Ground fault. Controller specific output driver circuit diagnoses the low sided driver for a short to ground failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to ground failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to ground.	≤ 100 Ω impedance between signal and controller ground	Engine running Ignition Voltage	 > 11.0	50 Failures out of 63 Samples 100 msec rate	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
IGNITION CONTROL #1 CIRCUIT High	P2301	Diagnoses Cylinder #1 Ignition Control (EST) output driver circuit for a Short to Power fault. Controller specific output driver circuit diagnoses the low sided driver for a short to power failure when the output is powered on by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to power failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to power.	≤ 100 Ω impedance between signal and controller power	Engine running Ignition Voltage	 > 11.0 Volts	50 Failures out of 63 Samples 100 msec rate	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
IGNITION CONTROL #2 CIRCUIT Low	P2303	Diagnoses Cylinder #2 Ignition Control (EST) output driver circuit for a Short to Ground fault. Controller specific output driver circuit diagnoses the low sided driver for a short to ground failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to ground failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to ground.	≤ 100 Ω impedance between signal and controller ground	Engine running Ignition Voltage	> 11.0 Volts	50 Failures out of 63 Samples 100 msec rate	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
IGNITION CONTROL #2 CIRCUIT High	P2304	Diagnoses Cylinder #2 Ignition Control (EST) output driver circuit for a Short to Power fault	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to power failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to power.	 ≤ 100 Ω impedance between signal and controller power	Engine running Ignition Voltage	 > 11.0 Volts	50 Failures out of 63 Samples 100 msec rate	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
IGNITION CONTROL #3 CIRCUIT Low	P2306	Diagnoses Cylinder #3 Ignition Control (EST) output driver circuit for a Short to Ground fault. Controller specific output driver circuit diagnoses the low sided driver for a short to ground failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to ground failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to ground.	 ≤ 100 Ω impedance between signal and controller ground	Engine running Ignition Voltage	 > 11.0 Volts	50 Failures out of 63 Samples 100 msec rate	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
IGNITION CONTROL #3 CIRCUIT High	P2307	Diagnoses Cylinder #3 Ignition Control (EST) output driver circuit for a Short to Power fault	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to power failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to power.	≤ 100 Ω impedance between signal and controller power	Engine running Ignition Voltage	> 11.0 Volts	50 Failures out of 63 Samples 100 msec rate	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
IGNITION CONTROL #4 CIRCUIT Low	P2309	Diagnoses Cylinder #4 Ignition Control (EST) output driver circuit for a Short to Ground fault. Controller specific output driver circuit diagnoses the low sided driver for a short to ground failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to ground failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to ground.	≤ 100 Ω impedance between signal and controller ground	Engine running Ignition Voltage	> 11.0 Volts	50 Failures out of 63 Samples 100 msec rate	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
IGNITION CONTROL #4 CIRCUIT High	P2310	Diagnoses Cylinder #4 Ignition Control (EST) output driver circuit for a Short to Power fault	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to power failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to power.	≤ 100 Ω impedance between signal and controller power	Engine running Ignition Voltage	 > 11.0 Volts	50 Failures out of 63 Samples 100 msec rate	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Transmission Control Torque Request Circuit	P2544	Determines if the torque request from the TCM is valid	Protect error - Serial Communication message 2's complement not equal ($189/$199) OR Rolling count error - Serial Communication message ($189/$199) rolling count index value OR Range Error - Serial Communication message - ($189/$199) TCM Requested Torque Increase OR Multi-transition error - Trans torque intervention type request change	Message <> two's complement of message Message <> previous message rolling count value + one > 350 Nm Requested torque intervention type toggles from not increasing request to increasing request	Diagnostic Status Power Mode Ignition Voltage Engine Running Run/Crank Active No Serial communication loss to TCM (U0101)	Enabled = Run > 6.41 volts = True > 0.50 Sec No loss of communication	>= 16 failures out of 20 samples. Performed on every received message >= 6 Rolling count errors out of 10 samples. Performed on every received message >=6 range errors out of 10 samples. Performed on every received message >=3 multi-transitions out of 5 samples. Performed every 200 msec	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Control Module Power Off Timer Performance	P262B	This DTC determines if the hardware timer does not initialize or count properly. There are two tests to ensure proper functioning of the timer: Count Up Test (CUT) and Range Test (RaTe). Count Up Test (CUT): Verifies that the HWIO timer is counting up with the proper increment. Range Test (RaTe): When the run/crank is not active both the hardware and mirror timers are started. The timers are compared when module shutdown is initiated or run/crank becomes active.	Count Up Test: Time difference between the current read and the previous read of the timer Range Test: The variation of the HWIO timer and mirror timer is	> 1.50 seconds > 0.25 %.			Count Up Test: 4 failures out of 20 samples 1 sec / sample Continuous while run/crank is not active and until controller shutdown is initiated. Range Test: Once per trip when controller shutdown is initiated or run/ crank becomes active.	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Malfunction Indicator Lamp (MIL) Control Circuit (ODM) Low	P263A	Detects an inoperative malfunction indicator lamp control circuit. This diagnostic reports the DTC when a short to ground is detected.	Voltage low during driver off state (indicates short-to-ground)	Short to ground: ≤ 0.5 Ω impedance between output and controller ground	Run/Crank Voltage Remote Vehicle Start is not active	Voltage ≥ 11.00 volts	1 failures out of 1 samples 50 ms / sample	Type B, No MIL NO MIL Note: In certain controllers P0650 may also set (MIL Control Open Circuit)

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Malfunction Indicator Lamp (MIL) Control Circuit (ODM) High	P263B	Detects an inoperative malfunction indicator lamp control circuit. This diagnostic reports the DTC when a short to power is detected.	Voltage high during driver on state (indicates short to power)	Short to power: ≤ 0.5 Ω impedance between output and controller power	Run/Crank Voltage Remote Vehicle Start is not active	Voltage ≥ 11.00 volts	4 failures out of 5 samples 50 ms / sample	Type B, No MIL NO MIL

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Control Module Communication on Bus A Off	U0073	This DTC monitors for a BUS A off condition	Bus off failures equals or exceeds	5 counts (equivalent to 0.83 seconds)	General Enable Criteria:		Diagnostic runs in 12.5 ms loop	Type A, 1 Trips
					Starter motor engaged for Or	> 15.00 milliseconds		
					Run/Crank ignition voltage	> 8.41 Volts		
			before the sample time of is reached	0.83 seconds				
					All below criteria have been met for	>= 5.00 seconds		
					Normal CAN transmission on Bus	Enabled		
					Controller not in programming mode			
					If bus type = Sensor Bus:			
					Sensor bus relay is on			
					Otherwise:			
					If power mode = Run/ Crank:			
					Power Mode	= Run		
					If calibratable low voltage disable mode is not Never Disabled			
					Low voltage disable mode: OBDII			
					If OBDII: Run/Crank ignition voltage	>= 11.00 Volts		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					If EOBD: Run/Crank ignition voltage If Secure: Starter motor engaged for Or Run/Crank ignition voltage If Hybrid Secure: Run/Crank ignition voltage If power mode = Accessory Off key cycle diagnostics are enabled Or Controller is an OBD controller Controller shutdown impending Power Mode Battery voltage	>= 9.00 Volts > 15.00 milliseconds > 8.41 Volts >= 6.41 Volts Enabled OBD Controller = False = Not crank >= 11.00 Volts		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Lost Communication With TCM	U0101	This DTC monitors for a loss of communication with the Transmission Control Module.	Message is not received from controller for		General Enable Criteria:		Diagnostic runs in 12.5 ms loop	Type A, 1 Trips
					If message is on Bus A:			
			Message $0C7	≥ 0.50 seconds	U0073	Not Active		
			Message $0F9	≥ 0.50 seconds	If message is on Bus B:			
					U0074	Not Active		
			Message $189	≥ 0.50 seconds	If message is on Bus S:			
			Message $19D	≥ 0.50 seconds	U0076	Not Active		
			Message $1A6	≥ 0.50 seconds	Starter motor engaged for	> 15.00 milliseconds		
					Or			
			Message $1AF	≥ 0.50 seconds	Run/Crank ignition voltage	> 8.41 Volts		
			Message $1F5	≥ 0.50 seconds				
					Bus is enabled for	>= 0.40 seconds		
			Message $4C9	≥ 10.00 seconds				
					The following criteria have been enabled for	>= 5.00 seconds		
					Normal CAN transmission on Bus	Enabled		
					Transition from accessory mode to off is pending	= False		
					Controller not in programming mode			
					If bus type = Sensor Bus:			
					Battery voltage	> 11.00 Volts		
					Sensor Bus Relay	= On		
					Otherwise:			

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					If power mode = Run/ Crank:			
					Power Mode	= Run		
					If calibratable low voltage disable mode is not Never Disabled			
					Low voltage disable mode: OBDII			
					If OBDII:			
					Run/Crank ignition voltage	>= 11.00 Volts		
					If EOBD:			
					Run/Crank ignition voltage	>= 9.00 Volts		
					If Secure:			
					Starter motor engaged for Or	> 15.00 milliseconds		
					Run/Crank ignition voltage	> 8.41 Volts		
					If Hybrid Secure:			
					Run/Crank ignition voltage	>= 6.41 Volts		
					If power mode = Accessory			
					Off key cycle diagnostics are enabled Or	Enabled		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Controller is an OBD controller	OBD Controller		
					Controller shutdown impending	= False		
					Power Mode	= Not crank		
					Battery voltage	>= 11.00 Volts		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Lost Communication With Anti-Lock Brake System (ABS) Control Module	U0121	This DTC monitors for a loss of communication with the Anti-Lock Brake System (ABS) Control Module (Non-OBD Module ID 243).	Message is not received from controller for		General Enable Criteria:		Diagnostic runs in 12.5 ms loop	Type C, No SVS "Emissions Neutral Diagnostics – Type C"
					If message is on Bus A:			
			Message $0C1	≥ 0.50 seconds	U0073	Not Active		
					If message is on Bus B:			
			Message $0C5	≥ 0.50 seconds	U0074	Not Active		
			Message $1C7	≥ 0.50 seconds	If message is on Bus S:			
			Message $1E9	≥ 0.50 seconds	U0076	Not Active		
					Starter motor engaged for	> 15.00 milliseconds		
					Or			
					Run/Crank ignition voltage	> 8.41 Volts		
					Bus is enabled for	>= 0.40 seconds		
					The following criteria have been enabled for	>= 5.00 seconds		
					Normal CAN transmission on Bus	Enabled		
					Transition from accessory mode to off is pending	= False		
					Controller not in programming mode			
					If bus type = Sensor Bus:			
					Battery voltage	> 11.00 Volts		
					Sensor Bus Relay	= On		
					Otherwise:			
					If power mode = Run/ Crank:			

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Power Mode	= Run		
					If calibratable low voltage disable mode is not Never Disabled			
					Low voltage disable mode: OBDII			
					If OBDII: Run/Crank ignition voltage	>= 11.00 Volts		
					If EOBD: Run/Crank ignition voltage	>= 9.00 Volts		
					If Secure: Starter motor engaged for	> 15.00 milliseconds		
					Or			
					Run/Crank ignition voltage	> 8.41 Volts		
					If Hybrid Secure: Run/Crank ignition voltage	>= 6.41 Volts		
					If power mode = Accessory			
					Off key cycle diagnostics are enabled	Enabled		
					Or			
					Controller is an OBD controller	OBD Controller		
					Controller shutdown impending	= False		
					Power Mode	= Not crank		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Battery voltage	>= 11.00 Volts		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Lost Communication With Power Steering Control Module	U0131	This DTC monitors for a loss of communication with the Power Steering Control Module	Message is not received from controller for Message $1E5	 ≥ 10.00 seconds	General Enable Criteria: If message is on Bus A: U0073 If message is on Bus B: U0074 If message is on Bus S: U0076 Starter motor engaged for Or Run/Crank ignition voltage Bus is enabled for The following criteria have been enabled for Normal CAN transmission on Bus Transition from accessory mode to off is pending Controller not in programming mode If bus type = Sensor Bus: Battery voltage Sensor Bus Relay Otherwise: If power mode = Run/ Crank:	 Not Active Not Active Not Active > 15.00 milliseconds > 8.41 Volts >= 0.40 seconds >= 5.00 seconds Enabled = False > 11.00 Volts = On	Diagnostic runs in 12.5 ms loop	Type C, No SVS "Safety Emissions Neutral Diagnostic"

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Power Mode	= Run		
					If calibratable low voltage disable mode is not Never Disabled			
					Low voltage disable mode: OBDII			
					If OBDII: Run/Crank ignition voltage	>= 11.00 Volts		
					If EOBD: Run/Crank ignition voltage	>= 9.00 Volts		
					If Secure: Starter motor engaged for	> 15.00 milliseconds		
					Or			
					Run/Crank ignition voltage	> 8.41 Volts		
					If Hybrid Secure: Run/Crank ignition voltage	>= 6.41 Volts		
					If power mode = Accessory			
					Off key cycle diagnostics are enabled	Enabled		
					Or			
					Controller is an OBD controller	OBD Controller		
					Controller shutdown impending	= False		
					Power Mode	= Not crank		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Battery voltage	>= 11.00 Volts		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Lost Communication With Body Control Module	U0140	This DTC monitors for a loss of communication with the Body Control Module.	Message is not received from controller for Message $0F1 Message $1E1 Message $1F1 Message $451	 ≥ 0.50 seconds ≥ 0.50 seconds ≥ 0.50 seconds ≥ 0.50 seconds	General Enable Criteria: If message is on Bus A: U0073 If message is on Bus B: U0074 If message is on Bus S: U0076 Starter motor engaged for Or Run/Crank ignition voltage Bus is enabled for The following criteria have been enabled for Normal CAN transmission on Bus Transition from accessory mode to off is pending Controller not in programming mode If bus type = Sensor Bus: Battery voltage Sensor Bus Relay Otherwise: If power mode = Run/ Crank:	 Not Active Not Active Not Active > 15.00 milliseconds > 8.41 Volts >= 0.40 seconds >= 5.00 seconds Enabled = False > 11.00 Volts = On	Diagnostic runs in 12.5 ms loop	Type C, No SVS "Emissions Neutral Diagnostics – Type C"

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Power Mode	= Run		
					If calibratable low voltage disable mode is not Never Disabled			
					Low voltage disable mode: OBDII			
					If OBDII: Run/Crank ignition voltage	>= 11.00 Volts		
					If EOBD: Run/Crank ignition voltage	>= 9.00 Volts		
					If Secure: Starter motor engaged for	> 15.00 milliseconds		
					Or			
					Run/Crank ignition voltage	> 8.41 Volts		
					If Hybrid Secure: Run/Crank ignition voltage	>= 6.41 Volts		
					If power mode = Accessory			
					Off key cycle diagnostics are enabled	Enabled		
					Or			
					Controller is an OBD controller	OBD Controller		
					Controller shutdown impending	= False		
					Power Mode	= Not crank		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Battery voltage	>= 11.00 Volts		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Lost Communication With Gateway A	U0146	This DTC monitors for a loss of communication with Gateway A.	Message is not received from controller for Message $3CF	 ≥ 10.00 seconds	General Enable Criteria: If message is on Bus A: U0073 If message is on Bus B: U0074 If message is on Bus S: U0076 Starter motor engaged for Or Run/Crank ignition voltage Bus is enabled for The following criteria have been enabled for Normal CAN transmission on Bus Transition from accessory mode to off is pending Controller not in programming mode If bus type = Sensor Bus: Battery voltage Sensor Bus Relay Otherwise: If power mode = Run/ Crank:	 Not Active Not Active Not Active > 15.00 milliseconds > 8.41 Volts >= 0.40 seconds >= 5.00 seconds Enabled = False > 11.00 Volts = On	Diagnostic runs in 12.5 ms loop	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Power Mode	= Run		
					If calibratable low voltage disable mode is not Never Disabled			
					Low voltage disable mode: OBDII			
					If OBDII: Run/Crank ignition voltage	>= 11.00 Volts		
					If EOBD: Run/Crank ignition voltage	>= 9.00 Volts		
					If Secure: Starter motor engaged for	> 15.00 milliseconds		
					Or			
					Run/Crank ignition voltage	> 8.41 Volts		
					If Hybrid Secure: Run/Crank ignition voltage	>= 6.41 Volts		
					If power mode = Accessory			
					Off key cycle diagnostics are enabled	Enabled		
					Or			
					Controller is an OBD controller	OBD Controller		
					Controller shutdown impending	= False		
					Power Mode	= Not crank		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Battery voltage	>= 11.00 Volts		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Lost Communication with Throttle Position Sensor 1	U0606	Detects a continuous or intermittent short low or short high or open fault in the TPS SENT Communication Circuit 1 by monitoring the voltage and failing the diagnostic when the voltage for the wave pulse is below or above state threshold as defined by SAE J2716 SENT Protocol. Detects a message fault in the TPS SENT Communication Circuit by monitoring the message pulse time and failing the diagnostic when the time for the pulse is below a low time threshold or above a high time threshold or if the message age limit is greater than a time threshold. This diagnostic only runs when battery voltage is high enough.	Voltage for wave pulse is below state threshold as defined by SAE J2716 SENT Protocol OR Voltage for wave pulse is above state threshold as defined by SAE J2716 SENT Protocol OR Message Pulse < Message Pulse > OR Message Age Limit >= OR Signal CRC fails	0.5 V OR 4.1 V OR 0.125977 ms 0.209991 ms OR 3.125 ms	Run/Crank voltage	> 6.41 Volts	79 / 159 counts; 57 counts continuous; 3.125 ms /count in the ECM main processor	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Lost Communication with Throttle Position Sensor 2	U0607	Detects a continuous or intermittent short low or short high or open fault in the TPS SENT Communication Circuit 2 by monitoring the voltage and failing the diagnostic when the voltage for the wave pulse is below or above state threshold as defined by SAE J2716 SENT Protocol. Detects a message fault in the TPS SENT Communication Circuit by monitoring the message pulse time and failing the diagnostic when the time for the pulse is below a low time threshold or above a high time threshold or if the message age limit is greater than a time threshold. This diagnostic only runs when battery voltage is high enough.	Voltage for wave pulse is below state threshold as defined by SAE J2716 SENT Protocol OR Voltage for wave pulse is above state threshold as defined by SAE J2716 SENT Protocol OR Message Pulse < Message Pulse > OR Message Age Limit >= OR Signal CRC fails	0.5 V OR 4.1 V OR 0.125977 ms 0.209991 ms OR 3.125 ms	Run/Crank voltage	> 6.41 Volts	79 / 159 counts; 57 counts continuous; 3.125 ms /count in the ECM main processor	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
CGM Lost Communication with ECM	U18D5	This DTC monitors for a CGM Lost Communication with ECM error as determined by the CGM	The CGM Diagnostic Status Message signal in GMLAN frame $3CF indicates that the CGM Lost Communication with ECM DTC has set in the CGM.		General Enable Criteria:		Diagnostic runs in 12.5 ms loop	Type B, 2 Trips
					Message $3CF	is being received		
					Central Gateway Module	is present on the bus		
					ECM	is present on the bus		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
CGM Lost Communication with TCM	U18D7	This DTC monitors for a CGM Lost Communication with TCM error as determined by the CGM	The CGM Diagnostic Status Message signal in GMLAN frame $3CF indicates that the CGM Lost Communication with TCM DTC has set in the CGM.		General Enable Criteria: Message $3CF Central Gateway Module TCM	 is being received is present on the bus is present on the bus	Diagnostic runs in 12.5 ms loop	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Central Gateway Module High Speed CAN Bus Off	U2413	This DTC monitors for a Central Gateway Module High Speed CAN Bus Off error as determined by the CGM	The CGM Diagnostic Status Message signal in GMLAN frame $3CF indicates that the Central Gateway Module High Speed CAN Bus Off DTC has set in the CGM.		General Enable Criteria: Message $3CF Central Gateway Module	 is being received is present on the bus	Diagnostic runs in 12.5 ms loop	Type B, 2 Trips

Initial Supporting table - CalculatedPerfMaxEc1

Description: Maximum desired camshaft position for Exhaust CAM - Bank1

Value Units: Maximum desired camshaft position (degCam)
X Unit: Engine Oil Temperature (degC)
[1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17]
[-40 -28 -16 -4 8 20 32 44 56 68 80 92 104 116 128 140 152]

Y Units: Engine Speed (rpm)
[1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17]
[400 800 1200 1600 2000 2400 2800 3200 3600 4000 4400 4800 5200 5600 6000 6400 6800]

y/x	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17
1	11.5	11.5	11.5	22.5	24.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5
2	11.5	11.5	11.5	22.5	24.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5
3	11.5	11.5	11.5	22.5	24.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5
4	11.5	11.5	11.5	22.5	24.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5
5	11.5	11.5	11.5	22.5	24.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5
6	11.5	11.5	11.5	22.5	24.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5
7	11.5	11.5	11.5	22.5	24.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5
8	11.5	11.5	11.5	22.5	24.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5
9	11.5	11.5	11.5	22.5	24.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5
10	11.5	11.5	11.5	22.5	24.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5
11	11.5	11.5	11.5	22.5	24.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5
12	11.5	11.5	11.5	22.5	24.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5
13	11.5	11.5	11.5	22.5	24.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5
14	11.5	11.5	11.5	22.5	24.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5
15	11.5	11.5	11.5	22.5	24.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5
16	11.5	11.5	11.5	22.5	24.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5
17	11.5	11.5	11.5	22.5	24.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5

Initial Supporting table - CalculatedPerfMaxIc1

Description: Maximum desired camshaft position for Intake CAM - Bank1

Value Units: Maximum desired camshaft position (degCam)
X Unit: Engine Oil Temperature (degC)
[1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17]
[-40 -28 -16 -4 8 20 32 44 56 68 80 92 104 116 128 140 152]
Y Units: Engine Speed (rpm)
[1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17]
[400 800 1200 1600 2000 2400 2800 3200 3600 4000 4400 4800 5200 5600 6000 6400 6800]

y/x	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17
1	11.5	11.5	11.5	22.5	24.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5
2	11.5	11.5	11.5	22.5	24.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5
3	11.5	11.5	11.5	22.5	24.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5
4	11.5	11.5	11.5	22.5	24.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5
5	11.5	11.5	11.5	22.5	24.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5
6	11.5	11.5	11.5	22.5	24.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5
7	11.5	11.5	11.5	22.5	24.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5
8	11.5	11.5	11.5	22.5	24.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5
9	11.5	11.5	11.5	22.5	24.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5
10	11.5	11.5	11.5	22.5	24.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5
11	11.5	11.5	11.5	22.5	24.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5
12	11.5	11.5	11.5	22.5	24.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5
13	11.5	11.5	11.5	22.5	24.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5
14	11.5	11.5	11.5	22.5	24.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5
15	11.5	11.5	11.5	22.5	24.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5
16	11.5	11.5	11.5	22.5	24.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5
17	11.5	11.5	11.5	22.5	24.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.5

Initial Supporting table - P0521_P06DD_P06DE_OP_HiStatePressure

Description: Two Stage Oil Pump Oil Pressure in High State

Value Units: Nominal high state oil pressure (kPa)
X Unit: Engine oil temperature (deg C)

y/x	0.0	20.0	40.0	60.0	80.0	90.0	100.0	110.0	120.0
1,000.0	471.0	434.0	416.0	400.0	396.0	370.0	340.0	310.0	290.0
1,250.0	481.0	448.0	425.0	417.0	406.0	384.0	372.0	350.0	315.0
1,500.0	487.0	455.0	432.0	431.0	419.0	403.0	395.0	387.0	350.0
2,000.0	498.0	464.0	449.0	445.0	441.0	424.0	415.0	402.0	380.0
2,500.0	533.0	481.0	466.0	460.0	452.0	439.0	432.0	418.0	406.0
3,000.0	546.0	489.0	479.0	475.0	463.0	445.0	438.0	426.0	414.0
3,500.0	540.0	484.0	485.0	480.0	458.0	448.0	440.0	425.0	418.0
4,000.0	540.0	482.0	488.0	481.0	458.0	446.0	441.0	434.0	425.0
4,500.0	540.0	480.0	491.0	482.0	456.0	442.0	443.0	432.0	425.0

Initial Supporting table - P0521_P06DD_P06DE_OP_LoStatePressure

Description: Two Stage Oil Pump Oil Pressure in Low State

Value Units: Nominal low state oil pressure (kPa)
X Unit: Engine oil temperature (deg C)

y/x	0	20	40	60	80	90	100	110	120
1,000	256	242	231	226	217	211	205	201	188
1,250	259	246	235	232	224	219	214	210	197
1,500	261	247	238	237	231	227	223	216	206
2,000	267	252	243	243	238	234	229	222	216
2,500	280	257	249	247	242	237	234	223	213
3,000	280	261	251	249	243	240	237	230	223
3,500	280	260	253	252	245	242	238	234	230
4,000	280	260	254	253	246	242	239	235	230
4,500	280	261	255	255	246	242	240	235	230

Initial Supporting table - P06DD_P06DE_MaxEnableTorque_OP

Description: Two Stage Oil Pump Rationality Test Torque Max Enable Threshold

Value Units: Maximum engine torque (Nm)
X Unit: Engine speed (RPM)

y/x	1,000.0	1,250.0	1,500.0	1,750.0	2,000.0	2,250.0	2,500.0	2,750.0	3,000.0
1.0	0.0	0.0	100.0	100.0	100.0	100.0	100.0	0.0	0.0

Initial Supporting table - P06DD_P06DE_MinEnableTorque_OP

Description: Two Stage Oil Pump Rationality Test Torque Min Enable Threshold

Value Units: Min engine torque (Nm)
X Unit: Engine speed (RPM)

y/x	1,000.0	1,250.0	1,500.0	1,750.0	2,000.0	2,250.0	2,500.0	2,750.0	3,000.0
1.0	0.0	0.0	20.0	20.0	20.0	20.0	20.0	0.0	0.0

Initial Supporting table - P06DD_P06DE_MinOilPressThresh

Description: Intrusive diagnostic minimum pressure limit that is a function of Engine Speed and Oil Temperature

Value Units: Minimum engine oil pressure threshold (kPa)
X Unit: Engine oil temperature (deg C)

y/x	0	20	40	60	80	90	100	110	120
1,000	150	150	150	150	150	150	150	150	150
1,250	150	150	150	150	150	150	150	150	150
1,500	150	150	150	150	150	150	150	150	150
2,000	150	150	150	150	150	150	150	150	150
2,500	150	150	150	150	150	150	150	150	150
3,000	150	150	150	150	150	150	150	150	150
3,500	150	150	150	150	150	150	150	150	150
4,000	150	150	150	150	150	150	150	150	150
4,500	150	150	150	150	150	150	150	150	150

Initial Supporting table - P06DD_P06DE_OP_StateChangeMin

Description: Minimum allowed pressure change on a Two Stage Oil Pump state change

Value Units: Min pressure change (kPa)
X Unit: Engine oil temperature (deg C)

y/x	0.0	20.0	40.0	60.0	80.0	90.0	100.0	110.0	120.0
1,000.0	107.5	96.0	92.5	87.0	70.5	52.0	37.5	22.0	6.0
1,250.0	111.0	101.0	95.0	92.5	83.0	74.0	60.0	47.5	27.5
1,500.0	113.0	104.0	97.0	97.0	90.0	85.0	81.0	65.0	52.0
2,000.0	115.5	106.0	103.0	101.0	96.0	93.0	91.0	73.5	55.5
2,500.0	126.5	112.0	108.5	106.5	101.5	100.0	96.5	84.0	71.0
3,000.0	133.0	114.0	114.0	113.0	107.0	102.5	97.5	89.0	81.0
3,500.0	130.0	112.0	116.0	114.0	106.5	103.0	100.0	95.5	91.5
4,000.0	130.0	111.0	117.0	114.0	108.0	105.0	101.0	97.0	93.5
4,500.0	130.0	109.5	118.0	113.5	109.5	106.5	101.5	98.5	95.5

Initial Supporting table - Multiple DTC Use - Block learn cells to enable Post oxygen sensor tests

Description: This table describes the adaptive (Block Learn) cells in which to enable the Post (Secondary) Oxygen sensor response tests.
Note: When the table column heading matches the calibration value below it, that individual cell is enabled.

The cell numbers in the table are defined as:
CeFADR_e_Cell00_PurgOnAirMode5 = 0,
CeFADR_e_Cell01_PurgOnAirMode4 = 1,
CeFADR_e_Cell02_PurgOnAirMode3 = 2,
CeFADR_e_Cell03_PurgOnAirMode2 = 3,
CeFADR_e_Cell04_PurgOnAirMode1 = 4,
CeFADR_e_Cell05_PurgOnAirMode0 = 5,
CeFADR_e_Cell06_PurgOnIdle = 6,
CeFADR_e_Cell07_PurgOnDecel = 7,
CeFADR_e_Cell08_PurgOffAirMode5 = 8,
CeFADR_e_Cell09_PurgOffAirMode4 = 9,
CeFADR_e_Cell10_PurgOffAirMode3 = 10,
CeFADR_e_Cell11_PurgOffAirMode2 = 11,
CeFADR_e_Cell12_PurgOffAirMode1 = 12,
CeFADR_e_Cell13_PurgOffAirMode0 = 13,
CeFADR_e_Cell14_PurgOffIdle = 14,
CeFADR_e_Cell15_PurgOffDecel = 15

Value Units: Block Learn cell number
X Unit: Block Learn cell number

y/x	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	7	7	7	7	7	7	7	7	15	15	15	15	15	15	15	15

Initial Supporting table - Multiple DTC Use - Response Cell Enable Table

Description: This table describes the Block learn cells which enable the Pre (Primary) Oxygen sensor response tests.
Note: When the table column heading matches the calibration value below it, that individual cell is enabled.

Value Units: Block Learn cell name and number
X Unit: Block Learn cell name and number

Multiple DTC Use - Response Cell Enable Table - Part 1

y/x	CeFADR_e_Cell00_PurgOnAirMode5	CeFADR_e_Cell01_PurgOnAirMode4	CeFADR_e_Cell02_PurgOnAirMode3	CeFADR_e_Cell03_PurgOnAirMode2
1	CeFADR_e_Cell00_PurgOnAirMode5	CeFADR_e_Cell01_PurgOnAirMode4	CeFADR_e_Cell02_PurgOnAirMode3	CeFADR_e_Cell03_PurgOnAirMode2

Multiple DTC Use - Response Cell Enable Table - Part 2

y/x	CeFADR_e_Cell04_PurgOnAirMode1	CeFADR_e_Cell05_PurgOnAirMode0	CeFADR_e_Cell06_PurgOnIdle	CeFADR_e_Cell07_PurgOnDecel
1	CeFADR_e_Cell04_PurgOnAirMode1	CeFADR_e_Cell05_PurgOnAirMode0	CeFADR_e_Cell00_PurgOnAirMode5	CeFADR_e_Cell00_PurgOnAirMode5

Multiple DTC Use - Response Cell Enable Table - Part 3

y/x	CeFADR_e_Cell08_PurgOffAirMode5	CeFADR_e_Cell09_PurgOffAirMode4	CeFADR_e_Cell10_PurgOffAirMode3	CeFADR_e_Cell11_PurgOffAirMode2
1	CeFADR_e_Cell08_PurgOffAirMode5	CeFADR_e_Cell09_PurgOffAirMode4	CeFADR_e_Cell10_PurgOffAirMode3	CeFADR_e_Cell11_PurgOffAirMode2

Multiple DTC Use - Response Cell Enable Table - Part 4

y/x	CeFADR_e_Cell12_PurgOffAirMode1	CeFADR_e_Cell13_PurgOffAirMode0	CeFADR_e_Cell14_PurgOffIdle	CeFADR_e_Cell15_PurgOffDecel
1	CeFADR_e_Cell12_PurgOffAirMode1	CeFADR_e_Cell13_PurgOffAirMode0	CeFADR_e_Cell08_PurgOffAirMode5	CeFADR_e_Cell08_PurgOffAirMode5

Initial Supporting table - Multiple DTC Use_Green Sensor Delay Criteria - Limit

Description: This Calibration is the acculmulated airflow limit above which the Green condition is expired
Used for: P0133, P013A, P013B, P013C, P013D, P013E, P013F, P014A, P014B, P0153, P015A, P015B, P015C, P015D, P1133, P1153, P2270, P2271, P2272 and P2273.
Note: This feature is only enabled when the vehicle is new and cannot be enabled in service.

Value Units: Grams
X Unit: Acculmulated Engine Airflow

y/x	CiOXYR_O2_Bank1_Sensor1	CiOXYR_O2_Bank1_Sensor2	CiOXYR_O2_Bank2_Sensor1	CiOXYR_O2_Bank2_Sensor2
1	120,000	120,000	120,000	120,000

Initial Supporting table - P0011_CamPosErrorLimIc1

Description: Maximum Intake Cam 1 phase error as a function of engine speed and engine oil temperature.

Value Units: Maximum Intake Cam 1 phase error (degCAM)
X Unit: Engine Oil Temperature (degC)
Y Units: Engine Speed (rpm)

y/x	-40	-28	-16	-4	8	20	32	44	56	68	80	92	104	116	128	140	152
400	21.0	21.0	21.0	10.0	8.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0
800	21.0	21.0	21.0	10.0	8.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0
1,200	21.0	21.0	21.0	10.0	8.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0
1,600	21.0	21.0	21.0	10.0	8.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0
2,000	21.0	21.0	21.0	10.0	8.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0
2,400	21.0	21.0	21.0	10.0	8.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0
2,800	21.0	21.0	21.0	10.0	8.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0
3,200	21.0	21.0	21.0	10.0	8.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0
3,600	21.0	21.0	21.0	10.0	8.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0
4,000	21.0	21.0	21.0	10.0	8.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0
4,400	21.0	21.0	21.0	10.0	8.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0
4,800	21.0	21.0	21.0	10.0	8.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0
5,200	21.0	21.0	21.0	10.0	8.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0
5,600	21.0	21.0	21.0	10.0	8.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0
6,000	21.0	21.0	21.0	10.0	8.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0
6,400	21.0	21.0	21.0	10.0	8.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0
6,800	21.0	21.0	21.0	10.0	8.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0

Initial Supporting table - P0011_P0021_P05CC_P05CD_EngOilPressEnblIc

Description: Delay time before the oil pressure enable flag is set assuming all the oil pressure enable criteria are met

Value Units: Time (sec)
X Unit: Engine Coolant Temperature (degC)

y/x	-40	-28	-16	-4	8	20	32	44	56	68	80	92	104	116	128	140	152
1	30	25	10	10	10	10	10	3	2	2	2	2	2	2	3	3	3

Initial Supporting table - P0011_P0021_P05CC_P05CD_HiEngSpdHiDsblIc

Description: Minimum engine speed to disable Intake cam

Value Units: Engine Speed (rpm)
X Unit: Engine Oil Temp (degC)

y/x	-40	-28	-16	-4	8	20	32	44	56	68	80	92	104	116	128	140	152
1	8,000	8,000	8,000	8,000	8,000	8,000	8,000	8,000	8,000	8,000	8,000	8,000	8,000	8,000	8,000	8,000	8,000

Initial Supporting table - P0011_P0021_P05CC_P05CD_HiEngSpdLoEnblIc

Description: Maximum engine speed to enable Intake cam - works as hysteresis.

Value Units: Engine Speed (rpm)
X Unit: Engine Oil Temp (degC)

y/x	-40	-28	-16	-4	8	20	32	44	56	68	80	92	104	116	128	140	152
1	7,800	7,800	7,800	7,800	7,800	7,800	7,800	7,800	7,800	7,800	7,800	7,800	7,800	7,800	7,800	7,800	7,800

Initial Supporting table - P0011_P0021_P05CC_P05CD_LoPresHiEnblIc

Description: Intake cam is enabled when oil pressure exceeds this value

Value Units: Engine Speed (rpm)
X Unit: Engine Oil Temp (degC)

y/x	-40	-28	-16	-4	8	20	32	44	56	68	80	92	104	116	128	140	152
1	180	180	180	180	180	180	180	180	180	180	180	180	180	180	180	180	180

Initial Supporting table - P0011_P0021_P05CC_P05CD_LoPresLoDsblIc

Description: Intake cam is disabled when oil pressure falls below this value

Value Units: Engine Oil Pressure (kPa)
X Unit: Engine Oil Temp (degC)

y/x	-40	-28	-16	-4	8	20	32	44	56	68	80	92	104	116	128	140	152
1	150	150	150	150	150	150	150	150	150	150	150	150	150	150	150	150	150

Initial Supporting table - P0011_P0021_P05CC_P05CD_LoRpmHiEnblIc

Description: Intake cam is enabled when engine speed exceeds this value.

Value Units: Engine Speed (rpm)
X Unit: Engine Oil Temp (degC)

y/x	-40	-28	-16	-4	8	20	32	44	56	68	80	92	104	116	128	140	152
1	500	500	500	500	500	500	500	500	500	500	500	500	500	500	500	500	500

Initial Supporting table - P0011_P0021_P05CC_P05CD_LoRpmLoDsblIc

Description: Intake cam is disabled when engine speed is below this value.

Value Units: Engine Speed (rpm)
X Unit: Engine Oil Temp (degC)

y/x	-40	-28	-16	-4	8	20	32	44	56	68	80	92	104	116	128	140	152
1	450	450	450	450	450	450	450	450	450	450	450	450	450	450	450	450	450

Initial Supporting table - P0011_P0021_P05CC_P05CD_P0014_P0024_P05CE_P05CF_ColdStartEngRunning

Description: Engine running time must be greater than this threshold during a cold start to enable cam phasing

Value Units: Time (sec)
X Unit: Engine Oil Temp (degC)

y/x	-40	-28	-16	-4	8	20	32	44	56	68	80	92	104	116	128	140	152
1	3	3	3	3	3	2	2	1	0	0	0	0	0	0	0	0	0

Initial Supporting table - P0011_P05CC_StablePositionTimeIc1

Description: Minimum time for Intake Cam 1 phase position to be stable to enable performance diagnostic.

Value Units: Minimum time (sec)
X Unit: Engine Oil Temperature (degC)
Y Units: Engine Speed (rpm)

y/x	-40	-28	-16	-4	8	20	32	44	56	68	80	92	104	116	128	140	152
400	30.0	20.0	10.0	5.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	7.0	10.0
800	30.0	20.0	10.0	5.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	7.0	10.0
1,200	30.0	20.0	10.0	5.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	7.0	10.0
1,600	30.0	20.0	10.0	5.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	7.0	10.0
2,000	30.0	20.0	10.0	5.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	7.0	10.0
2,400	30.0	20.0	10.0	5.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	7.0	10.0
2,800	30.0	20.0	10.0	5.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	7.0	10.0
3,200	30.0	20.0	10.0	5.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	7.0	10.0
3,600	30.0	20.0	10.0	5.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	7.0	10.0
4,000	30.0	20.0	10.0	5.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	7.0	10.0
4,400	30.0	20.0	10.0	5.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	7.0	10.0
4,800	30.0	20.0	10.0	5.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	7.0	10.0
5,200	30.0	20.0	10.0	5.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	7.0	10.0
5,600	30.0	20.0	10.0	5.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	7.0	10.0
6,000	30.0	20.0	10.0	5.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	7.0	10.0
6,400	30.0	20.0	10.0	5.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	7.0	10.0
6,800	30.0	20.0	10.0	5.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	7.0	10.0

Initial Supporting table - P0014_CamPosErrorLimEc1

Description: Maximum Exhaust Cam 1 phase error as a function of engine speed and engine oil temperature.

Value Units: Maximum Exhaust Cam 1 phase error (degCAM)
X Unit: Engine Oil Temperature (degC)
Y Units: Engine Speed (rpm)

y/x	-40	-28	-16	-4	8	20	32	44	56	68	80	92	104	116	128	140	152
400	21.0	21.0	21.0	10.0	8.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0
800	21.0	21.0	21.0	10.0	8.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0
1,200	21.0	21.0	21.0	10.0	8.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0
1,600	21.0	21.0	21.0	10.0	8.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0
2,000	21.0	21.0	21.0	10.0	8.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0
2,400	21.0	21.0	21.0	10.0	8.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0
2,800	21.0	21.0	21.0	10.0	8.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0
3,200	21.0	21.0	21.0	10.0	8.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0
3,600	21.0	21.0	21.0	10.0	8.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0
4,000	21.0	21.0	21.0	10.0	8.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0
4,400	21.0	21.0	21.0	10.0	8.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0
4,800	21.0	21.0	21.0	10.0	8.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0
5,200	21.0	21.0	21.0	10.0	8.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0
5,600	21.0	21.0	21.0	10.0	8.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0
6,000	21.0	21.0	21.0	10.0	8.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0
6,400	21.0	21.0	21.0	10.0	8.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0
6,800	21.0	21.0	21.0	10.0	8.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0

Initial Supporting table - P0014_P0024_P05CE_P05CF_EngOilPressEnblEc

Description: Delay time before the oil pressure enable flag is set assuming all the oil pressure enable criteria are met

Value Units: Time (sec)
X Unit: Engine Coolant Temperature (degC)

y/x	-40	-28	-16	-4	8	20	32	44	56	68	80	92	104	116	128	140	152
1	30	25	10	10	10	10	10	3	2	2	2	2	2	2	3	3	3

Initial Supporting table - P0014_P0024_P05CE_P05CF_HiEngSpdHiDsblEc

Description: Exhaust cam is disabled when engine speed exceeds this value

Value Units: Engine Speed (rpm)
X Unit: Engine Oil Temp (degC)

y/x	-40	-28	-16	-4	8	20	32	44	56	68	80	92	104	116	128	140	152
1	8,000	8,000	8,000	8,000	8,000	8,000	8,000	8,000	8,000	8,000	8,000	8,000	8,000	8,000	8,000	8,000	8,000

Initial Supporting table - P0014_P0024_P05CE_P05CF_HiEngSpdLoEnblEc

Description: Exhaust cam is enabled when engine speed remains below this value

Value Units: Engine Speed (rpm)
X Unit: Engine Oil Temp (degC)

y/x	-40	-28	-16	-4	8	20	32	44	56	68	80	92	104	116	128	140	152
1	7,800	7,800	7,800	7,800	7,800	7,800	7,800	7,800	7,800	7,800	7,800	7,800	7,800	7,800	7,800	7,800	7,800

Initial Supporting table - P0014_P0024_P05CE_P05CF_LoPresHiEnblEc

Description: Exhaust cam is enabled when oil pressure exceeds this value

Value Units: Engine Oil Pressure (kPa)
X Unit: Engine Oil Temp (degC)

y/x	-40	-28	-16	-4	8	20	32	44	56	68	80	92	104	116	128	140	152
1	180	180	180	180	180	180	180	180	180	180	180	180	180	180	180	180	180

Initial Supporting table - P0014_P0024_P05CE_P05CF_LoPresLoDsblEc

Description: Exhaust cam is disabled when oil pressure falls below this value

Value Units: Engine Oil Pressure (kPa)
X Unit: Engine Oil Temp (degC)

y/x	-40	-28	-16	-4	8	20	32	44	56	68	80	92	104	116	128	140	152
1	150	150	150	150	150	150	150	150	150	150	150	150	150	150	150	150	150

Initial Supporting table - P0014_P0024_P05CE_P05CF_LoRpmHiEnblEc

Description: Exhaust cam is enabled when engine speed exceeds this value.

Value Units: Engine Speed (rpm)
X Unit: Engine Oil Temp (degC)

y/x	-40	-28	-16	-4	8	20	32	44	56	68	80	92	104	116	128	140	152
1	500	500	500	500	500	500	500	500	500	500	500	500	500	500	500	500	500

Initial Supporting table - P0014_P0024_P05CE_P05CF_LoRpmLoDsblEc

Description: Exhaust cam is disabled when engine speed is below this value.

Value Units: Engine Speed (rpm)
X Unit: Engine Oil Temp (degC)

y/x	-40	-28	-16	-4	8	20	32	44	56	68	80	92	104	116	128	140	152
1	450	450	450	450	450	450	450	450	450	450	450	450	450	450	450	450	450

Initial Supporting table - P0014_P05CE_StablePositionTimeEc1

Description: Minimum time for Exhaust Cam 1 phase position to be stable to enable performance diagnostic.

Value Units: Minimum time (sec)
X Unit: Engine Oil Temperature (degC)
Y Units: Engine Speed (rpm)

y/x	-40	-28	-16	-4	8	20	32	44	56	68	80	92	104	116	128	140	152
400	30.0	20.0	10.0	5.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	7.0	10.0
800	30.0	20.0	10.0	5.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	7.0	10.0
1,200	30.0	20.0	10.0	5.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	7.0	10.0
1,600	30.0	20.0	10.0	5.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	7.0	10.0
2,000	30.0	20.0	10.0	5.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	7.0	10.0
2,400	30.0	20.0	10.0	5.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	7.0	10.0
2,800	30.0	20.0	10.0	5.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	7.0	10.0
3,200	30.0	20.0	10.0	5.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	7.0	10.0
3,600	30.0	20.0	10.0	5.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	7.0	10.0
4,000	30.0	20.0	10.0	5.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	7.0	10.0
4,400	30.0	20.0	10.0	5.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	7.0	10.0
4,800	30.0	20.0	10.0	5.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	7.0	10.0
5,200	30.0	20.0	10.0	5.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	7.0	10.0
5,600	30.0	20.0	10.0	5.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	7.0	10.0
6,000	30.0	20.0	10.0	5.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	7.0	10.0
6,400	30.0	20.0	10.0	5.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	7.0	10.0
6,800	30.0	20.0	10.0	5.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	3.0	7.0	10.0

Initial Supporting table - P0016, P0017, P0018, P0019: Cam Correlation Oil Temperature Threshold

Description: P0016, P0017, P0018, P0019: Cam Correlation Oil Temperature Threshold

Value Units: Engine Run Time- Seconds
X Unit: Oil Temperature- C

y/x	-40	-28	-16	-4	8	20	32	44	56	68	80	92	104	116	128	140	152
1	35.0	10.0	7.0	5.0	3.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	2.0	2.0

Initial Supporting table - P0016-0019 Mid-Park Phaser Delay

Description: P0016-0019 Mid-Park Phaser Park Delay. Total delay is twice the calibration value as both 'hi' side and 'lo' side park check sequences are delayed by the stated calibration values

Value Units: Time - seconds
X Unit: Oil Temperature - degC

y/x	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17
1	41.0	24.0	7.0	6.0	5.0	1.2	1.2	1.2	1.2	1.2	1.2	1.2	1.2	1.2	1.2	1.2	1.2

Initial Supporting table - P0101, P0106, P0121, P012B, P0236, P1101: MAP1 Residual Weight Factor based on RPM

Description: P0101_P0106_P0121_P012B_P0236_P1101 MAP1 Residual Weight Factor based on RPM

Value Units: Weight Factor (Unitless)
X Unit: Engine Speed (RPM)

y/x	0	400	800	1,200	1,600	2,000	2,400	2,800	3,200	3,600	4,000	4,400	4,800	5,200	5,600	6,000	6,500
1	0.850	0.850	0.850	0.900	0.900	0.900	0.950	0.950	0.950	0.950	0.950	0.950	0.950	0.950	0.950	0.950	0.950

Initial Supporting table - P0101, P0106, P0121, P012B, P0236, P1101: MAP2 Residual Weight Factor based on RPM

Description: P0101_P0106_P0121_P012B_P0236_P1101 MAP2 Residual Weight Factor based on RPM

Value Units: Weight Factor (Unitless)
X Unit: Engine Speed (RPM)

y/x	0	400	800	1,200	1,600	2,000	2,400	2,800	3,200	3,600	4,000	4,400	4,800	5,200	5,600	6,000	6,500
1	0.850	0.850	0.850	0.900	0.900	0.900	0.950	0.950	0.950	0.950	0.950	0.950	0.950	0.950	0.950	0.950	0.950

Initial Supporting table - P0101, P0106, P0121, P012B, P0236, P1101: TPS Residual Weight Factor based on RPM

Description: P0101_P0106_P0121_P012B_P0236_P1101 TPS Residual Weight Factor based on RPM

Value Units: Weight Factor (Unitless)
X Unit: Engine Speed (RPM)

y/x	0	400	800	1,200	1,600	2,000	2,400	2,800	3,200	3,600	4,000	4,400	4,800	5,200	5,600	6,000	6,500
1	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000

Initial Supporting table - P0133_KnEOSD_t_ST_LRC_LimRS1

Description: X Table Axis for P0133

Value Units: Seconds
X Unit: X Table Axis for P0133, L2R Response time breakpoints for table

y/x	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17
1	0.000	0.010	0.022	0.034	0.046	0.059	0.071	0.083	0.095	0.107	0.119	0.131	0.144	0.156	0.168	0.180	2.000

Initial Supporting table - P0133_KnEOSD_t_ST_RLC_LimRS1

Description: Y Table Axis for P0133

Value Units: Seconds
Y Units: Y Table Axis for P0133, R2L Response time breakpoints for table

y/x	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17
1	0.000	0.010	0.021	0.033	0.044	0.056	0.067	0.079	0.090	0.101	0.113	0.124	0.136	0.147	0.159	0.170	2.000

Initial Supporting table - P0133_O2S Slow Response Bank 1 Sensor 1 Pass/Fail Threshold table

Description: This table discribes the Pass and Fail regions based on the diagnostic test result

Value Units: If the cell contains a "0" then the fault is indicated, if it contains a "1" a fault is not indicated.
X Unit: X axis is Lean to Rich response time (in sec), Please see the table below named "KnEOSD_t_ST_LRC_LimRS1" for the 17 X axis table breakpoints.
Y Units: Y axis is Rich to Lean response time (in sec), Please see the table below named "KnEOSD_t_ST_RLC_LimRS1" for the 17 Y axis table breakpoints.

y/x	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16
0	1	1	1	1	1	1	1	1	1	1	1	0	0	0	0	0	0
1	1	1	1	1	1	1	1	1	1	1	1	1	0	0	0	0	0
2	1	1	1	1	1	1	1	1	1	1	1	1	1	0	0	0	0
3	1	1	1	1	1	1	1	1	1	1	1	1	1	1	0	0	0
4	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	0	0
5	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	0	0
6	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	0	0
7	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	0	0
8	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	0	0
9	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	0	0
10	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	0	0
11	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	0	0
12	0	1	1	1	1	1	1	1	1	1	1	1	1	1	1	0	0
13	0	0	1	1	1	1	1	1	1	1	1	1	1	1	1	0	0
14	0	0	0	1	1	1	1	1	1	1	1	1	1	1	1	0	0
15	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
16	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

Initial Supporting table - P050D_P1400_CatalystLightOffExtendedEngineRunTimeExit

Description: Exit Catalyst Warm-up mode if Engine Run Time is greater than this value. This table is based on percent ethanol (x-axis) and catmon's NormRatio_EWMA value (y-axis). The NormRatio_EWMA value determines the state of the catalyst. Typically, NormRatio_EWMA values below 0.35 (0 is bad and 1 is good) represent catalysts that have degraded. The emission performance of these degraded catalysts can be improved by extending catalyst light off of GetE85R_Pct_FFS_CompAtEngFloat.

y/x	0	25	50	75	100
0.000	20	20	20	20	20
0.125	20	20	20	20	20
0.250	20	20	20	20	20
0.375	20	20	20	20	20
0.500	20	20	20	20	20
0.625	20	20	20	20	20
0.750	20	20	20	20	20
0.875	20	20	20	20	20
1.000	20	20	20	20	20

Initial Supporting table - P1400_CatalystLightOffExtendedEngineRunTimeExit

Description: Exit Catalyst Warm-up mode if Engine Run Time is greater than this value. This table is based on percent ethanol (x-axis) and catmon's NormRatio_EWMA value (y-axis). The NormRatio_EWMA value determines the state of the catalyst. Typically, NormRatio_EWMA values below 0.35 (0 is bad and 1 is good) represent catalysts that have degraded. The emission performance of these degraded catalysts can be improved by extending catalyst light off of GetE85R_Pct_FFS_CompAtEngFloat.

y/x	0	25	50	75	100
0.000	20	20	20	20	20
0.125	20	20	20	20	20
0.250	20	20	20	20	20
0.375	20	20	20	20	20
0.500	20	20	20	20	20
0.625	20	20	20	20	20
0.750	20	20	20	20	20
0.875	20	20	20	20	20
1.000	20	20	20	20	20

Initial Supporting table - P1400_ColdStartDiagnosticDelayBasedOnEngineRunTime

Description: Quality weight-based on engine run time. This allows adjustment of the weighting factors at various engine run times in order to prevent the updating of the cumulative quality timer or to change the value of the average qualified residual energy calculation to prevent false Fails of the diagnostic under circumstances inappropriate to update the calculation of the average qualified residual value.

y/x	0	3	3	4	5	10	15	20	30
1	0	1	1	1	1	1	1	1	1

Initial Supporting table - P1400_ColdStartDiagnosticDelayBasedOnEngineRunTimeCalAxis

Description: This is the x-axis for the KtCSED_K_TimeWght calibration table. Refer to the description for KtCSED_K_TimeWght for details.

y/x	1	2	3	4	5	6	7	8	9
1	0	3	3	4	5	10	15	20	30

Initial Supporting table - P1400_EngineSpeedResidual_Table

Description: This 1x17 table of engine exhaust flow values is used to calculate both the desired and the actual engine exhaust flow based on desired and actual engine speed. The desired engine exhaust flow is gathered from the desired engine speed (VeSPDR_n_EngDsrd). The value used for the actual engine exhaust flow is based on the actual engine RPM value.

y/x	0	300	500	600	890	900	950	975	1,000	1,075	1,350	1,400	1,700	1,800	1,900	2,000	2,500
1	0	9	9	9	9	9	20	21	22	24	25	25	25	25	25	25	25

Initial Supporting table - P1400_SparkResidual_Table

Description: Predicted engine-out energy potential based on either the desired cold start spark advance value or the actual spark advance value. ExhEngyPerUnitMass calibration is used to calculate both desired exhaust energy and actual energy. The desired and actual exhaust energy per unit mass values are used in part to calculate the desired exhaust energy per unit time and actual exhaust energy per unit time. Both desired and actual go into the residual exhaust energy per unit time calculation.

y/x	-20	-10	-7	-2	-1	0	5	10	20
1	1.00	1.00	1.00	1.00	1.00	0.63	0.63	0.63	0.63

Initial Supporting table - P0101, P0106, P010B, P0121, P012B, P0236, P1101: MAF1 Residual Weight Factor based on MAF Est

Description: P0101_P0106_P010B_P0121_P012B_P0236_P1101 MAF1 Residual Weight Factor based on MAF Est

Value Units: Weight Factor (Unitless)
X Unit: Estimated Engine Air Flow (Grams/Second)

y/x	0	50	70	73	76	79	82	85	89	95	100	110	120	150	200	280	350
1	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	0.900	0.900	0.900

Initial Supporting table - P0101, P0106, P010B, P0121, P012B, P0236, P1101: MAF1 Residual Weight Factor based on RPM

Description: P0101_P0106_P010B_P0121_P012B_P0236_P1101 MAF1 Residual Weight Factor based on RPM

Value Units: Weight Factor (Unitless)
X Unit: Engine Speed (RPM)

y/x	0	400	800	1,200	1,600	2,000	2,400	2,800	3,200	3,600	4,000	4,400	4,800	5,200	5,600	6,000	6,500
1	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	0.700	0.700	0.700	0.700	0.700	0.700

Initial Supporting table - P0116_Fail if power up ECT exceeds IAT by these values

Description: KtECTD_T_HSC_FastFailTempDiff

Value Units: Fast Failure temp difference (°C)
X Unit: IAT Temperature at Power up (°C)

y/x	-40	-28	-16	-4	8	20	32	44	56	68	80	92	104	116	128	140	152
1	80	80	80	60	60	40	40	25	25	25	15	15	15	25	30	30	30

Initial Supporting table - P0128_Maximum Accumulated Energy for Start-up ECT conditions - Alternate

Description: KtECTR_E_CTR_WrmUpEnrgyLimTest1

Value Units: Cooling system energy failure threshold (kJ)
X Unit: Minimum ECT for the key cycle (°C)

y/x	-20	-5	10	20	30	60	75
1	2,900	2,900	2,900	2,600	2,600	2,600	2,600

Initial Supporting table - P0128_Maximum Accumulated Energy for Start-up ECT conditions - Primary

Description: KtECTR_E_CTR_WrmUpEnrgyLimTest0

Value Units: Cooling system energy failure threshold (kJ)
X Unit: Minimum ECT for the key cycle (°C)

y/x	-20	-5	10	20	30	60	75
1	2,900	2,900	2,900	2,600	2,600	2,600	2,600

Initial Supporting table - P0606_Last Seed Timeout f(Loop Time)

Description: The max time for the Last Seed Timeout as a function of operating loop time sequence.

P0606_Last Seed Timeout f(Loop Time) - Part 1

y/x	CePISR_e_5msSeq	CePISR_e_6p25msSeq	CePISR_e_10msSeq	CePISR_e_12p5msSeq	CePISR_e_20msSeq	CePISR_e_25msSeq	CePISR_e_40msSeq
1	200.000	200.000	200.000	200.000	200.000	200.000	200.000

P0606_Last Seed Timeout f(Loop Time) - Part 2

y/x	CePISR_e_50msSeq	CePISR_e_80msSeq	CePISR_e_100msSeq	CePISR_e_EventA_Seq	CePISR_e_EventB_Seq	CePISR_e_EventC_Seq	
1	500.000	500.000	1,000.000	8,191.875	8,191.875	8,191.875	

Initial Supporting table - P0606_PSW Sequence Fail f(Loop Time)

Description: Fail threshold for PSW per operating loop.

P0606_PSW Sequence Fail f(Loop Time) - Part 1

y/x	CePISR_e_5msSeq	CePISR_e_6p25msSeq	CePISR_e_10msSeq	CePISR_e_12p5msSeq	CePISR_e_20msSeq	CePISR_e_25msSeq	CePISR_e_40msSeq
1	5	3	5	3	5	3	5

P0606_PSW Sequence Fail f(Loop Time) - Part 2

y/x	CePISR_e_50msSeq	CePISR_e_80msSeq	CePISR_e_100msSeq	CePISR_e_EventA_Seq	CePISR_e_EventB_Seq	CePISR_e_EventC_Seq	
1	3	5	3	5	5	5	

Initial Supporting table - P0606_PSW Sequence Sample f(Loop Time)

Description: Sample threshold for PSW per operating loop.

P0606_PSW Sequence Sample f(Loop Time) - Part 1

y/x	CePISR_e_5msSeq	CePISR_e_6p25msSeq	CePISR_e_10msSeq	CePISR_e_12p5msSeq	CePISR_e_20msSeq	CePISR_e_25msSeq	CePISR_e_40msSeq
1	4	4	4	4	4	4	4

P0606_PSW Sequence Sample f(Loop Time) - Part 2

y/x	CePISR_e_50msSeq	CePISR_e_80msSeq	CePISR_e_100msSeq	CePISR_e_EventA_Seq	CePISR_e_EventB_Seq	CePISR_e_EventC_Seq	
1	4	4	4	4	4	4	

Initial Supporting table - P16F3_Delta MAP Threshold f(Desired Engine Torque)

Description: Engine Sync based and Time based delta pressure threshold above which Torque Security error is reported.

y/x	0.00	50.00	100.00	150.00	200.00	300.00
1.00	22.42	22.42	22.42	22.42	22.42	22.42

Initial Supporting table - P16F3_Speed Control External Load f(Oil Temp, RPM)

Description: Specifies the external load table for SPDR torque security as a function of engine oil temperature and engine RPM.

y/x	-40.00	-20.00	-10.00	0.00	50.00	90.00
350.00	97.30	89.43	81.50	74.83	55.30	46.30
450.00	97.30	89.43	81.50	74.83	55.30	46.30
550.00	97.30	89.43	81.50	74.83	55.30	46.30
650.00	96.70	88.83	80.90	74.23	54.70	45.70
680.00	97.30	89.43	81.50	74.83	55.30	46.30
780.00	100.71	92.40	83.74	77.84	57.63	46.95
900.00	102.32	92.66	83.05	78.07	61.69	49.78
1,000.00	100.86	91.30	81.83	77.00	61.50	48.78
1,100.00	99.50	89.28	77.42	74.46	61.37	43.60
1,200.00	96.31	83.95	70.71	68.59	59.35	38.62
1,450.00	77.75	69.48	62.60	58.01	43.74	38.94
1,700.00	40.51	31.34	24.20	19.95	8.92	4.61
1,950.00	23.74	14.98	8.24	4.31	-5.55	-9.40
2,200.00	9.83	1.34	-5.13	-8.85	-17.93	-21.48
3,200.00	-38.30	-38.30	-38.30	-38.30	-38.30	-38.30
4,200.00	-42.13	-42.13	-42.13	-42.13	-42.13	-42.13
6,400.00	-45.96	-45.96	-45.96	-45.96	-45.96	-45.96

Initial Supporting table - 1st_FireAftrMisfr_Acel

Description: Used for P0300 - P0308, Multiplier for establishing the expected acceleration of the cylinder after the misfire

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	500	600	700	800	900	1,000	1,100	1,200	1,400	1,800	2,200	2,600	3,000	4,000	5,000	6,000	7,000
8	0.56	1.00	1.00	1.00	1.00	1.00	0.95	0.90	0.80	0.70	0.70	0.70	0.70	0.75	0.71	0.67	1.00
12	0.48	0.68	0.80	0.94	1.00	1.00	0.95	0.90	0.80	0.70	0.70	0.70	0.70	0.75	0.71	0.67	1.00
16	0.43	0.64	0.71	0.90	0.90	0.90	0.90	0.90	0.80	0.60	0.60	0.60	0.60	0.58	0.56	0.67	0.83
20	0.38	0.58	0.68	0.85	0.85	0.85	0.85	0.85	0.60	0.60	0.60	0.60	0.60	0.60	0.64	0.67	0.83
24	0.26	0.40	0.42	0.65	0.65	0.65	0.65	0.60	0.60	0.45	0.45	0.45	0.45	0.44	0.46	0.43	0.71
30	0.26	0.43	0.46	0.65	0.65	0.65	0.65	0.60	0.55	0.50	0.50	0.50	0.50	0.52	0.53	0.50	0.63
40	0.33	0.65	0.65	0.65	0.65	0.65	0.65	0.60	0.55	0.50	0.50	0.50	0.50	0.50	0.53	0.50	0.60
60	0.24	0.65	0.65	0.65	0.65	0.65	0.65	0.60	0.55	0.55	0.55	0.55	0.55	0.55	0.54	0.57	0.64
98	0.16	0.65	0.65	0.65	0.65	0.65	0.65	0.60	0.55	0.55	0.55	0.55	0.55	0.55	0.54	0.57	0.64

Initial Supporting table - 1st_FireAftrMisfr_Jerk

Description: Used for P0300 - P0308, Multiplier for establishing the expected Jerk of the cylinder after the misfire

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	500	600	700	800	900	1,000	1,100	1,200	1,400	1,800	2,200	2,600	3,000	4,000	5,000	6,000	7,000
8	-0.80	-0.88	-0.90	-0.89	-0.90	-0.72	-0.90	-0.77	-0.90	-0.90	-0.90	-0.76	-0.77	-0.79	-0.83	-0.80	-0.80
12	-0.65	-0.90	-0.90	-0.86	-0.90	-0.72	-0.68	-0.77	-0.90	-0.70	-0.90	-0.76	-0.76	-0.75	-0.83	-0.80	-0.80
16	-0.64	-0.90	-0.90	-0.88	-0.65	-0.72	-0.68	-0.80	-0.90	-0.70	-0.90	-0.76	-0.76	-0.76	-0.83	-0.80	-0.80
20	-0.75	-0.90	-0.90	-0.85	-0.65	-0.72	-0.68	-0.80	-0.90	-0.75	-0.90	-0.75	-0.75	-0.74	-0.75	-0.78	-0.89
24	-0.68	-0.90	-0.90	-0.73	-0.70	-0.75	-0.68	-0.80	-0.90	-0.83	-0.90	-0.75	-0.75	-0.76	-0.75	-0.73	-0.91
30	-0.66	-0.90	-0.90	-0.73	-0.90	-0.75	-0.68	-0.90	-0.90	-0.83	-0.86	-0.75	-0.75	-0.75	-0.75	-0.73	-0.87
40	-0.57	-0.90	-0.90	-0.71	-0.90	-0.75	-0.90	-0.90	-0.90	-0.83	-0.81	-0.75	-0.75	-0.75	-0.76	-0.77	-0.88
60	-0.47	-0.90	-0.90	-0.71	-0.90	-0.90	-0.90	-0.90	-0.90	-0.83	-0.90	-0.80	-0.80	-0.80	-0.79	-0.80	-0.89
98	-0.47	-0.90	-0.90	-0.71	-0.90	-0.90	-0.90	-0.90	-0.90	-0.83	-0.90	-0.80	-0.80	-0.80	-0.79	-0.80	-0.89

Initial Supporting table - 1stFireAfterMisJerkAFM

Description: Used for P0300 - P0308, Multiplier for establishing the expected jerk of the cylinder after the misfire if Active Fuel Management cylinder deact mode is active

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	800	1,000	1,200	1,600	2,000	2,400	2,600	3,000	3,500
8	1	1	1	1	1	1	1	1	1
12	1	1	1	1	1	1	1	1	1
16	1	1	1	1	1	1	1	1	1
20	1	1	1	1	1	1	1	1	1
24	1	1	1	1	1	1	1	1	1
30	1	1	1	1	1	1	1	1	1
40	1	1	1	1	1	1	1	1	1
60	1	1	1	1	1	1	1	1	1
98	1	1	1	1	1	1	1	1	1

Initial Supporting table - 1stFireAftrMisAcelAFM

Description: Used for P0300 - P0308, Multiplier for establishing the expected acceleration of the cylinder after the misfire if Active Fuel Management cylinder deact mode is active

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	800	1,000	1,200	1,600	2,000	2,400	2,600	3,000	3,500
8	1	1	1	1	1	1	1	1	1
12	1	1	1	1	1	1	1	1	1
16	1	1	1	1	1	1	1	1	1
20	1	1	1	1	1	1	1	1	1
24	1	1	1	1	1	1	1	1	1
30	1	1	1	1	1	1	1	1	1
40	1	1	1	1	1	1	1	1	1
60	1	1	1	1	1	1	1	1	1
98	1	1	1	1	1	1	1	1	1

Initial Supporting table - Abnormal Cyl Mode

Description: Used for P0300-P0308. Number of consecutive number of decelerating cylinders after the misfire that would be considered abnormal. (Cylinder Mode Equation)

Value Units: Number of consecutive number of decelerating cylinders (integer)
X Unit: thousands of RPM (rpm/1000)

y/x	0	1	2	3	4	5	6	7	8
1	4	4	4	4	4	4	4	4	4

Initial Supporting table - Abnormal Rev Mode

Description: Used for P0300-P0308. Abnormal Rev Mode Number of consecutive number of decelerating cylinders after the misfire that would be considered abnormal. (Rev Mode Equation)

Value Units: Number of consecutive number of decelerating cylinders (integer)
X Unit: thousands of RPM (rpm/1000)

y/x	0	1	2	3	4	5	6	7	8
1	2.00	2.00	2.00	2.00	2.00	2.00	2.00	2.00	2.00

Initial Supporting table - Abnormal SCD Mode

Description: Used for P0300-P0308. Number of consecutive number of decelerating cylinders after the misfire that would be considered abnormal. (SCD Mode Equation)

Value Units: Number of consecutive number of decelerating cylinders (integer)
X Unit: thousands of RPM (rpm/1000)

y/x	0	1	2	3	4	5	6	7	8
1	2	2	2	2	2	2	2	2	2

Initial Supporting table - Bank_SCD_Decel

Description: Used for P0300 - P0308, Mulitplier to SCD decel to account for different pattern of Paired cylinder misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	400	550	700	800	900	1,000	1,200	1,400	1,600
8	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
12	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
16	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
20	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
24	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
30	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
40	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
60	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
98	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00

Initial Supporting table - Bank_SCD_Jerk

Description: Used for P0300 - P0308, Mulitplier to Medres SCD jerk to account for different pattern of Paired cylinder misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: mulitplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	400	550	700	800	900	1,000	1,200	1,400	1,600
8	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
12	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
16	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
20	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
24	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
30	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
40	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
60	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
98	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00

Initial Supporting table - BankCylModeDecel

Description: Used for P0300 - P0308, Mulitplier to Lores Decel to account for different pattern of Paired cylinder misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	500	600	700	800	900	1,000	1,100	1,200	1,400	1,800	2,200	2,600	3,000	4,000	5,000	6,000	7,000
8	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
12	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
16	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
20	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
24	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
30	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
40	11.73	11.73	11.73	11.73	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
60	11.73	11.73	11.73	11.73	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
98	11.73	11.73	11.73	11.73	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00

Initial Supporting table - BankCylModeJerk

Description: Used for P0300 - P0308, Mulitplier to Lores Jerk to account for different pattern of Paired cylinder misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	500	600	700	800	900	1,000	1,100	1,200	1,400	1,800	2,200	2,600	3,000	4,000	5,000	6,000	7,000
8	10.14	10.14	10.14	12.60	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
12	10.14	10.14	10.14	12.60	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
16	8.50	8.50	8.50	9.64	13.37	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
20	5.83	5.83	5.83	9.36	10.96	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
24	5.83	5.83	5.83	5.83	10.86	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
30	5.13	5.13	5.13	5.13	8.11	9.36	14.83	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
40	4.68	4.68	4.68	4.68	5.92	6.93	14.83	15.60	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
60	4.68	4.68	4.68	4.68	5.92	6.93	14.83	15.60	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
98	4.68	4.68	4.68	4.68	5.92	6.93	14.83	15.60	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00

Initial Supporting table - Catalyst_Damage_Misfire_Percentage

Description: Catalyst Damaging Misfire Percentage" Table whenever secondary conditions are met.

Value Units: percent misfire over 200 revolutions (%)
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	0	1,000	2,000	3,000	4,000	5,000	6,000	7,000
0	24.6	24.6	24.6	24.6	20.6	10.6	10.6	10.6
10	24.6	24.6	24.6	24.6	20.6	10.6	10.6	10.6
20	24.6	24.6	23.6	22.6	20.6	10.6	10.6	4.6
30	23.6	23.6	20.6	20.6	14.6	10.6	4.6	4.6
40	20.6	20.6	16.6	12.6	10.6	7.6	4.6	4.6
50	16.6	16.6	10.6	8.6	7.6	4.6	4.6	4.6
60	10.6	10.6	7.6	7.6	4.6	4.6	4.6	4.6
70	7.6	7.6	4.6	4.6	4.6	4.6	4.6	4.6
80	4.6	4.6	4.6	4.6	4.6	4.6	4.6	4.6
90	4.6	4.6	4.6	4.6	4.6	4.6	4.6	4.6
100	4.6	4.6	4.6	4.6	4.6	4.6	4.6	4.6

Initial Supporting table - ClyAfterAFM_Decel

Description: Used for P0300 - P0308, Mulitplier to Lores decel to account for different pattern of misfire after a deactivated cylider. Similar to the second cylinder of consecutive cylinder misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	800	1,000	1,200	1,600	2,000	2,400	2,600	3,000	3,500
8	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
12	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
16	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
20	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
24	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
30	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
40	11.73	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
60	11.73	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
98	11.73	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00

Initial Supporting table - ClyBeforeAFM_Jerk

Description: Used for P0300 - P0308, Mulitplier to Lores decel to account for different pattern of misfire before a deactivated cylider, but after an active cylinder that follows an deactive cylinder on engine that supports cylinder deactivation in non even fire patterns.. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	800	1,000	1,200	1,600	2,000	2,400	2,600	3,000	3,500
8	12.60	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
12	12.60	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
16	9.64	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
20	9.36	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
24	5.83	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
30	5.13	9.36	16.00	16.00	16.00	16.00	16.00	16.00	16.00
40	4.68	6.93	15.60	16.00	16.00	16.00	16.00	16.00	16.00
60	4.68	6.93	15.60	16.00	16.00	16.00	16.00	16.00	16.00
98	4.68	6.93	15.60	16.00	16.00	16.00	16.00	16.00	16.00

Initial Supporting table - CombustModeIdleTbl

Description: Used for P0300 - P0308, Only used on Diesel engines. Combustion modes that will force use of Idle table. A value of CeCMBR_i_CombModesMax means not selected.

Value Units: Enumerated value of differant combustion modes (enumeration)
X Unit: Current Combustion Mode (enumeration)

CombustModeIdleTbl - Part 1

y/x	0	1	2	3	4	5
1	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax

CombustModeIdleTbl - Part 2

y/x	6	7	8	9	10	11
1	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax

CombustModeIdleTbl - Part 3

y/x	12	13	14	15	16	
1	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	

Initial Supporting table - ConsecCylModDecel

Description: Used for P0300 - P0308, Mulitplier to Lores decel to account for different pattern of the second cylinder of consecutive misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	500	600	700	800	900	1,000	1,100	1,200	1,400	1,800	2,200	2,600	3,000	4,000	5,000	6,000	7,000
8	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
12	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
16	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
20	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
24	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
30	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
40	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
60	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
98	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00

Initial Supporting table - ConsecCylModeJerk

Description: Used for P0300 - P0308, Mulitplier to Lores Jerk to account for different pattern of the second cylinder of consecutive misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	500	600	700	800	900	1,000	1,100	1,200	1,400	1,800	2,200	2,600	3,000	4,000	5,000	6,000	7,000
8	0	0	0	0	0	0	0	0	0	0	0	0	0	0	-1	-1	-1
12	0	0	0	0	0	0	0	0	0	0	0	0	0	0	-1	-1	-1
16	0	0	0	0	0	0	0	0	0	0	0	0	0	0	-1	-1	-1
20	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	-1	-1
24	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
30	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
40	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
60	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
98	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

Initial Supporting table - ConsecSCD_Decel

Description: Used for P0300 - P0308, Mulitplier to medres decel to account for different pattern of the second cylinder of consecutive misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	400	550	700	800	900	1,000	1,200	1,400	1,600
8	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
12	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
16	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
20	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
24	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
30	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
40	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
60	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
98	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00

Initial Supporting table - ConsecSCD_Jerk

Description: Used for P0300 - P0308, Mulitplier to medres Jerk to account for different pattern of the second cylinder of consecutive misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	400	550	700	800	900	1,000	1,200	1,400	1,600
8	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
12	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
16	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
20	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
24	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
30	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
40	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
60	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
98	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00

Initial Supporting table - CylAfterAFM_Jerk

Description: Used for P0300 - P0308, Mulitplier to Lores Jerk to account for different pattern of misfire after a deactivated cylider. Similar to the second cylinder of consecutive cylinder misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	800	1,000	1,200	1,600	2,000	2,400	2,600	3,000	3,500
8	13	16	16	16	16	16	16	16	16
12	13	16	16	16	16	16	16	16	16
16	10	16	16	16	16	16	16	16	16
20	9	16	16	16	16	16	16	16	16
24	6	16	16	16	16	16	16	16	16
30	5	9	16	16	16	16	16	16	16
40	5	7	16	16	16	16	16	16	16
60	5	7	16	16	16	16	16	16	16
98	5	7	16	16	16	16	16	16	16

Initial Supporting table - CylBeforeAFM_Decel

Description: Used for P0300 - P0308, Mulitplier to Lores decel to account for different pattern of misfire before a deactivated cylider, but after an active cylinder that follows an deactive cylinder on engine that supports cylinder deactivation in non even fire patterns.. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	800	1,000	1,200	1,600	2,000	2,400	2,600	3,000	3,500
8	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
12	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
16	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
20	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
24	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
30	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
40	11.73	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
60	11.73	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
98	11.73	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00

Initial Supporting table - CylModeDecel

Description: Used for P0300-P0308. Crankshaft decel threshold. Thresholds are a function of rpm and % engine Load.

Value Units: Delta time per cylinder (usec)
X Unit: RPM
Y Units: percent load of max indicated torque (%)

CylModeDecel - Part 1

y/x	400	500	600	700	800	900	1,000	1,100	1,200	1,400	1,600	1,800	2,000
3	3,785	2,010	1,228	1,228	1,228	900	600	505	400	230	200	150	90
6	3,785	2,010	1,228	1,228	1,228	900	600	505	400	230	200	150	90
8	4,100	2,200	1,228	1,228	1,228	900	600	505	400	230	200	150	90
10	4,430	2,360	1,228	1,228	1,228	900	600	505	400	230	200	150	90
12	4,770	2,550	1,800	1,530	1,300	900	600	505	400	230	200	150	90
14	5,130	2,800	2,000	1,600	1,315	900	600	505	400	230	220	150	95
16	5,500	2,950	2,000	1,800	1,426	900	600	505	400	242	240	160	105
18	5,880	3,200	2,100	1,800	1,500	970	600	600	400	300	250	178	118
20	6,300	3,400	2,200	1,900	1,510	985	895	780	620	350	262	189	129
22	6,660	3,600	2,300	2,100	1,525	990	899	790	625	460	391	220	139
24	7,100	3,900	2,500	2,400	1,530	991	900	800	626	675	413	288	184
26	7,470	4,050	2,550	2,450	1,685	1,000	951	850	630	680	459	346	199
30	8,150	4,420	2,700	2,500	1,779	1,050	1,030	900	690	685	520	420	261
40	9,990	5,450	2,794	2,794	2,794	1,457	1,200	1,000	800	790	525	445	308
60	12,600	7,510	2,794	2,794	2,794	1,457	1,200	1,000	800	790	525	445	308
78	12,601	9,260	2,794	2,794	2,794	1,457	1,200	1,000	800	790	525	445	308
97	12,601	11,310	2,794	2,794	2,794	1,457	1,200	1,000	800	790	525	445	308

CylModeDecel - Part 2

y/x	2,200	2,400	2,600	2,800	3,000	3,500	4,000	4,500	5,000	5,500	6,000	6,500	7,000
3	85	70	60	40	20	7	4	4	4	3	3	3	3
6	85	70	60	40	20	7	4	4	4	3	3	3	3
8	85	70	60	40	20	7	4	4	4	3	3	3	3
10	85	70	60	40	20	7	4	4	4	3	3	3	3
12	85	70	60	40	20	7	4	4	4	3	3	3	3
14	90	70	60	40	20	7	4	5	5	3	3	3	3
16	100	90	60	40	20	13	6	5	5	3	3	3	3
18	115	110	80	40	20	13	7	5	5	4	3	3	3
20	125	110	80	50	40	14	8	6	6	4	3	3	3
22	135	110	80	60	40	14	8	8	6	4	4	4	4
24	167	135	100	70	50	16	9	9	7	5	4	4	4

Initial Supporting table - CylModeDecel

26	210	136	110	80	60	16	10	8	7	5	4	4	4
30	220	170	120	90	70	18	11	9	8	6	4	4	4
40	246	184	134	105	95	21	14	11	9	7	5	5	5
60	246	220	175	137	108	29	22	16	12	10	7	7	7
78	246	220	175	137	108	29	22	16	12	10	7	7	7
97	246	220	175	137	108	29	22	16	12	10	7	7	7

Initial Supporting table - CylModeJerk

Description: Crankshaft jerk threshold. Thresholds are a function of rpm and % engine Load.

Value Units: Change in Delta time per cylinder from last cylinder (usec)
Y Units: percent load of max indicated torque (%)

CylModeJerk - Part 1

y/x	400	500	600	700	800	900	1,000	1,100	1,200	1,400	1,600	1,800	2,000
3	6,380	3,233	3,233	3,233	2,600	1,710	800	760	488	279	200	160	140
6	6,380	3,233	3,233	3,233	2,600	1,710	800	760	488	279	200	160	140
8	7,100	3,640	3,300	3,233	2,400	1,710	800	760	488	279	200	160	140
10	7,850	4,040	3,400	3,233	2,450	1,720	1,210	825	520	326	250	180	140
12	8,650	4,470	3,233	3,233	2,500	1,750	1,230	850	621	333	280	230	155
14	9,500	4,920	3,600	3,313	3,100	1,800	1,290	890	700	400	300	273	155
16	10,370	5,390	3,857	3,857	3,200	2,000	1,450	1,100	740	410	355	300	200
18	11,280	5,880	4,759	4,759	3,300	2,200	1,700	1,300	752	415	380	373	215
20	12,210	6,380	5,300	5,300	3,400	2,990	1,800	1,450	800	420	395	380	270
22	12,600	6,900	5,405	5,405	4,200	3,000	1,950	1,924	943	450	430	420	290
24	12,601	7,420	5,616	5,616	5,400	3,017	1,970	1,945	950	660	600	450	330
26	12,601	7,950	5,994	5,994	5,800	3,500	2,500	2,026	992	710	630	500	390
30	13,500	8,780	6,391	6,391	6,200	3,800	3,300	2,210	1,304	720	700	540	410
40	13,501	11,140	7,008	7,008	7,008	5,534	4,400	2,210	1,365	990	900	780	540
60	13,501	13,500	7,008	7,008	7,008	5,534	4,730	2,210	2,100	1,617	1,313	950	546
78	13,501	13,501	7,008	7,008	7,008	5,534	4,730	2,210	2,100	1,617	1,313	950	546
97	13,501	13,501	7,008	7,008	7,008	5,534	4,730	2,210	2,100	1,617	1,313	950	546

CylModeJerk - Part 2

y/x	2,200	2,400	2,600	2,800	3,000	3,500	4,000	4,500	5,000	5,500	6,000	6,500	7,000
3	120	80	70	53	45	14	7	4	3	3	3	3	3
6	120	80	70	53	45	14	7	4	3	3	3	3	3
8	120	80	70	53	45	14	7	4	3	3	3	3	3
10	120	80	70	53	45	14	7	4	3	3	3	3	3
12	130	120	100	65	55	19	12	6	3	3	3	3	3
14	153	150	110	90	85	19	12	7	3	3	3	3	3
16	153	150	110	105	100	22	13	8	3	4	3	3	3
18	155	151	120	105	100	23	15	9	7	5	4	4	4
20	165	160	130	105	100	29	20	12	8	6	5	5	5
22	170	165	135	105	100	34	24	13	10	7	5	5	5
24	175	170	155	120	105	39	25	16	10	8	6	6	6

Initial Supporting table - CylModeJerk

26	280	220	175	145	120	45	30	17	12	10	7	7	7
30	310	230	200	165	130	53	36	21	14	10	8	8	8
40	434	320	250	210	180	77	50	34	23	18	13	13	13
60	434	320	330	280	250	100	70	53	39	29	23	23	23
78	434	320	330	280	250	100	70	53	39	29	23	23	23
97	434	320	330	280	250	100	70	53	39	29	23	23	23

Initial Supporting table - DeacCylInversionDecel

Description: Used for P0300 - P0308, Negative Torque can cause crank readings to invert (active cylinders appear weak & deactivated cylinders appear "strong" If deactivated cylinders don't decelerate at least this amount then the crank signal is inverting. Function of speed and load.

Value Units: Delta time per cylinder (usec)
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	800	1,000	1,200	1,600	2,000	2,400	2,600	3,000	3,500
8	0	0	0	0	0	0	0	0	0
12	0	0	0	0	0	0	0	0	0
16	0	0	0	0	0	0	0	0	0
20	0	0	0	0	0	0	0	0	0
24	0	0	0	0	0	0	0	0	0
30	0	0	0	0	0	0	0	0	0
40	0	0	0	0	0	0	0	0	0
60	0	0	0	0	0	0	0	0	0
98	0	0	0	0	0	0	0	0	0

Initial Supporting table - DeacCylInversionJerk

Description: Used for P0300 - P0308, Negative Torque can cause crank readings to invert (active cylinders appear weak & deactivated cylinders appear "strong" If deactivated cylinders don't jerk at least this amount then the crank signal is inverting. Function of speed and load.

Value Units: Change in Delta time per cylinder from last cylinder (usec)
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	800	1,000	1,200	1,600	2,000	2,400	2,600	3,000	3,500
8	0	0	0	0	0	0	0	0	0
12	0	0	0	0	0	0	0	0	0
16	0	0	0	0	0	0	0	0	0
20	0	0	0	0	0	0	0	0	0
24	0	0	0	0	0	0	0	0	0
30	0	0	0	0	0	0	0	0	0
40	0	0	0	0	0	0	0	0	0
60	0	0	0	0	0	0	0	0	0
98	0	0	0	0	0	0	0	0	0

Initial Supporting table - EngineOverSpeedLimit

Description: Engine OverSpeed Limit versus gear

Value Units: RPM
X Unit: Enumeration of transmission gear state (enumeration)

EngineOverSpeedLimit - Part 1

y/x	CeTGRR_e_TransGr1	CeTGRR_e_TransGr2	CeTGRR_e_TransGr3	CeTGRR_e_TransGr4	CeTGRR_e_TransGr5	CeTGRR_e_TransGr6	CeTGRR_e_TransGr9
1	6,500	6,500	6,500	6,500	6,500	6,500	6,500

EngineOverSpeedLimit - Part 2

y/x	CeTGRR_e_TransGr10	CeTGRR_e_TransGrNeut	CeTGRR_e_TransGrRvrs	CeTGRR_e_TransGrPark	CeTGRR_e_TransGr7	CeTGRR_e_TransGr8	
1	6,500	4,000	6,500	4,000	6,500	6,500	

Initial Supporting table - InfrequentRegen

Description: Used for P0300-P0308. Only used on Diesel engines. Initiates a misfire delay when the current combustion mode matchs a selection in the table. A value of CeCMBR_i_CombModesMax means not selected.

Value Units: Enumerated value of differant combustion modes (enumeration)
X Unit: Current Combustion Mode (enumeration)

InfrequentRegen - Part 1

y/x	0	1	2	3	4	5
1	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax

InfrequentRegen - Part 2

y/x	6	7	8	9	10	11
1	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax

InfrequentRegen - Part 3

y/x	12	13	14	15	16	
1	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	

Initial Supporting table - Number of Normals

Description: Used for P0300-P0308. Number of Normals for the Driveline Ring Filter
After a low level misfire, another misfire may not be detectable until driveline ringing ceases. If no ringing seen, stop filter early.

Value Units: Number of Engine cycles after isolated misfire (Engine cycles)
X Unit: thousands of RPM   (rpm/1000)

y/x	0	1	2	3	4	5	6	7	8
1	2	2	2	2	2	2	2	2	2

Initial Supporting table - P0420_BestFailingOSCTableB1

Description: This table is a 9x17 table of baseline Best Failing (e.g. threshold converter) OSC times for catalyst Bank 1. The axis' for this table include the average airflow and the catalyst temperature. After OSC is measured for a specific temp and airflow,the BestFailing OSC value is found within this table for the measured temp and airflow and is used along with the OSC_TimeRaw (and the WorstPassing value) to calculate the Normalized Ratio for that specific test. The values in this table are based on the measured OSC for the identified BPU converter that is used for MIL illumination across the specific temp and airflow range for a given program.

y/x	1.73	2.28	2.83	3.38	3.94	4.49	5.04	5.60	6.15	6.70	7.25	7.81	8.36	8.91	9.46	10.02	10.57
636.00	0.92	0.78	0.65	0.51	0.42	0.35	0.33	0.30	0.25	0.24	0.21	0.19	0.17	0.03	0.02	0.01	0.00
670.00	0.95	0.82	0.67	0.53	0.43	0.37	0.36	0.31	0.26	0.25	0.22	0.20	0.18	0.04	0.03	0.02	0.01
704.00	0.98	0.85	0.68	0.55	0.43	0.39	0.38	0.31	0.27	0.26	0.22	0.21	0.19	0.05	0.03	0.02	0.01
738.00	1.01	0.86	0.69	0.57	0.44	0.40	0.39	0.32	0.28	0.27	0.23	0.22	0.21	0.05	0.04	0.03	0.02
772.00	1.04	0.88	0.70	0.58	0.45	0.41	0.40	0.33	0.29	0.27	0.24	0.23	0.21	0.06	0.05	0.04	0.02
805.00	1.08	0.90	0.71	0.60	0.46	0.42	0.41	0.33	0.29	0.28	0.25	0.23	0.22	0.07	0.05	0.04	0.02
839.00	1.14	0.92	0.72	0.61	0.46	0.43	0.42	0.34	0.31	0.29	0.25	0.24	0.23	0.08	0.06	0.05	0.03
873.00	1.21	0.95	0.74	0.62	0.47	0.44	0.42	0.35	0.32	0.30	0.26	0.25	0.24	0.08	0.07	0.05	0.03
907.00	1.26	0.97	0.75	0.63	0.48	0.45	0.43	0.36	0.32	0.31	0.27	0.25	0.24	0.09	0.07	0.06	0.03

Initial Supporting table - P0420_WorstPassingOSCTableB1

Description: This table is a 9x17 table of WorstPassing (e.g. 120k) OSC times for catalyst Bank 1. The axis' for this table include the average airflow and the catalyst temperature. After OSC is measured for a specific temp and airflow, the WorstPassing OSC value is found within this table for the measured temp and airflow and is used along with the OSC_TimeRaw (and the BestFailing OSC value) to calculate the Normalized Ratio for that specific test.The values in this table are based on the measured OSC for the WPA part across the temp and airflow range.

y/x	1.73	2.28	2.83	3.38	3.94	4.49	5.04	5.60	6.15	6.70	7.25	7.81	8.36	8.91	9.46	10.02	10.57
636.00	1.99	1.39	1.15	0.97	0.89	0.75	0.68	0.60	0.52	0.43	0.39	0.33	0.33	0.31	0.30	0.29	0.27
670.00	2.08	1.40	1.17	0.98	0.90	0.76	0.69	0.60	0.53	0.43	0.39	0.34	0.33	0.32	0.30	0.29	0.28
704.00	2.17	1.43	1.18	0.99	0.91	0.76	0.70	0.61	0.53	0.44	0.40	0.34	0.33	0.32	0.31	0.30	0.28
738.00	2.25	1.45	1.21	1.00	0.91	0.77	0.71	0.61	0.54	0.44	0.40	0.35	0.34	0.33	0.32	0.31	0.29
772.00	2.34	1.48	1.24	1.02	0.92	0.78	0.73	0.62	0.54	0.45	0.41	0.36	0.35	0.34	0.33	0.32	0.30
805.00	2.43	1.51	1.27	1.03	0.93	0.78	0.74	0.64	0.55	0.46	0.42	0.38	0.36	0.35	0.34	0.33	0.32
839.00	2.52	1.58	1.33	1.05	0.93	0.79	0.76	0.66	0.56	0.47	0.43	0.40	0.38	0.37	0.36	0.35	0.33
873.00	2.61	1.69	1.39	1.07	0.94	0.80	0.78	0.69	0.57	0.48	0.45	0.42	0.40	0.39	0.38	0.37	0.36
907.00	2.70	1.80	1.47	1.10	0.95	0.81	0.80	0.72	0.59	0.49	0.48	0.44	0.42	0.41	0.40	0.39	0.38

Initial Supporting table - Pair_SCD_Decel

Description: Used for P0300 - P0308, Mulitplier to SCD_Decel to account for different pattern of Paired cylinder misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	400	550	700	800	900	1,000	1,200	1,400	1,600
8	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
12	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
16	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
20	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
24	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
30	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
40	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
60	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
98	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00

Initial Supporting table - Pair_SCD_Jerk

Description: Used for P0300 - P0308, Mulitplier to P0300_SCD_Jerk to account for different pattern of Paired cylinder misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	400	550	700	800	900	1,000	1,200	1,400	1,600
8	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
12	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
16	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
20	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
24	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
30	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
40	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
60	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
98	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00

Initial Supporting table - PairCylModeDecel

Description: Used for P0300 - P0308, Mulitplier to Cyl Mode Deceleration to account for different pattern of Paired cylinder misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: mulitplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	500	600	700	800	900	1,000	1,100	1,200	1,400	1,800	2,200	2,600	3,000	4,000	5,000	6,000	7,000
8	0.46	0.83	0.83	0.83	0.72	0.87	0.87	0.83	0.83	0.80	0.80	0.80	0.80	0.75	0.71	0.83	0.83
12	0.40	0.57	0.67	0.78	0.72	0.87	0.87	0.83	0.83	0.80	0.80	0.80	0.80	0.75	0.71	0.83	0.83
16	0.40	0.59	0.66	0.83	0.73	0.87	1.00	0.88	0.83	0.75	0.80	0.80	0.80	0.67	0.89	0.83	0.83
20	0.37	0.57	0.66	0.83	0.69	0.59	0.66	0.76	0.83	0.69	0.80	0.70	0.70	0.73	0.73	0.83	0.83
24	0.33	0.51	0.54	0.83	0.72	0.71	0.66	0.76	0.55	0.61	0.69	0.70	0.70	0.72	0.69	0.86	0.86
30	0.33	0.55	0.59	0.83	0.90	0.78	0.71	0.82	0.59	0.50	0.64	0.70	0.70	0.71	0.73	0.75	0.75
40	0.43	0.83	0.83	0.83	0.90	0.67	0.69	0.80	0.73	0.76	0.69	0.70	0.70	0.71	0.71	0.60	0.60
60	0.31	0.83	0.83	0.83	0.90	0.67	0.64	0.80	0.73	0.76	0.69	0.70	0.70	0.70	0.71	0.57	0.57
98	0.21	0.83	0.83	0.83	0.90	0.67	0.64	0.80	0.73	0.76	0.69	0.70	0.70	0.70	0.71	0.57	0.57

Initial Supporting table - PairCylModeJerk

Description: Used for P0300 - P0308, Mulitplier to P0300_CylModeJerk to account for different pattern of Paired cylinder misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	500	600	700	800	900	1,000	1,100	1,200	1,400	1,800	2,200	2,600	3,000	4,000	5,000	6,000	7,000
8	0.71	0.78	0.80	0.93	0.80	1.00	0.80	0.93	0.98	0.80	0.80	0.80	0.80	1.36	0.83	0.80	0.80
12	0.58	0.80	0.80	0.99	0.80	0.80	0.80	0.80	0.89	0.87	0.80	0.80	0.80	0.79	0.83	0.80	0.80
16	0.57	0.80	0.80	0.83	0.82	0.80	0.80	0.80	0.80	0.80	0.80	0.80	0.80	0.80	0.83	0.80	0.80
20	0.66	0.80	0.80	0.83	0.80	0.80	0.80	0.80	0.85	0.80	0.82	0.80	0.80	0.79	0.81	0.78	0.78
24	0.61	0.80	0.80	0.83	0.80	0.80	0.80	0.80	0.80	0.83	0.79	0.70	0.70	0.70	0.70	0.82	0.82
30	0.58	0.80	0.80	0.82	0.80	0.80	0.80	0.80	0.79	0.79	0.82	0.70	0.70	0.70	0.71	0.80	0.80
40	0.50	0.80	0.80	0.80	0.80	0.80	0.80	0.80	0.80	0.88	0.78	0.70	0.70	0.70	0.70	1.00	1.00
60	0.42	0.80	0.80	0.80	0.80	0.80	0.80	0.80	0.80	0.80	0.80	0.70	0.70	0.70	0.71	0.80	0.80
98	0.42	0.80	0.80	0.80	0.80	0.80	0.80	0.80	0.80	0.80	0.80	0.70	0.70	0.70	0.71	0.80	0.80

Initial Supporting table - Random_SCD_Decel

Description: Used for P0300 - P0308, Mulitplier to SCD_Decel to account for different pattern of light level misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	400	550	700	800	900	1,000	1,200	1,400	1,600
8	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
12	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
16	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
20	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
24	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
30	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
40	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
60	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
98	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00

Initial Supporting table - Random_SCD_Jerk

Description: Used for P0300 - P0308, Mulitplier to Random_SCD_Jerk to account for different pattern of light level misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	400	550	700	800	900	1,000	1,200	1,400	1,600
8	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
12	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
16	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
20	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
24	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
30	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
40	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
60	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
98	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00

Initial Supporting table - RandomAFM_Decl

Description: Used for P0300 - P0308, Mulitplier to Cylinder_Decel while in Cylnder Deactivation mode to account for different pattern of light level misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	800	1,000	1,200	1,600	2,000	2,400	2,600	3,000	3,500
8	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
12	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
16	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
20	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
24	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
30	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
40	11.73	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
60	11.73	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
98	11.73	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00

Initial Supporting table - RandomAFM_Jerk

Description: Used for P0300 - P0308, Mulitplier to Cylinder_Jerk while in Cylnder Deactivation mode to account for different pattern of light level misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	800	1,000	1,200	1,600	2,000	2,400	2,600	3,000	3,500
8	12.60	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
12	12.60	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
16	9.64	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
20	9.36	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
24	5.83	16.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00
30	5.13	9.36	16.00	16.00	16.00	16.00	16.00	16.00	16.00
40	4.68	6.93	15.60	16.00	16.00	16.00	16.00	16.00	16.00
60	4.68	6.93	15.60	16.00	16.00	16.00	16.00	16.00	16.00
98	4.68	6.93	15.60	16.00	16.00	16.00	16.00	16.00	16.00

Initial Supporting table - RandomCylModDecel

Description: Used for P0300 - P0308. Multiplier to CylMode_Decel. account for different pattern of light level misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: Multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	500	600	700	800	900	1,000	1,100	1,200	1,400	1,800	2,200	2,600	3,000	4,000	5,000	6,000	7,000
8	1.00	1.50	1.50	1.50	1.11	1.00	1.09	1.00	1.09	1.00	1.00	1.00	1.25	2.25	1.29	1.33	1.33
12	1.00	1.02	1.20	1.42	1.24	1.00	1.09	1.20	1.20	1.20	1.00	1.00	1.50	2.50	1.29	1.33	1.33
16	1.00	1.10	1.22	1.54	1.79	1.17	1.39	1.50	1.50	1.20	1.00	1.17	2.25	3.00	1.56	1.50	1.50
20	1.00	1.27	1.47	2.09	1.98	1.45	1.15	1.20	1.10	1.20	1.04	1.13	1.38	2.67	1.64	2.17	2.17
24	1.00	1.38	1.43	2.06	2.12	1.67	1.63	1.15	1.00	1.10	1.02	1.05	1.30	2.89	1.85	2.14	2.14
30	1.00	1.19	1.28	1.80	2.29	1.75	1.78	1.87	1.15	1.15	1.00	1.08	1.29	2.86	2.07	2.25	2.25
40	1.00	1.18	1.18	1.18	2.20	1.96	1.90	2.23	1.02	1.11	1.18	1.23	1.27	2.86	2.76	2.80	2.80
60	1.00	1.18	1.18	1.18	2.20	1.96	1.90	2.23	1.14	1.24	1.18	1.30	1.48	2.73	1.96	2.00	2.00
98	1.00	1.18	1.18	1.18	2.20	1.96	1.90	2.23	1.14	1.24	1.18	1.30	1.48	2.73	1.96	2.00	2.00

Initial Supporting table - RandomCylModJerk

Description: Used for P0300 - P0308, Multiplier to CylMode_Jerk to account for different pattern of light level misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	500	600	700	800	900	1,000	1,100	1,200	1,400	1,800	2,200	2,600	3,000	4,000	5,000	6,000	7,000
8	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
12	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
16	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
20	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
24	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
30	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
40	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
60	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
98	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00

Initial Supporting table - RandomRevModDecl

Description: Used for P0300 - P0308, Mulitplier to RevMode_Decel to account for different pattern of light level misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	3,000	3,500	4,000	4,500	5,000	5,500	6,000	7,000	8,000
8	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
12	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
16	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
20	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
24	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
30	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
40	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
60	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
98	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00

Initial Supporting table - RepetSnapDecayAdjst

Description: Used for P0300 - P0308, If misfire is present in consecutive engine cycles, this multiplier is applied to the misfire jerk threshold and compared to a crankshaft snap value after the misfire has taken place.. Table lookup as a function of engine rpm.

Value Units: multiplier
X Unit: RPM

y/x	500	1,200	1,400	2,000	2,500	3,000	4,000	4,500	6,000
1	1.20	1.20	1.20	1.15	1.00	1.00	1.10	1.35	1.00

Initial Supporting table - RevMode_Decel

Description: Used for P0300-P0308. Crankshaft decel threshold. Thresholds are a function of rpm and % engine Load.

Value Units: Delta time between revolutions (usec)
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	1,100	1,200	1,400	1,600	1,800	2,000	2,200	2,400	2,600	2,800	3,000	3,500	4,000	4,500	5,000	5,500	6,000	6,500	7,000
3	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
6	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
8	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
10	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
12	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
14	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
16	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
18	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
20	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
22	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
24	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
26	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
30	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
40	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
60	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
78	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
97	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767

Initial Supporting table - Ring Filter

Description: Used for P0300-P0308. Driveline Ring Filter
After a low level misfire, another misfire may not be detectable until driveline ringing ceases. If no ringing seen, stop filter early.

Value Units: Number of Engine cycles after isolated misfire (Engine cycles)
X Unit: thousands of RPM (rpm/1000)

y/x	0	1	2	3	4	5	6	7	8
1	4	4	4	4	4	4	4	4	4

Initial Supporting table - SCD_Decel

Description: Used for P0300-P0308 Crankshaft decel threshold. SCD mode uses smaller windows near TDC. Thresholds are a function of rpm and % engine Load.

Value Units: Delta time per cylinder (usec)
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	400	500	600	700	800	900	1,000	1,100	1,200	1,400	1,600	1,800	2,000
3	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
6	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
8	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
10	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
12	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
14	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
16	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
18	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
20	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
22	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
24	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
26	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
30	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
40	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
60	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
78	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
97	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767

Initial Supporting table - SCD_Jerk

Description: Used for P0300-P0308. Crankshaft jerk threshold. SCD mode uses smaller windows near TDC. Thresholds are a function of rpm and % engine Load.

Value Units: Change in Delta time per cylinder from last cylinder (usec)
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	400	500	600	700	800	900	1,000	1,100	1,200	1,400	1,600	1,800	2,000
3	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
6	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
8	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
10	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
12	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
14	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
16	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
18	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
20	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
22	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
24	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
26	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
30	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
40	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
60	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
78	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
97	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767

Initial Supporting table - SnapDecayAfterMisfire

Description: Used for P0300 - P0308, multiplier times the ddt_jerk value used used to detect misfire at that speed and load to see if size of disturbance has died down as expected of real misfire. Table lookup as a function of engine rpm and trans gear ratio.

Value Units: multiplier
X Unit: RPM
Y Units: gear ratio

y/x	500	1,200	1,400	2,000	2,500	3,000	4,000	4,500	6,000
1	1.20	1.30	1.30	1.30	1.20	1.00	1.00	1.00	1.00
1	1.60	1.60	1.60	1.10	1.10	1.20	1.20	1.10	0.80
1	1.55	1.55	1.55	1.10	1.00	1.00	1.00	1.15	0.80
2	1.55	1.55	1.55	1.10	1.10	1.15	1.15	1.10	1.10
2	1.40	1.40	1.35	1.20	1.20	1.10	1.10	1.10	1.10
3	1.00	1.00	1.00	0.80	0.80	0.80	0.80	1.10	1.10
3	1.20	1.20	0.80	0.80	0.75	1.00	1.00	1.00	1.00
4	1.15	1.15	0.95	0.95	0.95	0.95	0.95	0.95	0.95
4	1.25	1.25	1.25	0.95	0.95	0.95	0.95	0.95	0.95

Initial Supporting table - TOSSRoughRoadThres

Description: Used for P0300-P0308. Only used if Rough Road source = TOSS: dispersion value on Transmission Output Speed Sensor above which rough road is indicated present

Value Units: change in rpm per sec (rpm)
X Unit: Engine Speed (RPM)
Y Units: Transmission Speed (RPM)

y/x	600	800	1,000	1,200	1,400	1,600	1,800	2,000	2,200	2,400	2,600	2,800	3,000	3,500	4,000	4,500	5,000	5,500	6,000
100	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0
200	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0
300	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0
400	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0
500	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0
600	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0
700	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0
800	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0
900	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0
1,000	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0
1,100	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0
1,200	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0
1,300	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0
1,400	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0

Initial Supporting table - WaitToStart

Description: Used for P0300-P0308. Number of engine cycles to delay if diesel engine is cranked before wait to start lamp is extinguished. This lookup table determines the delay length by taking into account the coolant temperature.

Value Units: Number of Engine Cycles (integer)
X Unit: Engine Coolant (deg C)

y/x	-20	-10	0	10	20	30	40	50	60
1	0	0	0	0	0	0	0	0	0

Initial Supporting table - WSSRoughRoadThres

Description: Used for P0300-P0308. Only used if Wheel speed from ABS is used. If difference between wheel speed readings is larger than this limit, rough road is present

Value Units: acceleration
X Unit: Vehicle Speed (KPH)

y/x	0	12	24	36	48	60	72	85	97	109	121	133	145	157	169	181	193
1	1.04004	1.04004	1.04004	1.04004	1.04004	1.04004	1.04004	1.04004	1.04004	1.04004	1.04004	1.04004	1.04004	1.04004	1.04004	1.04004	1.04004

Initial Supporting table - ZeroTorqueAFM

Description: Used for P0300-P0308. Zero torque engine load while in Active Fuel Management. %of Max Brake Torque along the Neutral rev line, as a function of RPM and Baro

Value Units: Percent of Maximum Brake torque (%)
X Unit: RPM
Y Units: Barometric Pressure (kPa)

ZeroTorqueAFM - Part 1

y/x	400	500	600	700	800	900	1,000	1,100	1,200	1,400	1,600	1,800	2,000
65	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
75	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
85	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
95	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
105	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00

ZeroTorqueAFM - Part 2

y/x	2,200	2,400	2,600	2,800	3,000	3,500	4,000	4,500	5,000	5,500	6,000	6,500	7,000
65	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
75	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
85	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
95	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
105	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00

Initial Supporting table - ZeroTorqueEngLoad

Description: Used for P0300-P0308. %of Max Brake Torque that represents Zero Brake torque along the Neutral rev line, as a function of RPM and Baro

Value Units: Percent of Maximum Brake torque (%)
X Unit: RPM
Y Units: Barometric Pressure (kPa)

ZeroTorqueEngLoad - Part 1

y/x	400	500	600	700	800	900	1,000	1,100	1,200	1,400	1,600	1,800	2,000
65	-2.50	-2.50	-2.50	-2.50	-2.50	-2.50	-1.50	-1.00	-1.20	-2.00	-2.10	-2.50	-2.50
75	-2.50	-2.50	-2.50	-2.50	-2.50	-2.50	-1.50	-1.00	-1.20	-2.00	-2.10	-2.50	-2.50
85	-2.50	-2.50	-2.50	-2.50	-2.50	-2.50	-1.50	-1.00	-1.20	-2.00	-2.10	-2.50	-2.50
95	-1.68	-1.68	-1.68	-1.68	-1.68	-1.18	-0.42	0.00	0.00	-1.05	-1.57	-1.57	-1.57
105	-1.68	-1.68	-1.68	-1.68	-1.68	-1.18	-0.42	0.00	0.00	-1.05	-1.57	-1.57	-1.57

ZeroTorqueEngLoad - Part 2

y/x	2,200	2,400	2,600	2,800	3,000	3,500	4,000	4,500	5,000	5,500	6,000	6,500	7,000
65	-2.50	-2.50	-2.50	-2.50	-2.50	-0.20	2.11	4.42	6.73	9.03	11.33	13.64	15.95
75	-2.50	-2.50	-2.50	-2.50	-2.50	-0.20	2.11	4.42	6.73	9.03	11.33	13.64	15.95
85	-2.50	-2.50	-2.50	-2.50	-2.50	-0.20	2.11	4.42	6.73	9.03	11.33	13.64	15.95
95	-1.57	-1.57	-1.57	-1.57	-1.57	0.60	2.78	4.96	7.14	9.31	11.49	13.67	15.84
105	-1.57	-1.57	-1.57	-1.57	-1.57	0.60	2.78	4.96	7.14	9.31	11.49	13.67	15.84

Initial Supporting table - Closed Loop Enable Clarification - KaFCLP_U_SlphrIntglOfst_Thrsh

Description: Integral Offset voltage thresholds (bank and cell specific cals) used with KeFCLP_Pct_CatAccuSlphrPostDsbl to check for sulphur poisoning.

Value Units: millivolts
X Unit: Post Catalyst Number

y/x	CiOXYR_O2_PostCat1	CiOXYR_O2_PostCat2
CiFCLP_Decel	2,048	2,048
CiFCLP_Idle	2,048	2,048
CiFCLP_Cruise	2,048	2,048
CiFCLP_LightAccel	2,048	2,048
CiFCLP_HeavyAccel	2,048	2,048

Initial Supporting table - Closed Loop Enable Clarification - KcFCLP_Cnt_O2RdyCyclesThrsh

Description: Number of times a post oxygen sensor value must be in range before declaring it ready

Value Units: Time (events * 12.5 milliseconds)

y/x	1
1	80

Initial Supporting table - Closed Loop Enable Clarification - KcFULC_O2_SensorReadyEvents

Description: Number of times a pre oxygen sensor value must be in range before declaring it ready

Value Units: Time (events * 12.5 milliseconds)

y/x	1
1	20

Initial Supporting table - Closed Loop Enable Clarification - KeEOSD_U_RichThrsh

Description: The oxygen sensor voltage above which a sensor will be considered failing during a Rich Test.

Value Units: Volts

y/x	1
1	1,050

Initial Supporting table - Closed Loop Enable Clarification - KeFCLP_dm_IntegrationAirflowMax

Description: Maximum allowed estimated airflow for post O2 integral terms to be updated.

Value Units: Grams per Second

y/x	1
1	512

Initial Supporting table - Closed Loop Enable Clarification - KeFCLP_Pct_CatAccuSlphrPostDsbl

Description: Sulphur percent threshold above which post integral learning is disabled if the threshold criteria KaFCLP_U_SlphrIntglOfst_Thrsh is also met.

Value Units: Percent

y/x	1
1	255

Initial Supporting table - Closed Loop Enable Clarification - KeFCLP_T_IntegrationCatalystMax

Description: Maximum allowed estimated catalytic converter temperature for post O2 integral terms to be updated.

Value Units: Celcius

y/x	1
1	900

Initial Supporting table - Closed Loop Enable Clarification - KeFCLP_T_IntegrationCatalystMin

Description: Minimum allowed estimated catalytic converter temperature to begin using post O2 integration correction terms. Converter temperature must remain above this threshold to ramp-in the post O2 integration adjustments. Once the ramp-in has started, a converter temperature below this threshold will freeze the ramp-in multiplier. Post O2 integration will not be allowed below this converter temperature

Value Units: Celcius

y/x	1
1	350

Initial Supporting table - Closed Loop Enable Clarification - KeFULC_T_WRAF_SensorReadyThrsh

Description: Pumping cell temperature threshold above which the wideband oxygen sensor will be considered ready for use

Value Units: Degrees Celcius

y/x	1
1	700

Initial Supporting table - Closed Loop Enable Clarification - KeWRSC_T_HtrCntrlCL

Description: WRAF heater temperature enabling threshold for transition from Open Loop to Closed Loop

Value Units: Degrees Celcius

y/x	1
1	628

Initial Supporting table - Closed Loop Enable Clarification - KeWRSI_T_PumpCurrentEnable

Description: WRAF heater temperature threshold for enabling the sensor pump current

Value Units: Degrees Celcius

y/x	1
1	628

Initial Supporting table - Closed Loop Enable Clarification - KfFCLL_T_AdaptiveLoCoolant

Description: LTM learning is inhibited if the engine coolant temperature is below this calibration.

Value Units: Degrees Celcius

y/x	1
1	40

Initial Supporting table - Closed Loop Enable Clarification - KfFCLP_U_O2ReadyThrshLo

Description: Voltage limit checked against when determining if a post converter oxygen sensor is in range

Value Units: millivolts

y/x	1
1	1,100

Initial Supporting table - Closed Loop Enable Clarification - KfFULC_U_O2_SensorReadyThrshLo

Description: Voltage limit checked against when determining if a pre converter oxygen sensor is in range

Value Units: millivolts

y/x	1
1	1,100

Initial Supporting table - Closed Loop Enable Clarification - KtFCLL_p_AdaptiveLowMAP_Limit

Description: Long term fuel learning is disabled below this MAP limit as a function of barometric pressure.

Value Units: KPa
X Unit: KPa

y/x	65	70	75	80	85	90	95	100	105
1	17.0	17.0	17.0	17.0	17.5	18.0	18.5	19.0	19.0

Initial Supporting table - Closed Loop Enable Clarification - KtFCLP_t_PostIntglDisableTime

Description: Disable integral offset after engine start for this amount of time as a function of start up coolant temperature.

Value Units: Time in seconds
X Unit: Degrees Celcius

y/x	-40	-29	-18	-6	5	16	28	39	50	61	73	84	95	106	118	129	140
1	400.0	400.0	300.0	150.0	100.0	100.0	75.0	50.0	50.0	50.0	50.0	40.0	40.0	25.0	25.0	25.0	25.0

Initial Supporting table - Closed Loop Enable Clarification - KtFCLP_t_PostIntglRampInTime

Description: Time required to ramp integral offset to desired value as a function of start up coolant temperature.

Value Units: Time in seconds
X Unit: Degrees Celcius

y/x	-40	-29	-18	-6	5	16	28	39	50	61	73	84	95	106	118	129	140
1	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0

Initial Supporting table - Closed Loop Enable Clarification - KtFSTA_t_ClosedLoopAutostart

Description: Engine run time following an autostart, as a function of begin run coolant, which must be exceeded to enable CLOSED LOOP.

Value Units: Time in seconds
X Unit: Degrees Celcius

y/x	-40	-28	-16	-4	8	20	32	44	56	68	80	92	104	116	128	140	152
1	400.0	400.0	300.0	25.0	25.0	12.0	12.0	12.0	12.0	12.0	12.0	12.0	12.0	12.0	12.0	12.0	12.0

Initial Supporting table - Closed Loop Enable Clarification - KtFSTA_t_ClosedLoopTime

Description: Engine run time, as a function of startup coolant temperature, which must be exceeded to enable CLOSED LOOP.

Value Units: Time in seconds
X Unit: Degrees Celcius

y/x	-40	-28	-16	-4	8	20	32	44	56	68	80	92	104	116	128	140	152
1	400.0	400.0	300.0	25.0	25.0	12.0	12.0	12.0	12.0	12.0	12.0	12.0	12.0	12.0	12.0	12.0	12.0

Initial Supporting table - P0442 Volatility Time as a Function of Estimate of Ambient Temperature

Description: EONV volatility time as a function of estimated ambient temperature

Value Units: Volatility time (seconds)
X Unit: Estimated Ambient Temperature (Deg C)

y/x	-10	-4	1	7	13	18	24	29	35	41	46	52	58	63	69	74	80
1	30	30	45	60	80	120	225	293	400	400	400	400	400	400	400	400	400

Initial Supporting table - P0442 Engine Off Time Before Vehicle Off Maximum as a Function of Estimated Ambient Temperature

Description: Maximum engine off time before vehicle off time as a function of estimated ambient temperature (EAT)

Value Units: Maximum Engine Off Time Before Vehicle Off Time (seconds)
X Unit: Estimated Ambient Temperature (Deg C)

y/x	-10	-4	1	7	13	18	24	29	35	41	46	52	58	63	69	74	80
1	30	30	30	30	30	30	30	30	30	30	30	30	30	30	30	30	30

Initial Supporting table - P0442 EONV Pressure Threshold (Pascals)

Description: EONV pressure threshold as a function of fuel level and estimated ambient temperature (EAT)

Value Units: EONV Pressure Threshold (Pascals)
X Unit: Fuel Level (percent) from 0 to 100 with step size 6.25
Y Units: Estimated Ambient Temperature (deg C) from -10 to 80 with step size 5.625

y/x	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17
1	-168.8	-168.8	-171.2	-173.0	-173.9	-174.4	-173.7	-172.5	-170.5	-168.3	-165.7	-162.7	-159.8	-157.1	-154.5	-151.8	-151.8
2	-168.8	-168.8	-171.2	-173.0	-173.9	-174.4	-173.7	-172.5	-170.5	-168.3	-165.7	-162.7	-159.8	-157.1	-154.5	-151.8	-151.8
3	-165.9	-165.9	-167.8	-169.5	-170.3	-170.3	-169.5	-168.1	-166.1	-163.7	-160.8	-158.1	-155.4	-152.8	-150.3	-148.1	-148.1
4	-146.9	-146.9	-147.2	-146.9	-146.2	-145.2	-144.0	-142.3	-140.4	-138.4	-136.5	-135.0	-133.5	-132.6	-131.8	-131.6	-131.6
5	-137.9	-137.9	-136.5	-134.8	-132.6	-130.1	-127.2	-124.5	-124.5	-124.5	-124.5	-124.5	-124.5	-124.5	-124.5	-124.5	-124.5
6	-136.7	-136.7	-135.0	-133.1	-130.6	-127.5	-124.5	-124.5	-124.5	-124.5	-124.5	-124.5	-124.5	-124.5	-124.5	-124.5	-124.5
7	-139.1	-139.1	-138.4	-137.4	-136.0	-133.8	-131.4	-128.4	-125.3	-124.5	-124.5	-124.5	-124.5	-124.5	-124.5	-124.5	-124.5
8	-141.8	-141.8	-142.1	-142.1	-142.1	-141.6	-140.8	-139.9	-138.7	-137.2	-135.5	-133.5	-131.6	-129.9	-128.7	-127.7	-127.7
9	-141.1	-141.1	-141.6	-142.3	-142.8	-143.3	-143.5	-144.0	-144.0	-144.0	-143.8	-143.0	-142.3	-141.6	-140.6	-139.9	-139.9
10	-141.1	-141.1	-141.6	-142.3	-142.8	-143.3	-143.5	-144.0	-144.0	-144.0	-143.8	-143.0	-142.3	-141.6	-140.6	-139.9	-139.9
11	-141.1	-141.1	-141.6	-142.3	-142.8	-143.3	-143.5	-144.0	-144.0	-144.0	-143.8	-143.0	-142.3	-141.6	-140.6	-139.9	-139.9
12	-141.1	-141.1	-141.6	-142.3	-142.8	-143.3	-143.5	-144.0	-144.0	-144.0	-143.8	-143.0	-142.3	-141.6	-140.6	-139.9	-139.9
13	-141.1	-141.1	-141.6	-142.3	-142.8	-143.3	-143.5	-144.0	-144.0	-144.0	-143.8	-143.0	-142.3	-141.6	-140.6	-139.9	-139.9
14	-141.1	-141.1	-141.6	-142.3	-142.8	-143.3	-143.5	-144.0	-144.0	-144.0	-143.8	-143.0	-142.3	-141.6	-140.6	-139.9	-139.9
15	-141.1	-141.1	-141.6	-142.3	-142.8	-143.3	-143.5	-144.0	-144.0	-144.0	-143.8	-143.0	-142.3	-141.6	-140.6	-139.9	-139.9
16	-141.1	-141.1	-141.6	-142.3	-142.8	-143.3	-143.5	-144.0	-144.0	-144.0	-143.8	-143.0	-142.3	-141.6	-140.6	-139.9	-139.9
17	-141.1	-141.1	-141.6	-142.3	-142.8	-143.3	-143.5	-144.0	-144.0	-144.0	-143.8	-143.0	-142.3	-141.6	-140.6	-139.9	-139.9

Initial Supporting table - P0442 Estimate of Ambient Temperature Valid Conditioning Time as a Function of Ign Off Time

Description: EONV estimated ambient temperature valid conditioning time as a function of ignition off time

Value Units: Estimated Ambient Temperature Valid Conditioning Time (seconds)
X Unit: Ignition Off Time (seconds)

P0442 Estimate of Ambient Temperature Valid Conditioning Time as a Function of Ign Off Time - Part 1

y/x	0	600	1,200	1,800	2,400	3,000	3,600	4,200	4,800	5,400	6,000	6,600	7,200	7,800	8,400	9,000	9,600
1	155	490	490	490	490	490	370	366	361	357	353	348	344	340	335	331	327

P0442 Estimate of Ambient Temperature Valid Conditioning Time as a Function of Ign Off Time - Part 2

y/x	10,200	10,800	11,700	12,600	13,500	14,400	15,300	16,200	17,100	18,000	19,200	20,400	21,600	22,800	24,000	25,200	
1	322	318	312	305	299	292	289	286	282	279	275	270	266	257	249	240	

Initial Supporting table - P0496 Purge Valve Leak Test Engine Vacuum Test Time (Cold Start) as a Function of Fuel Level

Description: Purge valve leak test engine vacuum test time as a function of fuel level

Value Units: Purge Valve Leak Test Engine Vacuum Test Time (seconds)
X Unit: Fuel Level (percent)

y/x	0	6	12	19	25	31	37	44	50	56	62	69	75	81	87	94	100
1	32	32	32	32	32	32	32	32	32	32	32	31	29	28	26	25	25

Initial Supporting table - Cool Down Diagnostic Min Heat to Coolant

Description: KtECTR_P_CDD_HeatToCoolantMin

Value Units: Power (kW)
X Unit: Firing fraction (ratio)
Y Units: Ambient Air Temperature (Deg C)

y/x	0.00	0.25	0.50	0.75	1.00
-9.0	2.5	2.5	2.5	2.5	2.5
0.0	2.5	2.5	2.5	2.5	2.5
10.0	2.5	2.5	2.5	2.5	2.5
20.0	2.5	2.5	2.5	2.5	2.5
50.0	2.5	2.5	2.5	2.5	2.5

Initial Supporting table - P057B KtBRKI_K_CmpltTestPointWeight

Description:

y/x	0.000	0.020	0.040	0.250	0.350	0.450	0.550	0.750	1.000
1	0	1	1	1	1	1	1	1	1

Initial Supporting table - P057B KtBRKI_K_FastTestPointWeight

Description:

y/x	0.000	0.020	0.040	0.250	0.350	0.450	0.550	0.750	1.000
1	0	1	1	1	1	1	1	1	1

Initial Supporting table - DFCO_CoolEnblHi_Temp

Description:

y/x	-40	0	25
1	20.0	20.0	20.0

Initial Supporting table - DFCO_DelayAfterStart_Time

Description:

y/x	-30	-10	20	60	90
1	20.0	5.0	5.0	5.0	5.0

Initial Supporting table - DFCO_DsblLo_Vehicle_Speed

Description:

y/x	CeTCOR_e_NonEcoMode	CeTCOR_e_EcoMode
CeTGRR_e_TransGr1	0	0
CeTGRR_e_TransGr2	0	0
CeTGRR_e_TransGr3	0	0
CeTGRR_e_TransGr4	0	0
CeTGRR_e_TransGr5	0	0
CeTGRR_e_TransGr6	0	0
CeTGRR_e_TransGr9	0	0
CeTGRR_e_TransGr10	0	0
CeTGRR_e_TransGrNeut	0	0
CeTGRR_e_TransGrRvrs	0	0
CeTGRR_e_TransGrPark	0	0
CeTGRR_e_TransGr7	0	0
CeTGRR_e_TransGr8	0	0

Initial Supporting table - DFCO_EnblHi_Vehicle_Speed

Description:

y/x	CeTCOR_e_NonEcoMode	CeTCOR_e_EcoMode
CeTGRR_e_TransGr1	0.0	0.0
CeTGRR_e_TransGr2	0.0	0.0
CeTGRR_e_TransGr3	0.0	0.0
CeTGRR_e_TransGr4	0.0	0.0
CeTGRR_e_TransGr5	0.0	0.0
CeTGRR_e_TransGr6	0.0	0.0
CeTGRR_e_TransGr9	0.0	0.0
CeTGRR_e_TransGr10	0.0	0.0
CeTGRR_e_TransGrNeut	0.0	0.0
CeTGRR_e_TransGrRvrs	0.0	0.0
CeTGRR_e_TransGrPark	0.0	0.0
CeTGRR_e_TransGr7	0.0	0.0
CeTGRR_e_TransGr8	0.0	0.0

Initial Supporting table - DFCO_EngSpdEnblOfst

Description:

y/x	-1,750	-1,500	-1,250	-1,000	-700	-500	-300	-100	0
1	0	0	0	0	0	0	0	0	0

Initial Supporting table - Minimum Non-Purge Samples for Purge Vapor Fuel

Description: Number of Fuel Trim Monitor sample counts required to allow the Purge Vapor Fuel value to inhibit the Intrusive Rich test

Value Units: Sample Counts per loop rate of 100ms (divide by 10 to get seconds)
X Unit: Long Term Fuel Trim Cell I.D. (no units) (Only PurgeOff cells are used)

Minimum Non-Purge Samples for Purge Vapor Fuel - Part 1

y/x	CeFADR_e_Cell00_PurgOnAirMode5	CeFADR_e_Cell01_PurgOnAirMode4	CeFADR_e_Cell02_PurgOnAirMode3	CeFADR_e_Cell03_PurgOnAirMode2
1	65,535	65,535	65,535	65,535

Minimum Non-Purge Samples for Purge Vapor Fuel - Part 2

y/x	CeFADR_e_Cell04_PurgOnAirMode1	CeFADR_e_Cell05_PurgOnAirMode0	CeFADR_e_Cell06_PurgOnIdle	CeFADR_e_Cell07_PurgOnDecel
1	65,535	65,535	65,535	65,535

Minimum Non-Purge Samples for Purge Vapor Fuel - Part 3

y/x	CeFADR_e_Cell08_PurgOffAirMode5	CeFADR_e_Cell09_PurgOffAirMode4	CeFADR_e_Cell10_PurgOffAirMode3	CeFADR_e_Cell11_PurgOffAirMode2
1	65,535	65,535	65,535	65,535

Minimum Non-Purge Samples for Purge Vapor Fuel - Part 4

y/x	CeFADR_e_Cell12_PurgOffAirMode1	CeFADR_e_Cell13_PurgOffAirMode0	CeFADR_e_Cell14_PurgOffIdle	CeFADR_e_Cell15_PurgOffDecel
1	65,535	65,535	65,535	65,535

Initial Supporting table - P0171_P0172_P0174_P0175 Long-Term Fuel Trim Cell Usage

Description: Identifies which Long Term Fuel Trim Cell I.D.s are used for diagnosis. Only cells identified as "CeFADD_e_NonSelectedCell" are not used for diagnosis.

P0171_P0172_P0174_P0175 Long-Term Fuel Trim Cell Usage - Part 1

y/x	CeFADR_e_Cell00_PurgOnAirMode5	CeFADR_e_Cell01_PurgOnAirMode4	CeFADR_e_Cell02_PurgOnAirMode3	CeFADR_e_Cell03_PurgOnAirMode2
1	CeFADD_e_SelectedPurgeCell	CeFADD_e_SelectedPurgeCell	CeFADD_e_SelectedPurgeCell	CeFADD_e_SelectedPurgeCell

P0171_P0172_P0174_P0175 Long-Term Fuel Trim Cell Usage - Part 2

y/x	CeFADR_e_Cell04_PurgOnAirMode1	CeFADR_e_Cell05_PurgOnAirMode0	CeFADR_e_Cell06_PurgOnIdle	CeFADR_e_Cell07_PurgOnDecel
1	CeFADD_e_SelectedPurgeCell	CeFADD_e_SelectedPurgeCell	CeFADD_e_SelectedPurgeCell	CeFADD_e_SelectedPurgeCell

P0171_P0172_P0174_P0175 Long-Term Fuel Trim Cell Usage - Part 3

y/x	CeFADR_e_Cell08_PurgOffAirMode5	CeFADR_e_Cell09_PurgOffAirMode4	CeFADR_e_Cell10_PurgOffAirMode3	CeFADR_e_Cell11_PurgOffAirMode2
1	CeFADD_e_SelectedNonPurgeCell	CeFADD_e_SelectedNonPurgeCell	CeFADD_e_SelectedNonPurgeCell	CeFADD_e_SelectedNonPurgeCell

P0171_P0172_P0174_P0175 Long-Term Fuel Trim Cell Usage - Part 4

y/x	CeFADR_e_Cell12_PurgOffAirMode1	CeFADR_e_Cell13_PurgOffAirMode0	CeFADR_e_Cell14_PurgOffIdle	CeFADR_e_Cell15_PurgOffDecel
1	CeFADD_e_SelectedNonPurgeCell	CeFADD_e_SelectedNonPurgeCell	CeFADD_e_SelectedNonPurgeCell	CeFADD_e_SelectedNonPurgeCell

Initial Supporting table - P219A EWMA Coefficient

Description: The bank 1 EWMA coefficient used to filter the AFIM Variance Ratio.

Value Units: Unitless Scalar
X Unit: Unitless Scalar

y/x	-1.00	-0.50	0.00	0.50	1.00
1	0.12	0.12	0.12	0.12	0.12

Initial Supporting table - P219A Normalizer Bank1 Table

Description: Bank 1 Normalizer table used in the calculation of the Ratio for the current sample period.

Value Units: Unitless Scalar
X Unit: Engine Speed (RPM)
Y Units: Air Per Cylinder (APC) (mg/cylinder)

y/x	250	500	750	1,000	1,250	1,500	1,750	2,000	2,250	2,500	2,750	3,000	3,500	4,000	4,500	5,000	6,000
40	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00
80	400.00	400.00	400.00	1.25	1.25	1.25	2.00	2.00	2.00	400.00	2.50	2.50	2.75	2.75	400.00	400.00	400.00
120	400.00	400.00	400.00	1.25	1.25	5.50	2.50	2.00	2.00	6.00	3.75	2.50	2.75	3.50	4.00	400.00	400.00
160	400.00	2.00	2.00	5.00	5.00	10.00	2.75	2.50	8.25	6.00	5.00	4.25	2.00	4.00	4.00	400.00	400.00
200	400.00	2.00	2.00	2.00	9.50	14.00	1.50	12.50	10.50	9.00	6.25	7.50	3.75	2.75	2.75	400.00	400.00
240	400.00	2.00	2.00	2.00	14.00	14.00	14.25	25.25	6.00	7.00	3.50	13.50	6.00	4.50	2.75	400.00	400.00
280	400.00	400.00	400.00	400.00	400.00	16.00	16.00	24.00	39.50	13.00	9.25	22.75	14.50	6.00	400.00	400.00	400.00
320	400.00	400.00	400.00	400.00	400.00	30.00	30.00	39.75	20.25	13.00	19.50	21.00	22.75	400.00	400.00	400.00	400.00
360	400.00	400.00	400.00	400.00	400.00	30.00	30.00	39.75	25.00	30.00	24.75	19.50	400.00	400.00	400.00	400.00	400.00
400	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	30.00	30.00	30.00	400.00	400.00	400.00	400.00	400.00	400.00
440	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00
480	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00
520	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00
560	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00
640	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00
720	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00
800	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00	400.00

Initial Supporting table - P219A Quality Factor Bank1 Table

Description: Bank 1 lookup table of Quality Factors used in the calculation of the Ratio for the current sample period

Value Units: Unitless Scalar
X Unit: Engine Speed (RPM)
Y Units: Air Per Cylinder (APC) (mg/cylinder)

y/x	250	500	750	1,000	1,250	1,500	1,750	2,000	2,250	2,500	2,750	3,000	3,500	4,000	4,500	5,000	6,000
40	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
80	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
120	0.00	0.00	0.00	0.00	1.00	0.00	0.00	1.00	0.00	0.00	0.00	1.00	1.00	0.00	0.00	0.00	0.00
160	0.00	0.00	0.00	0.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	0.00	0.00	0.00
200	0.00	0.00	0.00	0.00	0.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	0.00	0.00	0.00
240	0.00	0.00	0.00	0.00	0.00	0.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	0.00	0.00	0.00	0.00
280	0.00	0.00	0.00	0.00	0.00	0.00	1.00	1.00	1.00	1.00	1.00	1.00	0.00	0.00	0.00	0.00	0.00
320	0.00	0.00	0.00	0.00	0.00	0.00	1.00	1.00	1.00	1.00	1.00	0.00	0.00	0.00	0.00	0.00	0.00
360	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	1.00	1.00	0.00	0.00	0.00	0.00	0.00	0.00
400	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
440	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
480	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
520	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
560	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
640	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
720	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
800	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00

Initial Supporting table - P219A Variance Threshold Bank1 Table

Description: Bank 1 lookup table of Variance metric used to calculate the Ratio for the current sample period

Value Units: Unitless ratio
X Unit: Engine Speed (RPM)
Y Units: Air Per Cylinder (APC) (mg/cylinder)

y/x	250	500	750	1,000	1,250	1,500	1,750	2,000	2,250	2,500	2,750	3,000	3,500	4,000	4,500	5,000	6,000
40	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00
80	200.00	200.00	200.00	3.25	3.25	3.25	6.75	6.75	6.75	200.00	1.25	1.25	2.50	2.50	200.00	200.00	200.00
120	200.00	200.00	200.00	3.25	3.25	4.00	5.75	6.75	6.75	6.25	3.00	1.25	2.50	2.50	2.75	200.00	200.00
160	200.00	1.50	1.50	5.75	5.75	4.50	4.50	5.75	6.25	6.25	4.75	2.00	2.75	2.75	2.75	200.00	200.00
200	200.00	1.50	1.50	1.50	6.50	7.25	10.50	9.00	6.00	6.75	6.00	5.00	5.75	6.00	6.00	200.00	200.00
240	200.00	1.50	1.50	1.50	7.25	7.25	12.00	10.50	12.00	6.25	7.50	6.00	6.75	6.50	6.00	200.00	200.00
280	200.00	200.00	200.00	200.00	200.00	15.00	15.00	12.75	11.50	11.50	9.50	6.00	6.25	6.75	200.00	200.00	200.00
320	200.00	200.00	200.00	200.00	200.00	15.75	15.75	11.00	13.25	12.50	9.25	7.75	6.00	200.00	200.00	200.00	200.00
360	200.00	200.00	200.00	200.00	200.00	15.75	15.75	11.00	11.25	9.50	9.25	9.25	200.00	200.00	200.00	200.00	200.00
400	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	9.50	9.50	9.50	200.00	200.00	200.00	200.00	200.00	200.00
440	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00
480	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00
520	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00
560	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00
640	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00
720	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00
800	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00	200.00

Initial Supporting table - P0068_Delta MAF Threshold f(TPS)

Description: Table of delta MAF values as a function of desired throttle position. The output of this table provides a delta MAF that if the measured minus the estimated MAF exceeds, is considered a fail.

Value Units: Delta MAF Values (dm)
X Unit: Desired Throttle Position (Pct)

y/x	5.00	10.00	15.00	20.00	25.00	30.00	35.00	40.00	100.00
1.00	11.88	11.88	11.88	13.68	16.35	19.65	14.20	255.00	255.00

Initial Supporting table - P0068_Delta MAP Threshold f(TPS)

Description: Table of delta MAP values as a function of desired throttle position. The output of this table provides a delta MAP that if the measured minus the estimated MAP exceeds, is considered a fail.

Value Units: Delta MAP Values (kPa)
X Unit: Desired Throttle Position (Pct)

y/x	5.00	10.00	15.00	20.00	25.00	30.00	35.00	40.00	100.00
1.00	46.31	46.31	46.31	40.46	42.35	37.07	22.42	255.00	255.00

Initial Supporting table - P0068_Maximum MAF f(RPM)

Description: Table of maximum MAF values vs. engine speed. This is the maximum MAF the engine can see under all ambient conditions.

Value Units: Delta MAF Values (dm)
X Unit: Engine Speed (RPM)

y/x	600.00	1,400.00	2,200.00	3,000.00	3,800.00	4,600.00	5,400.00	6,200.00	7,000.00
1.00	20.00	20.00	20.00	20.00	20.00	20.00	20.00	20.00	20.00

Initial Supporting table - P0068_Maximum MAF f(Volts)

Description: Table of maximum MAF values vs. system voltage. The output of the air meter is clamped to lower values as system voltage drops off.

Value Units: Delta MAF Values (dm)
X Unit: System Voltage (V)

y/x	6.00	7.00	8.00	9.00	10.00	11.00	12.00	13.00	14.00
1.00	511.99	511.99	511.99	511.99	511.99	511.99	511.99	511.99	511.99

Initial Supporting table - P0326_P0331_AbnormalNoise_Thresh_AFM

Description: Fail threshold for the Knock Performance Abnormal Noise Diagnostic when engine IS in AFM mode

y/x	500	1,000	1,500	2,000	2,500	3,000	3,500	4,000	4,500	5,000	5,500	6,000	6,500	7,000	7,500	8,000	8,500
1	0.452	0.452	0.452	0.342	0.271	0.223	0.199	0.168	0.148	0.134	0.119	0.119	0.113	0.104	0.093	0.085	0.072

Initial Supporting table - P0606_Last Seed Timeout f(Loop Time)

Description: The max time for the Last Seed Timeout as a function of operating loop time sequence.

Value Units: Max Time for Last Seed Timeout (ms)
X Unit: Operating Loop Sequence (enum)

P0606_Last Seed Timeout f(Loop Time) - Part 1

y/x	CePISR_e_5msSeq	CePISR_e_6p25msSeq	CePISR_e_10msSeq	CePISR_e_12p5msSeq	CePISR_e_20msSeq	CePISR_e_25msSeq	CePISR_e_40msSeq
1	200.000	200.000	200.000	200.000	200.000	200.000	200.000

P0606_Last Seed Timeout f(Loop Time) - Part 2

y/x	CePISR_e_50msSeq	CePISR_e_80msSeq	CePISR_e_100msSeq	CePISR_e_EventA_Seq	CePISR_e_EventB_Seq	CePISR_e_EventC_Seq	
1	500.000	500.000	1,000.000	8,191.875	8,191.875	8,191.875	

Initial Supporting table - P0606_PSW Sequence Fail f(Loop Time)

Description: Fail threshold for PSW per operating loop.

Value Units: Fail threshold for PSW (count)
X Unit: Operating Loop (enum)

P0606_PSW Sequence Fail f(Loop Time) - Part 1

y/x	CePISR_e_5msSeq	CePISR_e_6p25msSeq	CePISR_e_10msSeq	CePISR_e_12p5msSeq	CePISR_e_20msSeq	CePISR_e_25msSeq	CePISR_e_40msSeq
1	5	3	5	3	5	3	5

P0606_PSW Sequence Fail f(Loop Time) - Part 2

y/x	CePISR_e_50msSeq	CePISR_e_80msSeq	CePISR_e_100msSeq	CePISR_e_EventA_Seq	CePISR_e_EventB_Seq	CePISR_e_EventC_Seq	
1	3	5	3	5	5	5	

Initial Supporting table - P0606_PSW Sequence Sample f(Loop Time)

Description: Sample threshold for PSW per operating loop.

Value Units: Sample threshold for PSW (count)
X Unit: Operating Loop (enum)

P0606_PSW Sequence Sample f(Loop Time) - Part 1

y/x	CePISR_e_5msSeq	CePISR_e_6p25msSeq	CePISR_e_10msSeq	CePISR_e_12p5msSeq	CePISR_e_20msSeq	CePISR_e_25msSeq	CePISR_e_40msSeq
1	4	4	4	4	4	4	4

P0606_PSW Sequence Sample f(Loop Time) - Part 2

y/x	CePISR_e_50msSeq	CePISR_e_80msSeq	CePISR_e_100msSeq	CePISR_e_EventA_Seq	CePISR_e_EventB_Seq	CePISR_e_EventC_Seq	
1	4	4	4	4	4	4	

Initial Supporting table - P1682_PT Relay Pull-in Run/Crank Voltage f(IAT)

Description: The Run/Crank voltages required to pull in the PT relay as a function of induction air temperature.

Value Units: Run/Crank Voltages required to pull in PT Relay (V)
X Unit: Induction Air Temperature (deg C)

y/x	23.0	85.0	95.0	105.0	125.0
1	7.000	8.699	9.000	9.199	10.000

Initial Supporting table - P16F3_Delta MAP Threshold f(Desired Engine Torque)

Description: Engine Sync based and Time based delta pressure threshold above which Torque Security error is reported.

Value Units: Torque Security Threshold for Engine Sync and Time Based Delta Pressure (kPa)
X Unit: Desired Engine Torque (Nm)

y/x	0.00	50.00	100.00	150.00	200.00	300.00
1.00	22.42	22.42	22.42	22.42	22.42	22.42

Initial Supporting table - P16F3_Speed Control External Load f(Oil Temp, RPM)

Description: Specifies the external load table for SPDR torque security as a function of engine oil temperature and engine RPM.

Value Units: External Load Table for SPDR (Nm)
X Unit: Engine Oil Temperature (deg C)
Y Units: Engine Speed (RPM)

y/x	-40.00	-20.00	-10.00	0.00	50.00	90.00
350.00	97.30	89.43	81.50	74.83	55.30	46.30
450.00	97.30	89.43	81.50	74.83	55.30	46.30
550.00	97.30	89.43	81.50	74.83	55.30	46.30
650.00	96.70	88.83	80.90	74.23	54.70	45.70
680.00	97.30	89.43	81.50	74.83	55.30	46.30
780.00	100.71	92.40	83.74	77.84	57.63	46.95
900.00	102.32	92.66	83.05	78.07	61.69	49.78
1,000.00	100.86	91.30	81.83	77.00	61.50	48.78
1,100.00	99.50	89.28	77.42	74.46	61.37	43.60
1,200.00	96.31	83.95	70.71	68.59	59.35	38.62
1,450.00	77.75	69.48	62.60	58.01	43.74	38.94
1,700.00	40.51	31.34	24.20	19.95	8.92	4.61
1,950.00	23.74	14.98	8.24	4.31	-5.55	-9.40
2,200.00	9.83	1.34	-5.13	-8.85	-17.93	-21.48
3,200.00	-38.30	-38.30	-38.30	-38.30	-38.30	-38.30
4,200.00	-42.13	-42.13	-42.13	-42.13	-42.13	-42.13
6,400.00	-45.96	-45.96	-45.96	-45.96	-45.96	-45.96

Initial Supporting table - RufCyl_Decel

Description: Used for P0300-P0308. Crankshaft decel threshold during Idle or GPF regen. Thresholds are a function of rpm and % engine Load.

Value Units: Delta time per cylinder (usec)
X Unit: rpm
Y Units: percent load of max indicated torque (%)

RufCyl_Decel - Part 1

y/x	400	500	600	700	800	900	1,000	1,100	1,200	1,400	1,600	1,800	2,000
3	3,785	2,010	1,228	1,228	1,228	900	600	505	400	230	200	150	90
6	3,785	2,010	1,228	1,228	1,228	900	600	505	400	230	200	150	90
8	4,100	2,200	1,228	1,228	1,228	900	600	505	400	230	200	150	90
10	4,430	2,360	1,228	1,228	1,228	900	600	505	400	230	200	150	90
12	4,770	2,550	1,800	1,530	1,300	900	600	505	400	230	200	150	90
14	5,130	2,800	2,000	1,600	1,315	900	600	505	400	230	220	150	95
16	5,500	2,950	2,000	1,800	1,426	900	600	505	400	242	251	160	105
18	5,880	3,200	2,100	1,800	1,500	970	600	600	400	325	272	178	118
20	6,300	3,400	2,200	1,900	1,510	985	895	780	552	357	299	189	129
22	6,660	3,600	2,300	2,100	1,525	990	899	790	558	336	391	220	139
24	7,100	3,900	2,500	2,400	1,530	991	900	800	559	300	413	288	184
26	7,470	4,050	2,550	2,450	1,685	1,000	951	850	506	322	459	346	199
30	8,150	4,420	2,700	2,500	1,779	1,050	1,030	900	548	499	520	420	261
40	9,990	5,450	2,794	2,794	2,794	1,457	1,200	1,000	720	632	525	445	308
60	12,600	7,510	2,794	2,794	2,794	1,457	1,200	1,000	800	790	525	445	308
78	12,601	9,260	2,794	2,794	2,794	1,457	1,200	1,000	800	790	525	445	308
97	12,601	11,310	2,794	2,794	2,794	1,457	1,200	1,000	800	790	525	445	308

RufCyl_Decel - Part 2

y/x	2,200	2,400	2,600	2,800	3,000	3,500	4,000	4,500	5,000	5,500	6,000	6,500	7,000
3	85	70	60	40	20	7	4	4	4	3	3	3	3
6	85	70	60	40	20	7	4	4	4	3	3	3	3
8	85	70	60	40	20	7	4	4	4	3	3	3	3
10	85	70	60	40	20	7	4	4	4	3	3	3	3
12	85	70	60	40	20	7	4	4	4	3	3	3	3
14	90	70	60	40	20	7	4	5	5	3	3	3	3
16	100	90	60	40	20	13	6	5	5	3	3	3	3
18	115	110	80	40	20	13	7	5	5	4	3	3	3
20	125	110	80	50	40	14	8	6	6	4	3	3	3
22	135	110	80	60	40	14	8	8	6	4	4	4	4
24	167	135	100	70	50	16	9	9	7	5	4	4	4

Initial Supporting table - RufCyl_Decel

26	210	136	110	80	60	16	10	8	7	5	4	4	4
30	220	170	120	90	70	18	11	9	8	6	4	4	4
40	246	184	134	105	95	21	14	11	9	7	5	5	5
60	246	220	175	137	108	29	22	16	12	10	7	7	7
78	246	220	175	137	108	29	22	16	12	10	7	7	7
97	246	220	175	137	108	29	22	16	12	10	7	7	7

Initial Supporting table - RufCyl_Jerk

Description: Crankshaft jerk threshold during Idle or GPF regen. Thresholds are a function of rpm and % engine Load.

Value Units: Delta time per cylinder (usec)
X Unit: rpm
Y Units: percent load of max indicated torque (%)

RufCyl_Jerk - Part 1

y/x	400	500	600	700	800	900	1,000	1,100	1,200	1,400	1,600	1,800	2,000
3	6,380	3,233	3,233	3,233	2,600	1,710	800	760	488	279	200	160	140
6	6,380	3,233	3,233	3,233	2,600	1,710	800	760	488	279	200	160	140
8	7,100	3,640	3,300	3,233	2,400	1,710	800	760	488	279	200	160	140
10	7,850	4,040	3,400	3,233	2,450	1,720	1,210	825	520	326	250	180	140
12	8,650	4,470	3,233	3,233	2,500	1,750	1,230	850	621	333	280	230	155
14	9,500	4,920	3,600	3,313	3,100	1,800	1,290	890	700	360	290	273	155
16	10,370	5,390	3,857	3,857	3,200	2,000	1,450	1,100	740	369	272	300	200
18	11,280	5,880	4,759	4,759	3,300	2,200	1,700	1,300	752	325	282	373	215
20	12,210	6,380	5,300	5,300	3,400	2,990	1,800	1,450	753	337	318	380	270
22	12,600	6,900	5,405	5,405	4,200	3,000	1,950	1,924	754	334	400	390	290
24	12,601	7,420	5,616	5,616	5,400	3,017	1,970	1,945	760	326	600	450	330
26	12,601	7,950	5,994	5,994	5,800	3,500	2,500	2,026	740	320	630	500	390
30	13,500	8,780	6,391	6,391	6,200	3,800	3,300	2,210	1,224	666	700	540	410
40	13,501	11,140	7,008	7,008	7,008	5,534	4,400	2,210	1,365	990	900	780	540
60	13,501	13,500	7,008	7,008	7,008	5,534	4,730	2,210	2,100	1,617	1,313	950	546
78	13,501	13,501	7,008	7,008	7,008	5,534	4,730	2,210	2,100	1,617	1,313	950	546
97	13,501	13,501	7,008	7,008	7,008	5,534	4,730	2,210	2,100	1,617	1,313	950	546

RufCyl_Jerk - Part 2

y/x	2,200	2,400	2,600	2,800	3,000	3,500	4,000	4,500	5,000	5,500	6,000	6,500	7,000
3	120	80	70	53	45	14	7	4	3	3	3	3	3
6	120	80	70	53	45	14	7	4	3	3	3	3	3
8	120	80	70	53	45	14	7	4	3	3	3	3	3
10	120	80	70	53	45	14	7	4	3	3	3	3	3
12	130	120	100	65	55	19	12	6	3	3	3	3	3
14	153	150	110	90	85	19	12	7	3	3	3	3	3
16	153	150	110	105	100	22	13	8	3	4	3	3	3
18	155	151	120	105	100	23	15	9	7	5	4	4	4
20	165	160	130	105	100	29	20	12	8	6	5	5	5
22	170	165	135	105	100	34	24	13	10	7	5	5	5
24	175	170	155	120	105	39	25	16	10	8	6	6	6

Initial Supporting table - RufCyl_Jerk

26	280	220	175	145	120	45	30	17	12	10	7	7	7
30	310	230	200	165	130	53	36	21	14	10	8	8	8
40	434	320	250	210	180	77	50	34	23	18	13	13	13
60	434	320	330	280	250	100	70	53	39	29	23	23	23
78	434	320	330	280	250	100	70	53	39	29	23	23	23
97	434	320	330	280	250	100	70	53	39	29	23	23	23

Initial Supporting table - RufSCD_Decel

Description: Used for P0300-P0308. Crankshaft decel threshold while in SCD mode during Idle or GPF regen. SCD mode uses smaller windows near TDC. Thresholds are a function of rpm and % engine Load. Note: Misfire's Load term is %, but not PID$04. PID $04 is not robust to temperature and alititude shifts. (especially decel and jerk thresholds since they track actual air trapped in cylinder)

Value Units: Delta time per cylinder (usec)
X Unit: rpm
Y Units: percent load of max indicated torque (%)

RufSCD_Decel - Part 1

y/x	400	500	600	700	800	900	1,000	1,100	1,200	1,400	1,600	1,800	2,000
3	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
6	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
8	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
10	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
12	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
14	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
16	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
18	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
20	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
22	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
24	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
26	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
30	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
40	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
60	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
78	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
97	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767

RufSCD_Decel - Part 2

y/x	2,200	2,400	2,600	2,800	3,000	3,500	4,000	4,500	5,000	5,500	6,000	6,500	7,000
3	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
6	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
8	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
10	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
12	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
14	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
16	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
18	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
20	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767

Initial Supporting table - RufSCD_Decel

22	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
24	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
26	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
30	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
40	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
60	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
78	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
97	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767

Initial Supporting table - RufSCD_Jerk

Description: Used for P0300-P0308. Crankshaft jerk threshold while in SCD mode during Idle or GPF regen. SCD mode uses smaller windows near TDC. Thresholds are a function of rpm and % engine Load.

Value Units: Delta time per cylinder (usec)
X Unit: rpm
Y Units: percent load of max indicated torque (%)

RufSCD_Jerk - Part 1

y/x	400	500	600	700	800	900	1,000	1,100	1,200	1,400	1,600	1,800	2,000
3	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
6	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
8	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
10	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
12	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
14	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
16	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
18	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
20	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
22	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
24	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
26	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
30	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
40	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
60	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
78	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
97	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767

RufSCD_Jerk - Part 2

y/x	2,200	2,400	2,600	2,800	3,000	3,500	4,000	4,500	5,000	5,500	6,000	6,500	7,000
3	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
6	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
8	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
10	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
12	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
14	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
16	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
18	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
20	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
22	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767

Initial Supporting table - RufSCD_Jerk

24	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
26	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
30	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
40	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
60	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
78	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
97	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767

Initial Supporting table - P0324_PerCyl_ExcessiveKnock_Threshold

Description: Fail threshold for the Knock Performance per-cylinder Excessive Knock Diagnostic

y/x	500	1,000	1,500	2,000	2,500	3,000	3,500	4,000	4,500	5,000	5,500	6,000	6,500	7,000	7,500	8,000	8,500
1	2.00	2.00	2.00	2.00	2.00	2.00	2.00	2.00	2.00	2.00	2.00	2.00	2.00	2.00	2.00	2.00	2.00

Initial Supporting table - P0325_P0330_OpenCktThrshMax (20 kHz)

Description: Knock Open Circuit Diagnostic Maximum Threshold when using the 20 kHz method (see "OpenMethod" description)

y/x	500	1,000	1,500	2,000	2,500	3,000	3,500	4,000	4,500	5,000	5,500	6,000	6,500	7,000	7,500	8,000	8,500
1	1.7402	1.7305	1.7285	1.7266	1.7070	1.6953	1.7051	1.6777	1.6973	1.5449	1.4121	1.2773	1.1895	0.9883	0.8809	0.7734	0.6602

Initial Supporting table - P0325_P0330_OpenCktThrshMax (Normal Noise)

Description: Knock Open Circuit Diagnostic Minimum Threshold when using the Normal Noise method (see "OpenMethod" description): When using the Normal Noise method (see "OpenMethod" description).

y/x	500	1,000	1,500	2,000	2,500	3,000	3,500	4,000	4,500	5,000	5,500	6,000	6,500	7,000	7,500	8,000	8,500
1	0.4668	0.4102	0.3672	0.3359	0.3145	0.2988	0.2930	0.2891	0.2891	0.2910	0.2930	0.2910	0.2891	0.2793	0.2656	0.2402	0.2070

Initial Supporting table - P0325_P0330_OpenCktThrshMin (20 kHz)

Description: Knock Open Circuit Diagnostic Minimum Threshold when using the 20 kHz method (see "OpenMethod" description)

y/x	500	1,000	1,500	2,000	2,500	3,000	3,500	4,000	4,500	5,000	5,500	6,000	6,500	7,000	7,500	8,000	8,500
1	0.7500	0.7422	0.7383	0.7363	0.7227	0.7129	0.7246	0.7129	0.7148	0.6563	0.6016	0.5508	0.5273	0.4824	0.4453	0.4121	0.3887

Initial Supporting table - P0325_P0330_OpenCktThrshMin (Normal Noise)

Description: Knock Open Circuit Diagnostic Minimum Threshold when using the Normal Noise method (see "OpenMethod" description): When using the Normal Noise method (see "OpenMethod" description).

y/x	500	1,000	1,500	2,000	2,500	3,000	3,500	4,000	4,500	5,000	5,500	6,000	6,500	7,000	7,500	8,000	8,500
1	0.2422	0.1895	0.1523	0.1289	0.1191	0.1211	0.1387	0.1680	0.2090	0.2617	0.3281	0.4043	0.4941	0.5918	0.7012	0.8223	0.9531

Initial Supporting table - P0325_P0330_OpenMethod_2

Description: Defines which Knock Open Circuit Diagnostic method to use.

P0325_P0330_OpenMethod_2 - Part 1

y/x	0	1	2	3	4
1	CeKNKD_e_Open_20KHz	CeKNKD_e_Open_20KHz	CeKNKD_e_Open_20KHz	CeKNKD_e_Open_20KHz	CeKNKD_e_Open_20KHz

P0325_P0330_OpenMethod_2 - Part 2

y/x	5	6	7	8	9
1	CeKNKD_e_Open_20KHz	CeKNKD_e_Open_20KHz	CeKNKD_e_Open_20KHz	CeKNKD_e_Open_20KHz	CeKNKD_e_Open_20KHz

P0325_P0330_OpenMethod_2 - Part 3

y/x	10	11	12	13	14
1	CeKNKD_e_Open_20KHz	CeKNKD_e_Open_20KHz	CeKNKD_e_Open_20KHz	CeKNKD_e_Open_20KHz	CeKNKD_e_Open_20KHz

P0325_P0330_OpenMethod_2 - Part 4

y/x	15	16			
1	CeKNKD_e_Open_20KHz	CeKNKD_e_Open_20KHz			

Initial Supporting table - P0326_P0331_AbnormalNoise_CylsEnabled

Description: Specifies which cylinders will be used for the Abnormal Noise portion of the performance diagnostics (1 = cylinder used, 0 = cylinder not used)

y/x	0	1	2	3	4	5	6	7
1	1	1	1	1	0	0	0	0

Initial Supporting table - P0326_P0331_AbnormalNoise_Threshold

Description: Fail threshold for the Knock Performance Abnormal Noise Diagnostic when engine is NOT in AFM mode

y/x	500	1,000	1,500	2,000	2,500	3,000	3,500	4,000	4,500	5,000	5,500	6,000	6,500	7,000	7,500	8,000	8,500
1	0.167	0.167	0.167	0.116	0.106	0.082	0.075	0.083	0.067	0.067	0.051	0.096	0.096	0.096	0.096	0.096	0.096

Initial Supporting table - P06B6_P06B7_OpenTestCktThrshMax

Description: Knock Open Circuit Minimum Threshold for Internal Circuit Diagnostic. Used only when the 20 kHz method is being used (see "OpenMethod" description). The Open Test Circuit ensures that the internal circuit used to generate the 20 kHz signal for the Open Circuit diags (P0325, P0330) is within range.

y/x	500	1,000	1,500	2,000	2,500	3,000	3,500	4,000	4,500	5,000	5,500	6,000	6,500	7,000	7,500	8,000	8,500
1	0.055	0.055	0.059	0.053	0.051	0.057	0.055	0.061	0.074	0.078	0.117	0.170	0.180	0.188	0.193	0.195	0.215

Initial Supporting table - P06B6_P06B7_OpenTestCktThrshMin

Description: Knock Open Circuit Minimum Threshold for Internal Circuit Diagnostic. Used only when the 20 kHz method is being used (see "OpenMethod" description). The Open Test Circuit ensures that the internal circuit used to generate the 20 kHz signal for the Open Circuit diags (P0325, P0330) is within range.

y/x	500	1,000	1,500	2,000	2,500	3,000	3,500	4,000	4,500	5,000	5,500	6,000	6,500	7,000	7,500	8,000	8,500
1	0.023	0.023	0.025	0.023	0.023	0.025	0.025	0.027	0.035	0.039	0.063	0.094	0.102	0.104	0.107	0.109	0.113

Component/System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Hand Wheel Angle Sensor	C0460	Checking PWM Period. Emissions neutral default action: disable steering angle based auto-stop inhibit and perform auto-stops.	PWM Period OOR High	x > 6ms	Diagnostic Voltage Vehicle Power Mode	= Enabled = 6V < voltage < 16V = RUN	500ms	Safety Emissions Neutral Diagnostic - Type C
Hand Wheel Angle Sensor	C0460	Checking PWM Period. Emissions neutral default action: disable steering angle based auto-stop inhibit and perform auto-stops.	PWM Period OOR Low	x < 4ms	Diagnostic Voltage Vehicle Power Mode	= Enabled = 6V < voltage < 16V = RUN	500ms	Safety Emissions Neutral Diagnostic - Type C
Hand Wheel Angle Sensor	C0460	Checking PWM Duty Cycle. Emissions neutral default action: disable steering angle based auto-stop inhibit and perform auto-stops.	PWM Duty Cycle OOR High	x > 90%	Diagnostic Voltage Vehicle Power Mode	= Enabled = 6V < voltage < 16V = RUN	500ms	Safety Emissions Neutral Diagnostic - Type C
Hand Wheel Angle Sensor	C0460	Checking PWM Duty Cycle. Emissions neutral default action: disable steering angle based auto-stop inhibit and perform auto-stops.	PWM Duty Cycle OOR Low	x < 10%	Diagnostic Voltage Vehicle Power Mode	= Enabled = 6V < voltage < 16V = RUN	500ms	Safety Emissions Neutral Diagnostic - Type C
Hand Wheel Angle Sensor	C0460	Rationality. Emissions neutral default action: disable steering angle based auto-stop inhibit and perform auto stops.	Vernier Reserve Misalignment	x < 25%	Diagnostic Voltage Vehicle Power Mode	= Enabled = 6V < voltage < 16V = RUN	500ms	Safety Emissions Neutral Diagnostic - Type C
Hand Wheel Angle Sensor	C0460	Rationality. Emissions neutral default action: disable steering angle based auto-stop inhibit and perform auto stops.	Rationality check between PWM and SENT1 or SENT2	x > 27°	Diagnostic Voltage Vehicle Power Mode	= Enabled = 6V < voltage < 16V = RUN	500ms	Safety Emissions Neutral Diagnostic - Type C
Hand Wheel Angle Sensor	C0460	Rationality. Emissions neutral default action: disable steering angle based auto-stop inhibit and perform auto stops.	Rationality check between SENT1 and SENT2	x > 2°	Diagnostic Voltage Vehicle Power Mode	= Enabled = 6V < voltage < 16V = RUN	500ms	Safety Emissions Neutral Diagnostic - Type C
Hand Wheel Angle Sensor	C0460	Checking PWM Duty Cycle. Emissions neutral default action: disable steering angle based auto-stop inhibit and perform auto-stops.	Short to 5V	x > 90%	Diagnostic Voltage Vehicle Power Mode	= Enabled = 6V < voltage < 16V = RUN	500ms	Safety Emissions Neutral Diagnostic - Type C
Hand Wheel Angle Sensor	C0460	Checking PWM Duty Cycle. Emissions neutral default action: disable steering angle based auto-stop inhibit and perform auto-stops.	Short to GND	x > 90%	Diagnostic Voltage Vehicle Power Mode	= Enabled = 6V < voltage < 16V = RUN	500ms	Safety Emissions Neutral Diagnostic - Type C

Component/System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Hand Wheel Angle Sensor	C0460	Checking PWM Duty Cycle. Emissions neutral default action: disable steering angle based auto-stop inhibit and perform auto-stops.	Open Circuit	x < 10%	Diagnostic Voltage Vehicle Power Mode	= Enabled = 6V < voltage < 16V = RUN	500ms	Safety Emissions Neutral Diagnostic - Type C
Hand Wheel Angle Sensor	C0460	Voltage OOR. Emissions neutral default action: disable steering angle based auto-stop inhibit and perform auto stops.	High sensor voltage	x > 5.5V	Diagnostic Voltage Vehicle Power Mode	= Enabled = 6V < voltage < 16V = RUN	500ms	Safety Emissions Neutral Diagnostic - Type C
Hand Wheel Angle Sensor	C0460	Voltage OOR. Emissions neutral default action: disable steering angle based auto-stop inhibit and perform auto stops.	Low sensor voltage	x < 4.55V	Diagnostic Voltage Vehicle Power Mode	= Enabled = 6V < voltage < 16V = RUN	500ms	Safety Emissions Neutral Diagnostic - Type C
Torsion Angle Sensor	C0545	Rationality. Emissions neutral default action: disable steering angle based auto-stop inhibit and perform auto stops.	SENT 1 and SENT 2 threshold exceeded	x > 1°	Diagnostic Voltage Vehicle Power Mode	= Enabled = 6V < voltage < 16V = RUN	32ms	Safety Emissions Neutral Diagnostic - Type C
ECU Hardware Interface	C056D	Sensor Regulator Output Voltage. Emissions neutral default action: disable steering angle based auto-stop inhibit and perform auto-stops.	Voltage OOR for 32ms [TAS Sensor]	4.5V > x > 5.5V	Diagnostic Voltage Vehicle Power Mode	= Enabled = 6V < voltage < 16V = RUN	32ms	Safety Emissions Neutral Diagnostic - Type C
ECU Hardware Interface	C056D	Sensor Regulator Output Voltage. Emissions neutral default action: disable steering angle based auto-stop inhibit and perform auto-stops.	Voltage OOR for 500ms [SAS Sensor]	4.5V > x > 5.5V	Diagnostic Voltage Vehicle Power Mode	= Enabled = 6V < voltage < 16V = RUN	500ms	Safety Emissions Neutral Diagnostic - Type C

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
System voltage (V_IGN)	P0561	System voltage (V_IGN) Performance Diagnostic	ABS(VIGN-VBatt)	≧ 3 volt			4 sec	One Trip
					System voltage (V_IGN)	>= 10 V		
					System voltage (V_IGN)	=< 32 V		
					Propulsion System Active	= TRUE		
					Starter Motor Engaged	= FALSE		
					Power Source (V_BATT)	>= 5 V		
					TCM Run Crank status	= TRUE		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: U0100, P0885, U0073		
						ECM: None		
System voltage (V_IGN)	P0562	System voltage (V_IGN) Low	System voltage (V_IGN)	< 10 volt			5 sec	No MIL
					Engine speed	>= 725 rpm		
					Actual Secondary Pressure Solenoid	> 0.3 MPa		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0842, P0843		
						ECM: P0315, P0335, P0336		
System voltage (V_IGN)	P0563	System voltage (V_IGN) High	System voltage (V_IGN)	> 16 volt			5 sec	No MIL
					Engine speed	>= 725 rpm		
					Vehicle Speed (calculated from TOSS)	>= 0.6 mph		
					Actual Secondary Pressure Solenoid	> 0.3 MPa		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0792, P0842, P0843 □3		
						ECM: P0315, P0335, P0336		
TCM CPU	P0601	ROM Fail	ROM Diagnosis (Checksum confirm) Result from OS	= Fail			Immediately	One Trip
			OR					
			Fast ROM (Checksum confirm) Diagnosis Result from OS	= Fail				
					System voltage (V_IGN)	= IGN-ON		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
Transmission Control Module (TCM)	P0602	Control Module Programming Error	Data Parameter set as 'Service TCM Status '	= ON (0x01)	None		Immediately	One Trip
				Disable Conditions:	MIL not Illuminated for DTC's:	TCM: None ECM: None		
Transmission Control Module (TCM)	P0603	Control Module Long-Term Memory Reset	Non-volatile memory (static or dynamic) checksum mismatch OR Non-volatile memory Writing Error	= TRUE = TRUE	None		Immediately after next cycle of failure detection	One Trip
				Disable Conditions:	MIL not Illuminated for DTC's:	TCM: None ECM: None		
	P0604	RAM Fail	RAM Diagnosis (Checksum confirm) Result from OS OR Fast RAM Diagnosis (Checksum confirm) Result from Operation System	= Fail = Fail	System voltage (V_IGN)	= IGN-ON	Immediately	One Trip
	P0606	CPU Fail	CPU Diagnosis Result from Operating System OR Semiconductor-Relay Stuck Off Diagnosis Result from Operating System OR Semiconductor-Relay Stuck On Diagnosis Result from Operating System	= Fail = Fail = Fail	System voltage (V_IGN)	= after IGN-ON before TCM Power-Off (after IGN Off)	Immediately	One Trip
A/T Range (TR) Switch	P0705	Transmission Range Switch Circuit	Fail Case 1 The range signal from the TR switch	switch signal is in a "no range signal" state	System voltage (V_IGN) System voltage (V_IGN) Power Source (V_BATT)	>= 10 V =< 32 V >= 9 V	30 Sec	One Trip

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: None ECM: None		
			Fail Case 2 The range signal from the TR switch	switch signal is in a "no range signal" state			5 Sec	
					System voltage (V_IGN)	>= 10 V		
					System voltage (V_IGN)	=< 32 V		
					Power Source (V_BATT)	>= 9 V		
					Engine speed - Calculated turbine speed	> 200 (calibration value) rpm		
					Calculated turbine speed	>= 250 (calibration value) rpm		
					LU pattern	≠ LU condition (LU is OFF)		
					ATF Temperature	>= 20 degC		
					Clutch Status	= Close		
					Vehicle Speed (calculated by TOSS)	>= 2 mph	(Calibration value)	
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: U0100, P0717, P0711, P0712, P0713 ECM: P0315, P0335, P0336		
A/T Range (TR) Switch	P0706	Transmission Range Switch Performance	The range signal from the TR switch	more than one "range signal" is detected (Except combination of D and L which has overlap by design;defaults to D range)			2 Sec	One Trip
					System voltage (V_IGN)	>= 10 V		
					System voltage (V_IGN)	=< 32 V		
					Power Source (V_BATT)	>= 9 V		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: None ECM: None		
Transmission Fluid Temperature Sensor (TFT)	P0711	Transmission Fluid Temperature Sensor Performance	ATF Fluid temperature stuck in temperature zone				600 sec	One Trip
			A/T Fluid temperature	<= 10 C°				
			A/T Fluid temperature	>= -40 C°	System voltage (V_IGN)	>= 10 V		
					System voltage (V_IGN)	=< 32 V		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
					Power Source (V_BATT)	>= 9 V		
					Range	D Range		
					Engine speed	>= 450 rpm		
					Vehicle speed (calc from TOSS)	>= 7 mph		
					Pedal position	>= 12.5 %		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0705, P0706, U0100, P0721 ECM: None		
Transmission Fluid Temperature Sensor (TFT)	P0712	Transmission Fluid Temperature Sensor Circuit Low Voltage (short to ground).	A/T Fluid temperature	>= 180 C°			5 sec	One Trip
					System voltage (V_IGN)	>= 10 V		
					System voltage (V_IGN)	=< 32 V		
					Power Source (V_BATT)	>= 9 V		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: None ECM: None		
Transmission Fluid Temperature Sensor (TFT)	P0713	Transmission Fluid Temperature Sensor Circuit High Voltage (open or short to power).	A/T Fluid temperature	<= -40 C°			5 sec	One Trip
					System voltage (V_IGN)	>= 10 V		
					System voltage (V_IGN)	=< 32 V		
					Power Source (V_BATT)	>= 9 V		
					Vehicle speed (calc from TOSS)	>= 7 mph		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: None ECM: None		
Transmission Input Speed Sensor (TISS)	P0717	Input Speed Sensor Circuit No Signal	<u>Fail Case 1</u> Primary pulley speed	< 150 RPM			5 Sec	One Trip
					System voltage (V_IGN)	>= 10 V		
					System voltage (V_IGN)	=< 32 V		
					Power Source (V_BATT)	>= 9 V		
					Secondary Pulley speed	>= 1000 RPM		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
		Check pulse input	Fail Case 2 Pulse input	No pulse			500 msec	
					System voltage (V_IGN)	>= 10 V		
					System voltage (V_IGN)	=< 32 V		
					Power Source (V_BATT)	>= 9 V		
					Latest calculated Primary pulley speed	>= 1000 RPM		
				Disable Conditions:	MIL not Illuminated for DTC's:	TCM: None ECM: None		
A/T Vehicle Speed Sensor (Output Gear Speed Sensor)	P0721	Output Speed Sensor Performance	Fail Case 1 Output gear speed	< 150 RPM			10 sec	One Trip
					System voltage (V_IGN)	>= 10 V		
					System voltage (V_IGN)	=< 32 V		
					Power Source (V_BATT)	>= 9 V		
					Secondary Pulley speed	>= 1500 rpm		
					Range	D Range or L Range or R Range		
					Calculated turbine speed has experienced after aux gear engagement	< 300 rpm		
					□3 Output gear speed has experienced after aux gear engagement	> 250 rpm		
				Disable Conditions:	MIL not Illuminated for DTC's:	TCM: P0705, P0706		
		Pulse input	Fail Case 2 Pulse input	No pulse			500 msec	
					System voltage (V_IGN)	>= 10 V		
					System voltage (V_IGN)	=< 32 V		
					Power Source (V_BATT)	>= 9 V		
					Latest calculated Output gear speed	>= 730 RPM		
				Disable Conditions:	MIL not Illuminated for DTC's:	TCM: None ECM: None		
Torque Converter Clutch (TCC)	P0741	TCC System Stuck OFF	Torque converter slip	>= (40 + Vehicle Speed (calculated from TOSS) [mph] x 1.6/2) RPM			30 Sec	Two Trips
					System voltage (V_IGN)	>= 10 V		
					System voltage (V_IGN)	=< 32 V		
					TCC Mode	Commanded Lock		
					Lock up command oil pressure	> 0.2 MPa		
					Semi-Conductor Lower Relay Voltage	> 7.5 V		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
				Disable Conditions:	MIL not Illuminated for DTC's:	TCM: P0717, P17C9 ECM: P0315, P0335, P0336		
Torque Converter Clutch (TCC)	P0742	TCC System Stuck ON	The LU coast learning value	< -0.1 MPa			Immediately	One Trip
					System voltage (V_IGN)	>= 10 V		
					System voltage (V_IGN)	=< 32 V		
					LU coast learning control	Experienced at least once in the same driving cycle		
					TCC Slip	< 100 rpm		
					Engine speed	<= 1500 rpm		
					Trans Fluid Temperature	> 10 degC < 140 degC		
					TCC Mode	Commanded Lock		
					Semi-Conductor Lower Relay Voltage	> 7.5 V		
				Disable Conditions:	MIL not Illuminated for DTC's:	TCM: P2763, P2764, P0741, P0705, P0706, P0713, P0712, P0711, P0841, P0842, P0843, P0885, P0961, P0962, P0963, U0100, P17C9, P0717 □3 ECM: None		
Secondary pulley Speed Sensor	P0792	Intermediate Shaft Speed Sensor Circuit Performance Check Secondary pulley speed	Fail Case 1 Secondary pulley speed	< 150 RPM			5 Sec	One Trip
					System voltage (V_IGN)	>= 10 V		
					System voltage (V_IGN)	=< 32 V		
					Power Source (V_BATT)	>= 9 V		
					Primary pulley speed	>= 1000 rpm		
			Fail Case 2 Check pulse input	No pulse			500 msec	
					System voltage (V_IGN)	>= 10 V		
					System voltage (V_IGN)	=< 32 V		
					Power Source (V_BATT)	>= 9 V		
					Latest calculated Secondary pulley speed	>= 1000 rpm		
				Disable Conditions:	MIL not Illuminated for DTC's:	TCM: None ECM: None		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
Auxiliary Shift Gear In Neutral	P0796	Pressure Control Solenoid Valve 3 Stuck Off	Actual auxiliary shift gear ratio (Secondary pulley speed / output gear speed)	>= 2.232			2 sec	One Trip
		[Gear ratio in Neutral (1st gear)]						
		Check current commanded gear ratio and actual gear ratio			System voltage (V_IGN)	>= 10 V		
					System voltage (V_IGN)	=< 32 V		
					Engine speed	> 725 rpm		
					Output gear speed	> 300 rpm		
					Secondary pulley speed	> 300 rpm		
					Range	D Range or L Range		
					Pedal position	>= 7.8 %		
					Current commanded auxiliary shift gear	= 1st Gear		
					Semi-Conductor Lower Relay Voltage	> 7.5 V		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P2715,P2714, P0797, P0721, P0792, P0706, P0705, P0970, P0971, P2720, P2721, U0100, P17C9 ECM: P0315, P0335, P0336, P2122, P2123, P2127, P2128, P2138		
Auxiliary Shift Gear Interlock / Incorrect Auxiliary Shift Gear Ratio	P0797	Pressure Control Solenoid Valve 3 Stuck On [Gear ratio fail (2nd gear)] Check vehicle deceleration and the actual gear ratio	<u>Fail Case 1</u> Actual auxiliary shift gear ratio (secondary pulley spd / output gear speed)	> 1.5 < 2			200 msec	One Trip
					Engine speed	> 725 rpm		
					Output gear speed	> 300 rpm		
					Secondary pulley speed	> 300 rpm		
					Range	D Range or L Range		
					Vehicle speed (calc from TOSS)	>= 7 Mph		
					Vehicle G	< -0.05 G		
					Current commanded auxiliary shift gear	= 2nd gear		
					Semi-Conductor Lower Relay Voltage	> 8.4 V		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
		Check current commanded gear ratio and actual gear ratio	Fail Case 2 Actual auxiliary shift gear ratio (secondary pulley spd / output gear speed)	within +/-10% range of designed 1st gear ratio			500 msec	
					System voltage (V_IGN)	>= 10 V		
					System voltage (V_IGN)	=< 32 V		
					Engine speed	> 725 rpm		
					Output gear speed	> 300 rpm		
					Secondary pulley speed	> 300 rpm		
					Range	D Range or L Range		
					Pedal position	>= 7.8 %		
					Current commanded auxiliary shift gear	= 2nd gear		
					Semi-Conductor Lower Relay Voltage	> 8.4 V		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P2715,P2714, P0796, P0721, P0792, P0706, P0705, P0970, P0971, P2720, P2721, U0100, P17C9 ECM: P0315, P0335, P0336, P2122, P2123, P2127, P2128, P2138		
Secondary pulley Pressure Sensor	P0841	Transmission Fluid Pressure Sensor Performance Rationality Compare actual pressure with target pressure	Fail Case 1 Actual secondary pressure - Target secondary pressure	> 0.675 MPa			5 sec	One Trip
					System voltage (V_IGN)	>= 10 V		
					System voltage (V_IGN)	=< 32 V		
					Range	D Range		
					Primary Pulley	> 306 rpm		
					Secondary Pulley	> 230 rpm		
					|Vehicle Speed Rate of Change| (| VS of present - VS of 10 msec ago|)	< 31 mph		
					□3			
					|Pedal position Rate of Change| (|Pedal pos of present - Pedal pos of 10 msec ago|)	< 21 %		
					Semi-Conductor Lower Relay Voltage	> 7.5 V		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
				Disable Conditions:	MIL not Illuminated for DTC's:	TCM: P0717, P0792, P0721, U0100, P0706, P0705, P0963, P0961, P0842, P0843, P0885, P17C9 ECM: P0315, P0335, P0336		
			Fail Case 2 Target secondary pressure - Actual secondary pressure	> 1.2 MPa			10 sec	
					Range	D Range		
					Engine speed	>= 400 rpm		
					Vehicle Speed (calculated from TOSS)	>= 7 mph		
					Pedal position	>= 12.5 %		
					Target secondary pressure	>= 0 MPa		
					A/T Fluid temperature	< 180 C°		
					A/T Fluid temperature	> 10 C°		
					Semi-Conductor Lower Relay Voltage	> 7.5 V		
				Disable Conditions:	MIL not Illuminated for DTC's:	TCM: P0717, P0792, P0721, U0100, P0706, P0705, P0963, P0962, P0961, P0842, P0843, P0741, P2764, P2763, P0711, P0712, P0713, P17C9 □3 ECM: P0315, P0335, P0336, P2122, P2123, P2127, P2128, P2138		
Secondary pulley Pressure Sensor	P0842	Transmission Fluid Pressure Sensor Circuit Low Voltage Check input voltage	Sensor circuit Input Voltage	<= 0.09 volts			5 sec	Two Trips
					System voltage (V_IGN)	>= 10 V		
					System voltage (V_IGN)	=< 32 V		
					A/T Fluid temperature	> -20 C°		
					Semi-Conductor Lower Relay Voltage	> 7.5 V		
				Disable Conditions:	MIL not Illuminated for DTC's:	TCM: P17C9 ECM: None		
Secondary pulley Pressure Sensor	P0843	Transmission Fluid Pressure Sensor Circuit High Voltage Check input voltage	Sensor circuit Input Voltage	>= 4.7 volts			5 sec	Two Trips
					System voltage (V_IGN)	>= 10 V		
					System voltage (V_IGN)	=< 32 V		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
					A/T Fluid temperature	> -20 C°		
					Target pressure of Secondary Pressure Solenoid	<= 5.7 MPa		
					Semi-Conductor Lower Relay Voltage	> 7.5 V		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P17C9 ECM: None		
ROM Assembly	P0863	Communication error	ROM assembly communication error	= TRUE			10 sec	One Trip
					System voltage (V_IGN)	>= 10 V		
					System voltage (V_IGN)	=< 32 V		
					Range	P range or N range		
					Output speed sensor pulse input starting from IGN-ON	= None		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: None ECM: None		
Transmission Fluid Pressure Switch	P0871	Transmission Fluid Pressure Switch Performance	Fail Case 1 High clutch pressure switch status	= ON			7.5 sec	One Trip
					Range	P Range or R Range or N range		
					Semi-Conductor Lower Relay Voltage	> 7.5 V		
					ROM assembly communication status	Not communicating		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0705, P0706, P0796, P2715, P2714, P0797, P0961, P0962, P0963, P2720, P2721, P0711, P0712, P0713, P17C9 ☐2 ECM: None		
			Fail Case 2 High clutch pressure switch status	= ON			7.5 sec	
					Oil Pressure SW Available judgment	= Not Complete		
					or			
					Vehicle Status	≠ Stop		
					Range	D range or L range		
					High clutch pressure command	=< 0 MPa		
					Engine speed	> 400 rpm		
					Current commanded auxiliary	= 1st gear		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
					shift gear			
					Semi-Conductor Lower Relay Voltage	> 7.5 V		
					ROM assembly communication status	Not communicating		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0705, P0706, P0796, P2715, P2714, P0797, P0961 ,P0962, P0963, P0970, P0971, P2720, P2721, P0711, P0712, P0713, P0721, P0717, P0792, P17C9 □2 ECM: None		
			Fail Case 3 High clutch pressure switch status	= OFF			> Refer to Table 1 sec	
					Range	D range or L range		
					High clutch pressure command	>= 0.2 MPa		
					Current commanded auxiliary shift gear	= 2nd		
					High Clutch pressure solenoid command current	=< 50 mA		
					High Clutch pressure solenoid monitor current	=< 60 mA		
					Engine speed	> 725 rpm		
					Output gear speed	> 300 rpm		
					Secondary pulley speed	> 300 rpm		
					Actual auxiliary shift gear ratio (secondary pulley spd / output gear speed)	< 1.1		
					Pedal position	>= 7.8 %		
					ROM assembly communication status	Not communicating		
					Semi-Conductor Lower Relay Voltage	> 7.5 V		
					MIL not Illuminated for DTC's:	TCM: P0705, P0706, P0796, P2715, P0797, P2714, P0961, P0962, P0963, P0970, P0971, P2720, P2721, P0711, P0712, P0713, P0721, P0792, P17C9 ECM: None		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
Input Voltage	P0885	Transmission Control Module (TCM) Power Relay Control Circuit	Power Source (V_BATT)	< 8.4 V			200 msec	One Trip
					System voltage (V_IGN)	> 11 V		
				Disable Conditions:	MIL not Illuminated for DTC's:	TCM: None		
						ECM: None		
Line Pressure Solenoid	P0961	Line Pressure Control Solenoid Valve Performance Check pulley ratio	Fail Case 1					One Trip
			(Primary pulley speed /Secondary pulley speed)*	> 2.55			200 msec	
					Range	D Range or L Range or R Range		
			* Failure detected when diagnostic logic experienced two times - interval time is 1 second		Engine Speed	> 600 rpm		
					Primary pulley speed	> 500 rpm		
					Key On timer	>= 500 ms		
					Vehicle G	>= -0.051 G		
					Output speed	<= 107 rpm		
					or			
					Secondary pulley speed	> 61 rpm		
					Pedal pressed	= TRUE		
					Semi-Conductor Lower Relay Voltage	> 7.5 V		
		Check pulley ratio	Fail Case 2					
			(Primary pulley speed /Secondary pulley speed)	> 3.35			100 msec	
					Range	D Range or L Range or R Range		
					Engine Speed	> 600 rpm		
			* Failure detected when diagnostic logic experienced two times - interval time is 1 second		Primary pulley speed	> 500 rpm		
					Key On timer	>= 500 ms		
					Vehicle G	>= -0.051 G		
					Output speed	<= 107 rpm		
					or			
					Secondary pulley speed	> 61 rpm		
					Pedal pressed	= TRUE		
					Semi-Conductor Lower Relay Voltage	> 7.5 V		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0717, P0721, P17C9 ECM: None		
Line Pressure Solenoid	P0962	Line Pressure Control Solenoid Valve Control Circuit Low Voltage	Monitored current	<= 200 mA			200 msec	One Trip
			Commanded current	>= 750 mA	System voltage (V_IGN)	>= 10 V		
					System voltage (V_IGN)	=< 32 V		
					Hardware circuitry detects short to ground	= TRUE		
					Line Pressure Solenoid command	= ON		
					Semi-Conductor Lower Relay Voltage	> 7.5 V		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0963, P17C9 ECM: None		
Line Pressure Solenoid	P0963	Line Pressure Control Solenoid Valve Control Circuit High Voltage	Monitored current	<= 200 mA			200 msec	One Trip
			Commanded current	>= 750 mA	System voltage (V_IGN)	>= 10 V		
					System voltage (V_IGN)	=< 32 V		
					Hardware circuitry detects short to ground	= FALSE		
					Line Pressure Solenoid command	= ON		
					Semi-Conductor Lower Relay Voltage	> 7.5 V		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0962, P17C9 ECM: None		
Primary Pressure Solenoid	P0965	Pressure Control Solenoid Valve 2 Performance	Fail Case 1 Pulley ratio (Primary pulley speed /Secondary pulley speed)	>= 2.0 and			5 Sec	One Trip
				<= 2.4				
					Range	D Range or L Range or R Range		
					Engine Speed	> 500 rpm		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
					Target pulley ratio	< 1.2		
					Semi-Conductor Lower Relay Voltage	> 7.5 V		
			Fail Case 2 Pulley ratio (Primary pulley speed /Secondary pulley speed)	>= 0.35 and			5 Sec	
				<= 0.75				
					Range	D Range or L Range or R Range		
					Engine Speed	> 500 rpm		
					Target pulley ratio	> 1.55		
					Semi-Conductor Lower Relay Voltage	> 7.5 V		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0717, P0792, P0842, P0843, P0841, P0962, P0963, P0961, P0966, P0967, P0706, P0705, U0100, P17C9 ECM: P0315, P0335, P0336		
Primary Pressure Solenoid	P0966	Pressure Control Solenoid Valve 2 Control Circuit Low Voltage STG	Monitored current	<= 200 mA			480 msec	One Trip
			Commanded current	>= 750 mA	System voltage (V_IGN)	>= 10 V		
					System voltage (V_IGN)	=< 32 V		
					Hardware circuitry detects short to ground	= TRUE		
					Primary Pressure Solenoid command	= ON		
					Semi-Conductor Lower Relay Voltage	> 7.5 V		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0967, P17C9 ECM: None		
Primary Pressure Solenoid	P0967	Pressure Control Solenoid Valve 2 Control Circuit High Voltage Open	Monitored current	<= 200 mA			200 msec	One Trip
			Commanded current	>= 750 mA	System voltage (V_IGN)	>= 10 V		
					System voltage (V_IGN)	=< 32 V		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
					Hardware circuitry detects short to ground	= FALSE		
					Primary Pressure Solenoid command	= ON		
					Semi-Conductor Lower Relay Voltage	> 7.5 V		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0966, P17C9		
						ECM: None		
Low Brake (L/B) Solenoid	P0970	Pressure Control Solenoid Valve 3 Control Circuit Low Voltage STG	Monitored current	<= 200 mA			480 msec	One Trip
			Commanded current	>= 750 mA	System voltage (V_IGN)	>= 10 V		
					System voltage (V_IGN)	=< 32 V		
					Hardware circuitry detects short to ground	= TRUE		
					Low Brake (L/B) Solenoid command	= ON		
					Semi-Conductor Lower Relay Voltage	> 7.5 V		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0971, P17C9		
						ECM: None		
Low Brake (L/B) Solenoid	P0971	Pressure Control Solenoid Valve 3 Control Circuit High Voltage Open	Fail Case 1 Monitored current	<= 200 mA			200 msec	One Trip
			Commanded current	>= 750 mA	System voltage (V_IGN)	>= 10 V		
					System voltage (V_IGN)	=< 32 V		
					Hardware circuitry detects short to ground	= FALSE		
					Low Brake (L/B) Solenoid command	= ON		
					Semi-Conductor Lower Relay Voltage	> 7.5 V		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0970, P17C9 ECM: None		
			Fail Case 2 Monitored voltage of Low Brake (L/B) Solenoid's drive circuit	>= 8 V			200 msec	
					Low Brake (L/B) Solenoid command duty	= 0 %		
					Semi-Conductor Lower Relay Voltage	> 7.5 V		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P17C9 ECM: None		
ROM Assembly	P1790	Data mismatch	Data mismatch between ROM assembly data and NVM data	= TRUE			Immediately	One Trip
					System voltage (V_IGN)	>= 10 V		
					System voltage (V_IGN)	=< 32 V		
					Range	P range or N range		
					ROM assembly read succeed	= TRUE		
					Output speed sensor pulse input starting from IGN-ON	= None		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: None ECM: None		
Internal Control Modul Driver Performance	P17C9	Voltage Level Monitor After the Semiconductor Relay	Fail Case 1 Actuator Supply Voltage	< 7.55 volt			5 sec	One trip
					Power Source (V_BATT)	>= 8.4 V		
					Power Source (V_BATT) - Actuator Supply Voltage	=< 3 V		
					System voltage (V_IGN)	> 9 V		
					System voltage (V_IGN)	< 32 V		
				Disable Conditions:	MIL not Illuminated for DTC's:	TCM: None ECM: None		
			Fail Case 2 Fail of Actuator on lower side of semi-conductor-Relay	= TRUE			5 sec	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
					Power Source (V_BATT) Power Source (V_BATT) - Actuator Supply Voltage System voltage (V_IGN) System voltage (V_IGN) Actuator Supply Voltage	>= 8.4 V =< 3 V > 9 V < 32 V < 8.4 V		
				Disable Conditions:	MIL not Illuminated for DTC's:	TCM: None ECM: None		
System voltage (V_IGN)	P2534	Ignition voltage Diagnosis(Low) by ignition switch open circuit	TCM Status (IGN Voltage	= ACC Mode =< 3 V)	Engine Controller Run Crank Terminal Status Starter Motor Engaged □3 Propulsion System Active CAN Communication Status **MIL not Illuminated for DTC's:**	= TRUE = FALSE = TRUE = Normal TCM: U0100 ECM: None	7 sec	One Trip
System voltage (V_IGN)	P2535	Ignition voltage Diagnosis(High) by ignition switch short circuit	TCM Status (IGN Voltage	= IGN mode > 3 V)	Engine Controller Run Crank Terminal Status is received	= FALSE	9 sec	One Trip
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: U0100 ECM: None		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
System voltage (V_IGN)	P2537	ACC voltage Diagnosis(Low)	IGN Voltage	≧ 9 V			32 sec	No MIL
			IGN Voltage	< 16 V				
			ACC Voltage	< 9 V				
					Engine Controller Run Crank Terminal Status	= TRUE		
					□3 Starter Motor Engaged	= FALSE		
					Propulsion System Active	= TRUE		
					CAN Communication Status	= Normal		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: U0100		
						ECM: None		
Auxiliary Shift Gear Interlock / Incorrect Auxiliary Shift Gear Ratio	P2714	Pressure Control (PC) Solenoid 4 - Stuck Off [Gear ratio fail (1st gear)] Check vehicle deceleration and the actual gear ratio	Fail Case 1 Actual auxiliary shift gear ratio (secondary pulley spd / output gear speed)	> 0.9			200 msec	One Trip
				< 1.4				
					System voltage (V_IGN)	>= 10 V		
					System voltage (V_IGN)	=< 32 V		
					Engine speed	> 725 rpm		
					Output gear speed	> 300 rpm		
					Secondary pulley speed	> 300 rpm		
					Range	D Range or L Range		
					Vehicle Speed (calculated from TOSS)	>= 7 Mph		
					Vehicle G	< -0.05 G		
					Current commanded auxiliary shift gear	= 1st Gear		
					Semi-Conductor Lower Relay Voltage	> 7.5 V		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P2715,P0797, P0796, P0721, P0792, P0706, P0705, P0970, P2720, U0100, U0073, P17C9		
						ECM: P0315, P0335, P0336, P2122, P2123, P2127, P2128, P2138		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
		Check current commanded gear ratio and actual gear ratio	Fail Case 2 Actual auxiliary shift gear ratio (secondary pulley spd / output gear speed)	within +/-10% range of designed 2nd gear ratio			500 msec	
					System voltage (V_IGN)	>= 10 V		
					System voltage (V_IGN)	=< 32 V		
					Engine speed	> 725 rpm		
					Output gear speed	> 300 rpm		
					Secondary pulley speed	> 300 rpm		
					Range	D Range or L Range		
					□3			
					Pedal position	>= 7.8 %		
					Current commanded auxiliary shift gear	= 1st Gear		
					Semi-Conductor Lower Relay Voltage	> 7.5 V		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P2715,P0797, P0796, P0721, P0792, P0706, P0705, P0970, P2720, U0100, U0073, P17C9 ECM:P0315, P0335, P0336, P2122, P2123, P2127, P2128, P2138		
			Fail Case 3 High clutch pressure switch status	= ON			7.5 sec	
					Engine speed	> 400 rpm		
					Vehicle Speed (calculated from TOSS)	< 7 Mph		
					High clutch pressure command	=< 0 MPa		
					Current commanded auxiliary shift gear	= 1st Gear		
					High clutch pressure switch valid judgment	= FALSE		
					High clutch pressure status changed from OFF to ON during engagement to D range	= TRUE		
					Semi-Conductor Lower Relay Voltage	> 7.5 V		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
				Disable Conditions:	MIL not Illuminated for DTC's:	TCM: P2714, P0797, P0796, P2715, P0970, P2720, P0721, P0792, P0717, P0706, P0705, P17C9 ECM: P0315, P0335, P0336		
			Fail Case 4 High clutch pressure switch status	= ON			7.5 sec	
					Engine speed	> 400 rpm		
					Vehicle Speed (calculated from TOSS)	< 7 Mph		
					Range	D Range or L Range		
					High clutch pressure command	=< 0 MPa		
					Current commanded auxiliary shift gear	= 1st Gear		
					High clutch pressure switch valid judgment	= TRUE		
					Semi-Conductor Lower Relay Voltage	> 7.5 V		
				Disable Conditions:	MIL not Illuminated for DTC's:	TCM: P2714, P0797, P0796, P2715, P0970, P2720, P0721, P0792, P0717, P0706, P0705, P17C9 ECM: P0315, P0335, P0336		
Auxiliary Shift Gear In Neutral	P2715	Pressure Control Solenoid Valve 4 Stuck On [Gear ratio in Neutral (2nd gear)] Check current commanded gear ratio and actual gear ratio	Actual auxiliary shift gear ratio (secondary pulley spd / output gear speed)	>= 2.232			2 sec	One Trip
					System voltage (V_IGN)	>= 10 V		
					System voltage (V_IGN)	=< 32 V		
					Engine speed	> 725 rpm		
					Output gear speed	> 300 rpm		
					Secondary pulley speed	> 300 rpm		
					Range	D Range or L Range		
					Pedal position	>= 7.8 %		
					Current commanded auxiliary shift gear	= 2nd gear		
					Semi-Conductor Lower Relay Voltage	> 8.4 V		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
				Disable Conditions:	MIL not Illuminated for DTC's:	TCM: P2714, P0796, P0797, P0721, P0792, P0706, P0705, P0970, P0971, P2720, P2721, U0100, P17C9 ECM: P0315, P0335, P0336, P2122, P2123, P2127, P2128, P2138		
High Clutch (H/C) Solenoid	P2720	Pressure Control Solenoid Valve 4 Control Circuit Low Voltage STG	Monitored current	<= 200 mA			200 msec	One Trip
			Commanded current	>= 750 mA	System voltage (V_IGN)	>= 10 V		
					System voltage (V_IGN)	=< 32 V		
					Hardware circuitry detects short to ground	= TRUE		
					High Clutch (H/C) Solenoid command	= ON		
					Semi-Conductor Lower Relay Voltage	> 7.5 V		
				Disable Conditions:	MIL not Illuminated for DTC's:	TCM: P2721, P17C9 ECM: None		
High Clutch (H/C) Solenoid	P2721	Pressure Control Solenoid Valve 4 Control Circuit High Voltage Open	Fail Case 1 Monitored current	<= 200 mA			200 msec	One Trip
			Commanded current	>= 750 mA	System voltage (V_IGN)	>= 10 V		
					System voltage (V_IGN)	=< 32 V		
					Hardware circuitry detects short to ground	= FALSE		
					High Clutch (H/C) Solenoid command	= ON		
					Semi-Conductor Lower Relay Voltage	> 7.5 V		
				Disable Conditions:	MIL not Illuminated for DTC's:	TCM: P2720, P17C9 ECM: None		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value		Secondary Malfunction	Enable Conditions			Time Required		Mil Illum.
			Fail Case 2 Monitored voltage of High Clutch (H/C) Solenoid's drive circuit	>= 8	V					200	msec	
						High Clutch (H/C) Solenoid command duty	=	0	%			
						Semi-Conductor Lower Relay Voltage	>	7.5	V			
					Disable Conditions:	MIL not Illuminated for DTC's:	TCM: P17C9					
							ECM: None					
TCC Linear Solenoid	P2763	Torque Converter Clutch (TCC) Pressure Control Solenoid Valve Control Circuit High Voltage Open	Monitored current	<= 200	mA					5	Sec	Two Trips
			Commanded current	>= 750	mA	System voltage (V_IGN)	>=	10	V			
						System voltage (V_IGN)	=<	32	V			
						Hardware circuitry detects short to ground	=	FALSE				
						TCC Linear Solenoid command	=	ON				
						Semi-Conductor Lower Relay Voltage	>	7.5	V			
					Disable Conditions:	MIL not Illuminated for DTC's:	TCM: P2764, P17C9					
							ECM: None					
TCC Linear Solenoid	P2764	Torque Converter Clutch (TCC) Pressure Control Solenoid Valve Control Circuit Low Voltage STG	Monitored current	<= 200	mA					480	msec	Two Trips
			Commanded Current	>= 750	mA	System voltage (V_IGN)	>=	10	V			
						System voltage (V_IGN)	=<	32	V			

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value		Secondary Malfunction	Enable Conditions			Time Required		Mil Illum.
						Hardware circuitry detects short to ground	=	TRUE				
						TCC Linear Solenoid command	=	ON				
						Semi-Conductor Lower Relay Voltage	>	7.5	V			
					Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P2763, P17C9					
							ECM: None					
			Fail Case 1									Two Trips
Electric Oil Pump	P0B09	Electric Oil Pump Electrical Failure During Being Indicated Driving	Monitored State Duty Signal From Electric Oil Pump	< 46	%					1.0	sec	
			OR Monitored State Duty Signal From Electric Oil Pump	> 54	%	Ignition ON for	>	0.36	sec			
						Time after Input voltage > 10 v	>	0.52	sec			
						Electric Oil Pump commanded ON for	>	1.0	sec			
						Relay commanded	=	ON				
						EOP State Signal Frequency	>	90	Hz			
						EOP State Signal Frequency	<	110	Hz			
						Semi-Conductor Lower Relay Voltage	>	10	V			
						Has experienced EOP duty signal of 0%	=	TRUE				
					Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P17C9					
							ECM: None					
			Fail Case 2									
		Electric Oil Pump Electrical Failure During Being Indicated Stopping	Monitored State Duty Signal From Electric Oil Pump	< 26	%					1.0	sec	
			OR Monitored State Duty Signal From Electric Oil Pump	> 34	%	Ignition ON for	>	0.36	sec			
						Time after Input voltage > 10 v	>	0.52	sec			

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
					Electric Oil Pump commanded OFF for	> 0.25 sec		
					Relay commanded ON for	> 0.52 sec		
					EOP State Signal Frequency	> 90 Hz		
					EOP State Signal Frequency	< 110 Hz		
					Semi-Conductor Lower Relay Voltage	> 10 V		
					Has experienced EOP duty signal of 0%	= TRUE		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P17C9 ECM: None		
Electric Oil Pump	P2796	Electric Oil Pump Electrical Failure During Being Indicated Driving	Monitored State Duty Signal From Electric Oil Pump	< 46 %			1.0 sec	Two Trips
			OR					
			Monitored State Duty Signal From Electric Oil Pump	> 54 %	Ignition ON for	> 0.36 sec		
					Time after Input voltage > 10 v	> 0.52 sec		
					Electric Oil Pump commanded ON for	> 1.0 sec		
					Relay commanded	= ON		
					EOP State Signal Frequency	> 90 Hz		
					EOP State Signal Frequency	< 110 Hz		
					Semi-Conductor Lower Relay Voltage	> 10 V		
					Has NOT experienced EOP duty signal of 0%	= TRUE		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P17C9 ECM: None		
		Electric Oil Pump Electrical Failure During Being Indicated Stopping	Monitored State Duty Signal From Electric Oil Pump	< 26 %			1.0 sec	
			OR		Ignition ON for	> 0.36 sec		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
			□3 Monitored State Duty Signal From Electric Oil Pump	> 34 %				
					Time after Input voltage > 10 v	> 0.52 sec		
					Electric Oil Pump commanded OFF for	> 0.25 sec		
					Relay commanded ON for	> 0.52 sec		
					EOP State Signal Frequency	> 90 Hz		
					EOP State Signal Frequency	< 110 Hz		
					Semi-Conductor Lower Relay Voltage	> 10 V		
					Has NOT experienced EOP duty signal of 0%	= TRUE		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P17C9 ECM: None		
Electric Oil Pump	P2797	Electric Oil Pump Performance	Line pressure*	< 0.06 Mpa			10 sec	Two Trips
			* Failure detected when diagnostic logic experiences the condition two times		Ignition ON for	> 0.36 sec		
					Time after Input voltage > 10 v	> 0.52 sec		
					Relay commanded	= ON		
					Start stop control commanded	= ON		
					Semi-Conductor Lower Relay Voltage	> 10 V		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0841, P0842, P0843 P2796,P2799, P17C9 ECM: None		
Relay of Electric Oil Pump	P2799	Stuck ON	Monitored State Duty Signal From Electric Oil Pump	≠ 0 %			5.0 sec	Two Trips
					Ignition ON for	> 0.36 sec		
					Input voltage	> 10 V		
					Relay commanded	= OFF		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
					Semi-Conductor Lower Relay Voltage	> 10 V		
				Disable Conditions:	MIL not Illuminated for DTC's:	TCM: P17C9 ECM: None		
Communication	U0073	Controller Area Network Bus Communication Error	Bus off detected	= TRUE			3 Sec	One Trip
					Time after System voltage (V_IGN) over 10 V	> 3 sec		
					Engine speed OR	>= 600 rpm		
					Calculated turbine speed OR	>= 600 rpm		
					Engine Speed Status	= INVALID		
					No CPU, ROM or RAM error	= TRUE		
				Disable Conditions:	MIL not Illuminated for DTC's:	TCM: None ECM: None		
Communication	U0100	Lost Communications with Engine Control System	No CAN messages from ECM	= TRUE			2 Sec	One Trip
			OR		Time after System voltage (V_IGN) over 10 V	> 3 sec		
			ECM CAN message wrong format	= TRUE				
					Engine speed OR	>= 600 rpm		
					Calculated turbine speed □3 OR	>= 600 rpm		
					Engine Speed Status	= INVALID		
					No CPU, ROM or RAM error	= TRUE		
				Disable Conditions:	MIL not Illuminated for DTC's:	TCM: U0073 ECM: None		
Communication	U0121	Lost Communications with EBCM（ABS）	No CAN messages from EBCM	= TRUE			2 Sec	No MIL
			OR		Time after System voltage (V_IGN) over 10 V	> 3 sec		
			EBCM CAN message wrong format	= TRUE				
					Engine speed	>= 600 rpm		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
					OR			
					Calculated turbine speed	>= 600 rpm		
					OR			
					Engine Speed Status	= INVALID		
					No CPU, ROM or RAM error	= TRUE		
				Disable Conditions:	MIL not Illuminated for DTC's:	TCM: U0073 ECM: None		
Gateway Module	U0146	Lost communication wth central gateway module	No CAN messages from CGM	= TRUE			2 Sec	One Trip
			OR		Time after System voltage (V_IGN) over 10 V	> 3 sec		
			CGM CAN message wrong format	= TRUE				
					Engine speed	>= 600 rpm		
					OR			
					Calculated turbine speed	>= 600 rpm		
					OR			
					Engine Speed Status	= INVALID		
					No CPU, ROM or RAM error	= TRUE		
				Disable Conditions:	MIL not Illuminated for DTC's:	TCM: U0073 ECM: None		
Longitudinal Acceleration Sensor	C1252	Longitudinal Acceleration Sensor Circuit Low	G Sensor	≦ -1.71 G	No CAN communication failure	= TRUE	5.0 sec	No MIL
					Two fault occurences accumulated or continuous	= TRUE		
					System voltage (V_IGN)	>= 10 volt		
					System voltage (V_IGN)	<= 32 volt		
					Power Source (V_BATT)	>= 9 V		
					Vehicle Speed (calculated from TOSS)	>= 0.6 mph		
				Disable Conditions:	MIL not Illuminated for DTC's:	TCM: U0073, P175F ECM: None		
	C1253	Longitudinal Acceleration Sensor Circuit	G Sensor	≧ 1.71 G	No CAN communication failure	= TRUE	5.0 sec	No MIL
					Two fault occurences accumulated or continuous	= TRUE		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
					System voltage (V_IGN)	>= 10 volt		
					System voltage (V_IGN)	<= 32 volt		
					Power Source (V_BATT)	>= 9 V		
					Vehicle Speed (calculated from TOSS)	>= 0.6 mph		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: U0073, P175F ECM: None		
	C1254	Longitudinal Acceleration Sensor Performance	|G Sensor variation|	<= 0.011 G	No CAN communication failure	= TRUE	5.0 sec	No MIL
					Two fault occurences accumulated or continuous	= TRUE		
					1 second after conditions below are met:			
					System voltage (V_IGN)	>= 10 volt		
					System voltage (V_IGN)	<= 32 volt		
					Power Source (V_BATT)	>= 9 V		
					Circuit high	FALSE		
					Circuit low	FALSE		
					G Variation (calculated from vehicle speed)	>= 0.027 G		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: U0073, P175F ECM: None		
	P175F	Acceleration Sensor Signal Message Counter	Error Counter	>= 20 (window timer Error counts 60 sec) ※Error is counted when ARC CAN signal is not same with Expected ARC value	No CAN communication failure	= TRUE	Immediately	No MIL
					System voltage (V_IGN)	>= 9 volt		
					Power Source (V_BATT)	>= 9 V		
						TCM: None ECM: None		
Wheel Speed	C1227	Left Rear Wheel Speed Failure	|(Left Rear Wheel Speed)-(Right Rear Wheel Speed)|	> 10 mph			5 sec	Non MIL
			AND		System voltage (V_IGN)	>= 10 V		
			|(Left Rear Wheel Speed)-(Front Wheel Speed)|	> 10 mph	System voltage (V_IGN)	=< 32 V		
					Power Source (V_BATT)	>= 9 V		
					Vehicle speed (calculated from TOSS)	>= 3 mph		
					Range	not N Range, not D Range		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
					Engine Torque	> 15 Nm		
					|(Right Rear Wheel Speed)-(Front Wheel Speed)|	< 10 mph		
					Right Rear Wheel Speed Failure not occurred	= TRUE		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: U0100, U0121 ECM: None		
Wheel Speed	C1228	Right Rear Wheel Speed Failure	|(Right Rear Wheel Speed)-(Left Rear Wheel Speed)|	> 10 mph			5 sec	Non MIL
			AND		System voltage (V_IGN)	>= 10 V		
			|(Right Rear Wheel Speed)-(Front Wheel Speed)|	> 10 mph	System voltage (V_IGN)	=< 32 V		
					Power Source (V_BATT)	>= 9 V		
					Vehicle speed (calculated from TOSS)	>= 3 mph		
					Range	not N Range, not D Range		
					Engine Torque	> 15 Nm		
					|(Left Rear Wheel Speed)-(Front Wheel Speed)|	< 10 mph		
					Left Rear Wheel Speed Failure not occurred	= TRUE		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: U0100, U0121 ECM: None		